1084

JUN/21 TP301 VERSION 1

Smart Position Transmitter









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web: www.smar.com/contactus.asp

INTRODUCTION

The **TP301** is from the well-know Hart[®] [—]family of Smar's devices. It is a smart transmitter for position measurements. It can measure displacement or movement of rotary or linear type. The digital technology and communication provide an easy interface between the field and control room and several interesting features that considerably reduce the installation, operation, and maintenance costs.

TP301 uses a magnetic coupler without physical contact to measure the position. Therefore, it is immune to vibrations resulting in a larger operational timelife. The magnetic coupler replacing the mechanical connection, results in a clear reduction of the deadband. TP301 can be set up in any linear or rotary valve, actuator or a variety of other equipment, such as floodgate skylight, dampers, rolls mill height, crusher, etc.

The **TP301**, besides the normal function of position measurement and 4-20 mA output generation, offers the following features:

- ✓ Linear or rotary travel type;
- ✓ 0.1% F.S.;
- ✓ Position calibration (4 20 mA) via local adjustment or remote calibration via configurator;
- ✓ Non contact position sensing;
- ✓ Optional LCD indicator;
- ✓ Diagnostics and configuration via Hart® communication.

NOTE

Get the best results of the TP301 by carefully reading these instructions.

NOTE

This manual is compatible with version 1.XX, where 1 denotes software version and XX software release. The indication 1.XX means that this manual is compatible with any release of software version 1.

Waiver of responsibility

The contents of this manual abides by the hardware and software used on the current equipment version. Eventually there may occur divergencies between this manual and the equipment. The information from this document are periodically reviewed and the necessary or identified corrections will be included in the following editions. Suggestions for their improvement are welcome.

Warning

For more objectivity and clarity, this manual does not contain all the detailed information on the product and, in addition, it does not cover every possible mounting, operation or maintenance cases.

Before installing and utilizing the equipment, check if the model of the acquired equipment complies with the technical requirements for the application. This checking is the user's responsibility.

If the user needs more information, or on the event of specific problems not specified or treated in this manual, the information should be sought from Smar. Furthermore, the user recognizes that the contents of this manual by no means modify past or present agreements, confirmation or judicial relationship, in whole or in part.

All of Smar's obligation result from the purchasing agreement signed between the parties, which includes the complete and sole valid warranty term. Contractual clauses related to the warranty are not limited nor extended by virtue of the technical information contained in this manual.

Only qualified personnel are allowed to participate in the activities of mounting, electrical connection, startup and maintenance of the equipment. Qualified personnel are understood to be the persons familiar with the mounting, electrical connection, startup and operation of the equipment or other similar apparatus that are technically fit for their work. Smar provides specific training to instruct and qualify such professionals. However, each country must comply with the local safety procedures, legal provisions and regulations for the mounting and operation of electrical installations, as well as with the laws and regulations on classified areas, such as intrinsic safety, explosion proof, increased safety and instrumented safety systems, among others.

The user is responsible for the incorrect or inadequate handling of equipments run with pneumatic or hydraulic pressure or, still, subject to corrosive, aggressive or combustible products, since their utilization may cause severe bodily harm and/or material damages.

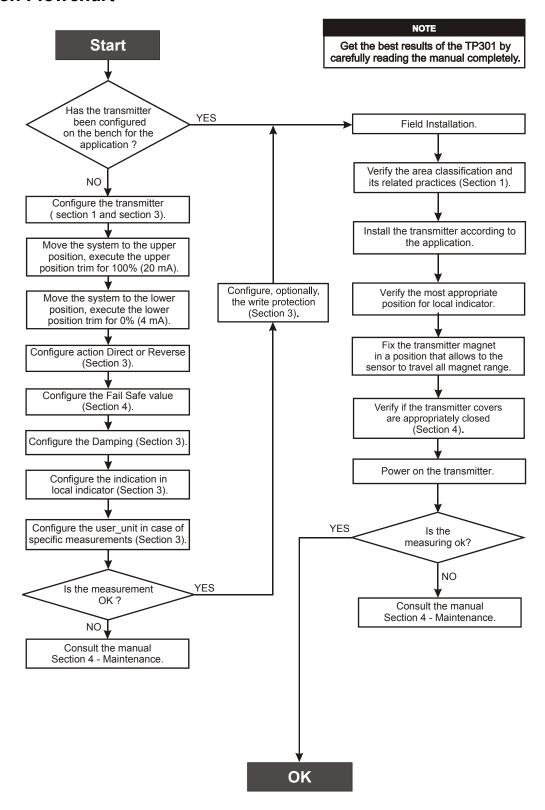
The field equipment referred to in this manual, when acquired for classified or hazardous areas, has its certification void when having its parts replaced or interchanged without functional and approval tests by Smar or any of Smar authorized dealers, which are the competent companies for certifying that the equipment in its entirety meets the applicable standards and regulations. The same is true when converting the equipment of a communication protocol to another. In this case, it is necessary sending the equipment to Smar or any of its authorized dealer. Moreover, the certificates are different and the user is responsible for their correct use.

Always respect the instructions provided in the Manual. Smar is not responsible for any losses and/or damages resulting from the inadequate use of its equipments. It is the user's responsibility to know and apply the safety practices in his country.

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Installation Flowchart



INSTALLATION

General

NOTE

The installation carried out in hazardous areas should follow the recommendations of the IEC60079-14 standard.

NOTE

See appendix "A" Hazardous Area Certifications.

The overall accuracy of measurement and control depends on several variables. Although the converter has an outstanding performance, proper installation is essential, in order to maximize its performance.

Among all factors, which may affect converter accuracy environmental conditions are the most difficult to control. There are, however, ways of reducing the effects of temperature, humidity and vibration.

In warm environments, the transmitter should be installed to avoid, as much as possible, direct exposure to the sun. Installation close to lines and vessels subjected to high temperatures should also be avoided. Use of sun shades or heat shields to protect the transmitter from external heat sources should be considered, if necessary.

Humidity is fatal to electronic circuits. In areas subjected to high relative humidity, the o-rings for the electronics cover must be correctly placed. Removal of the electronics cover in the field should be reduced to the minimum necessary, since each time it is re-moved, the circuits are exposed to the humidity.

The electronic circuit is protected by a humidity proof coating, but frequent exposures to humidity may affect the protection provided. It is also important to keep the covers tightened in place. Every time they are removed, the threads are exposed to corrosion, since these parts cannot be protected by painting. Code approved sealing methods on conduit entering the transmitter should be employed.

Although the transmitter is virtually insensitive to vibration, installation close pumps, turbines or other vibrating equipment should be avoided.

Mounting

The **TP301** mounting depends on the type movement, linear or rotary. Two brackets are required for mounting, one for the magnet and the other for the transmitter itself.

NOTE

Make sure that arrow engraved on the magnet coincides with the arrow engraved on the Position Transmitter when the system is in mid travel. When mounting the the Position Transmitter, consider that:

- 1. There is no friction between the internal magnet face and the position sensor salience all over the travel (rotary or linear).
- 2. A minimum distance of 2 mm to of 4 mm distance is recommended between the magnet external face and the Position Transmitter face.

Should the transmitter installation change, or magnet change, or should any other modification, the transmitter will require a re-calibration.

IMPORTANT

If the self diagnostics detect a transmitter failure, for example the loss of the power, the analog signal will go to 3.9 mA or to 21.0 mA to alert the user (High or low alarm signal is user selectable).

The following Figures 1.1 and 1.3 show both linear and rotary typical mounting:

Rotary Movement

Install the magnet on the valve stem using the magnet mounting bracket.

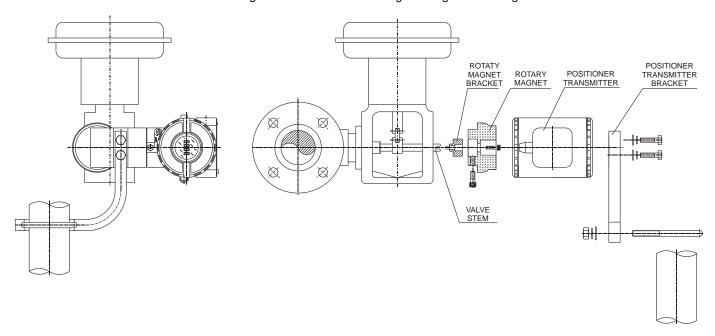


Figure 1.1 - Transmitter on a Rotary Actuator

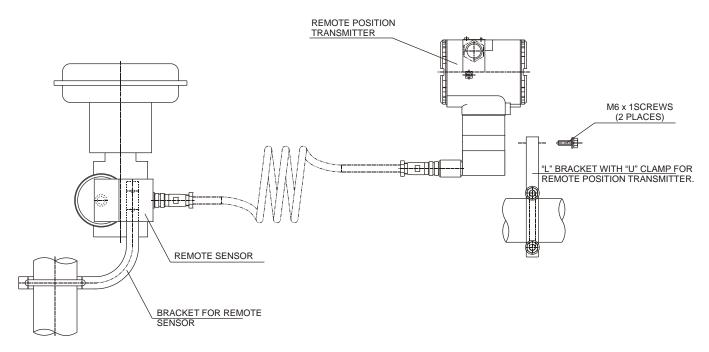


Figure 1.2 - Position Transmitter on Rotary Actuator with Remote Position Sensor

Linear Movement

Install the magnet on the valve stem using the magnet mounting bracket.

The linear magnet movement must be orthogonal in relation to the main axis of the position transmitter. For example, if the linear magnet movement is vertical, the transmitter main axis must be horizontal, as show in Figure 1.3.

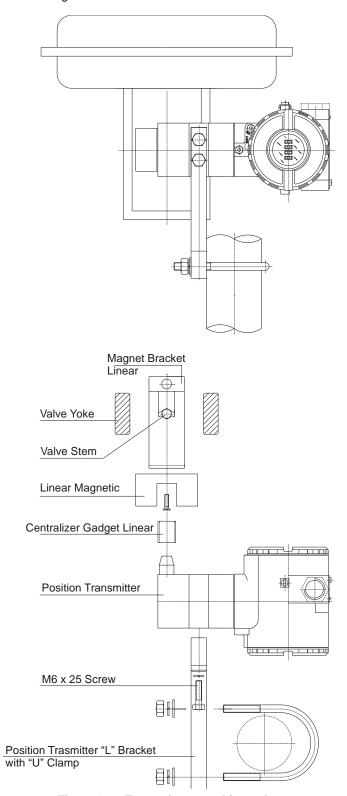


Figure 1.3 - Transmitter on a Linear Actuator

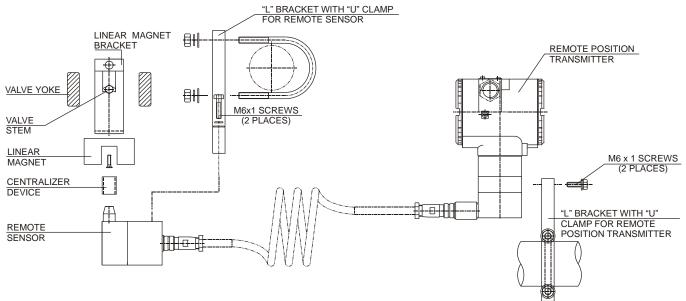
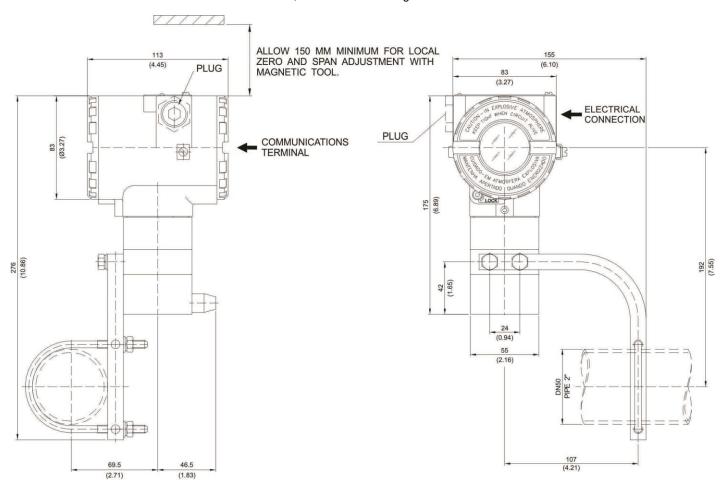


Figure 1.4 - Position Transmitter on Linear Actuator with Remote Position Sensor

See below the **TP301**, dimensional drawings.



LINEAR MAGNET

ROTARY MAGNET

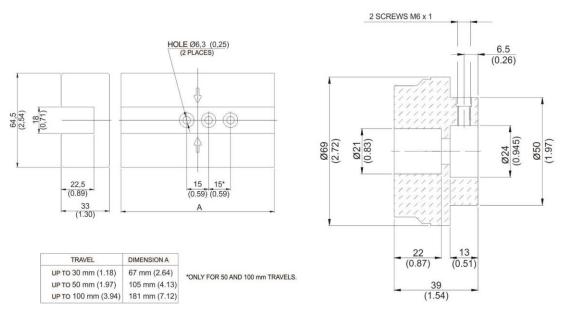


Figure 1.5 - TP301 Dimensional Drawing / Magnets Dimensional Drawing

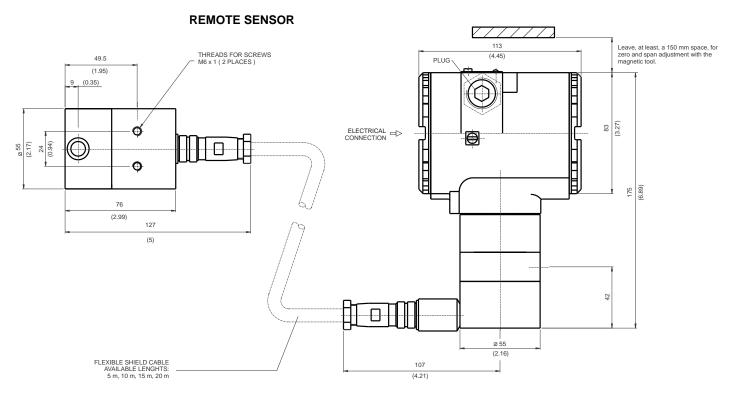


Figure 1.5.a - Remote Sensor Dimensional Drawing

SPECIAL MOUNTING BRACKET - ROTARY VDI / VDE NAMUR

Mounting bracket of the position transmitter for rotary valves actuated via type actuators rack and pinion, designed to comply with NAMUR VDI/VDE.

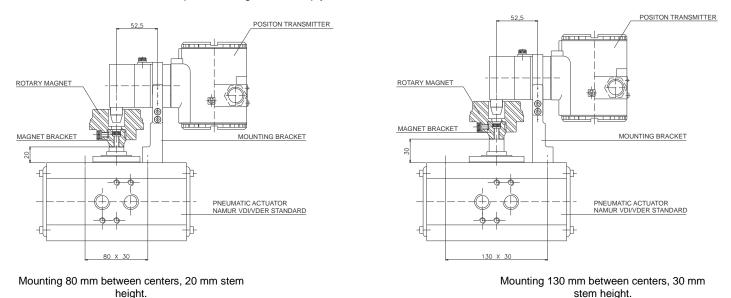


Figure 1.5.b - Special Mounting Bracket Dimensional Drawing - Rotary VDI / VDE NAMUR

Electronic Housing Rotating

The electronic housing rotates for a better digital display reading. To rotate it, release the housing rotation screw.

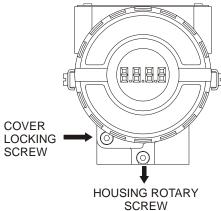


Figure 1.6 - Cover Locking and Housing Rotation Set Screw

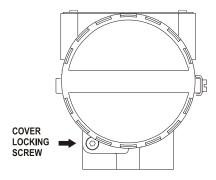


Figure 1.7 - Cover Locking Screw

Electric Wiring

The digital display also rotates for better reading. It is necessary to release the electronic house front cover (release de cover locking screw), release the electronic circuit board screws and choose one of the 90° different positions. Reassembly the whole set. To access the terminal block for electronic connections, remove the cover locking screw.

The terminal block accepts forks or eye-type connectors. For convenience there are two ground terminals: one inside the cover and one external, located close to the conduit entries.

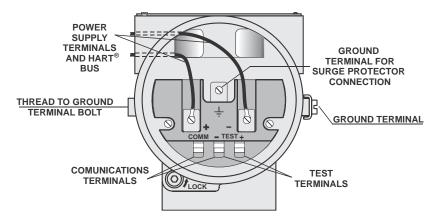


Figure 1.8 - Wiring Block

Use of twisted pair (22 AWG or greater than) cables is recommended. Avoid routing signal wiring cables close to power cables or switching equipment.

The **TP301** is protected against reverse polarity, and supports □50 mA without damage.

The following figures show the possibilities for TP301 connections.

ATTENTION

For proper operation, the configurator requires a minimum load of 250 Ohm between it and the power supply.

The configurator can be connected to the transmitter communication terminals or at any point of the signal line by using the interface IF3 with alligator clips.

It is also recommended to ground the shield of shielded cables at one end only. The non grounded end must be carefully isolated.

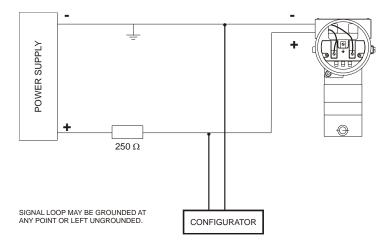


Figure 1.9 - TP301 Wiring Diagram

The Figure 1.10 shows a typical **TP301** connection in multidrop configuration. Such configurations allow a maximum of 15 transmitters on the same line connected in parallel. Take care to the power supply capacity as well, when many transmitters are connected on the same line.

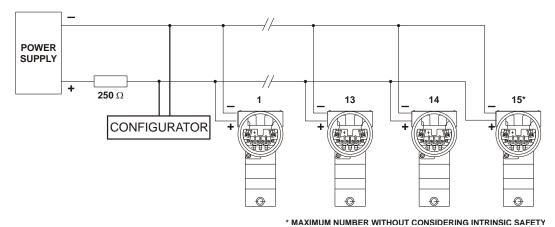


Figure 1.10 - TP301 Wiring Diagram for Multidrop Configuration

NOTE

Make sure that the transmitter is operating within the operating area as shown on the load curve. Communication requires a minimum load of 250 Ohm.

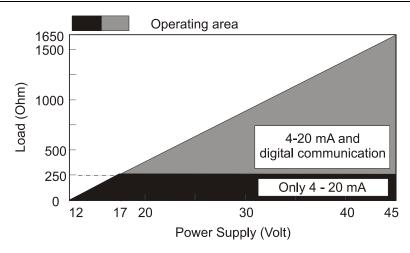


Figure 1.11 - Load Curve

Recommendations for mounting Approved Equipment with the IP66/68 W certifications ("W" indicates certification for use in saline atmospheres)

NOTE

This TP301 certification is valid for stainless steel transmitter manufactured, approved with the certification IP66/68 W. All transmitter external material, such as plugs, connections etc., should be made in stainless steel

The electrical connection with 1/2" – 14NPT thread must use a sealant. A non-hardening silicone sealant is recommended.

The instrument modification or replacement parts supplied by other than authorized representative of Smar is prohibited and will void the certification.

Rotary and Linear Magnet

The Figure 1.12 shows typical shapes for both magnets. For better transmitter performance, the linear magnet is presented with different lengths. Consult the ordering code table for the best choice.



Figure 1.12 - Linear and Rotary Magnet Models

Remote Position Sensor

The remote magnetic position sensor, based on hall effect, is recommended for high temperature or extreme vibration applications. It prevents excessive wear of the equipment and, consequently, increasing the transmitter lifetime

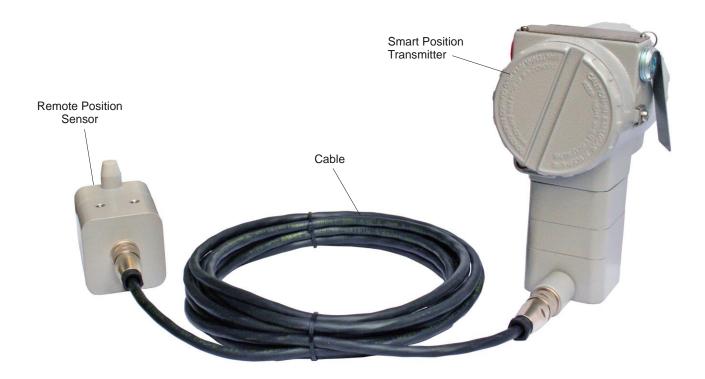


Figure 1.13 - Remote Position Sensor

The electric signals on the remote sensor's cable and connections are of low intensity. Therefore, when installing the cable inside the conduit (maximum limit 20 (meters) length), keep it away from possible sources of induction and/or magnetic interference. The cable supplied by Smar is shielded with excellent protection against electromagnetic interference, but despite of this protection, it is recommended to avoid the cable sharing the same conduit with other cables.

The connector for Remote Position Sensor is easy to handle and simple to install.

See the installation procedure:



Figure 1.14 - Connecting the Cable to the Remote Position Sensor



Figure 1.15 - Connecting the Cable to the Position Transmitter

Installation in Hazardous Areas

Consult the Appendix A for Hazardous Location Approvals.

OPERATION

Functional Description - Position Sensor

The Position Sensor supplies an output voltage proportional to the applied magnetic field. This magnetic sensor, based on hall effect, is ideal for sensing linear or rotative position. The mechanical vibrations do not affect Position Sensor.

Functional Description - Electronics

The function of each block in the block diagram is described below.

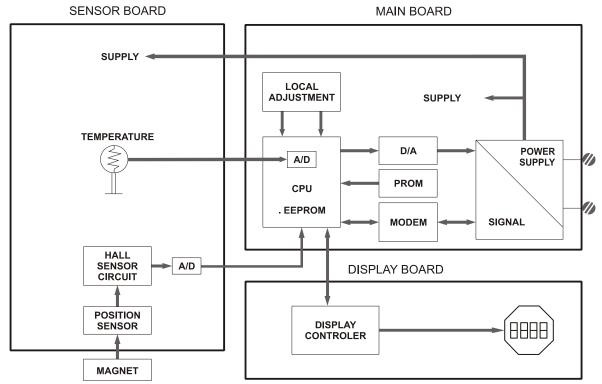


Figure 2.1 - TP301 Block Diagram

Hall Effect Position Sensor

The magnet, installed in the instrument to the position to be measured, moves the of the instrument movement accordingly. The hall effect position sensor detects the movement and produces a small voltage change variation proportional to the magnetic field variation due to the magnet movement.

Temperature Sensor

The sensor circuit of hall processes that tension variation, generating a signal for the converter A/D. The converter A/D produces a set of signals for the transmitter CPU (Central Processing Unit).

Modem HART

Modulates and demodulates communication signals superimposed onto current line. A "1" is represented by 1200 Hz and a "0" by 2200 Hz. The frequency signal is symmetrical and does not affect the DC level of the of the 4 - 20 mA signal.

CPU Central Processing Unit, RAM, PROM and EEPROM

The CPU is the transmitter intelligent part, being responsible for the data management and block execution, operation self-diagnostics and communication. The program is stored in PROM. For temporary storage of data there is a RAM. The data in the RAM is lost if the power is switched off, however the device also has a non-volatile EEPROM where key data is stored. Examples of such data are the calibration and **TP301** configuration.

Power Supply

The transmitter is powered with 12 to 45 Vdc using the signal line (2-wire system). The transmitter quiescent consumption is 3.6 mA; during operation, consumption may be as high as 21 mA, depending on the measurement and sensor status. If configured for low signal failure, the **TP301** shows 3.6 mA indication if configured for high signal failure, it shows 21 mA indication; 3.8 mA in the case of low saturation; 20.5 mA in the case of high saturation and measurements proportional to the range position between 4 mA and 20 mA. 4 mA corresponds to 0% of the working range and 20 mA to 100 % of the range.

Display Controller

Receives data from the CPU and drives the liquid crystal display (LCD).

Local Adjustment

Local adjustment is provided by means of two magnetically actuated switches with no external electric or mechanical contact, by using a magnetic tool..

Local Indicator

The local indicator is used for signaling and operation in local adjustment. During normal operation, the **TP301** remains in the monitoring mode and the display indicates the valve position, either as a percentage or as a current readout, according to the end-user configuration. The magnetic tool activates the local programming mode, by inserting it in orifice Z on the electronic housing.

The possible configuration and monitoring operation are shown on figure 2.2. When first powered, the **TP301** initializes, by showing model **TP301** and its software version (X.XX) on the display.

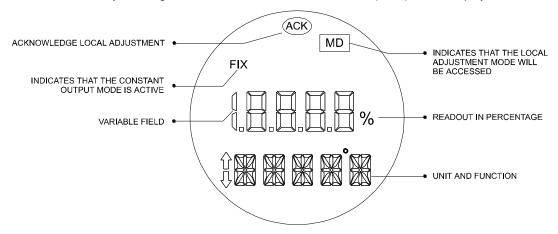


Figure 2.2 - Local Indicator

Monitoring

During normal operation, the **TP301** remains in the monitoring mode. The figure 2.3 shows the positioning on the display. The display simultaneously shows the readout and other information chosen.

Normal displaying is interrupted when the magnetic tool is placed in orifice Z (Local Adjustment), starting the programming and local adjustment mode. The figure 3.1 shows the result of tool insertion in orifices Z and S, which inform, respectively, movement and actuation of the selected options.

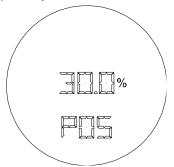


Figure 2.3 - Typical Indicator

CONFIGURATION

The **TP301** is configured via Local Adjust or configurators with digital communication (HART® Protocol). It is also possible to configure the **TP301** via the CONF401 configuration tool or any FDT/DTM software application, both for desk or laptop.

To enable local adjustment, the jumper "W1" located on top of the main board shall be connected to the pins where the word "ON" is engraved on the circuit board. See Figure 3.2.

There are two orifices on the position transmitter, under its nameplate, identified by S and Z respectively, which provide access to two magnetic switches actuated by means of a magnetic tool.

NOTE

In this section the "magnetic tool" will be referred to as "TOOL", and the orifices identified by "S" and "Z" will be "S" orifice and "Z" orifice, respectively.

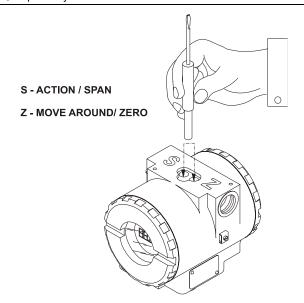


Figure 3.1 - Orifices of Local Adjustment

The table below shows the results of actions on "Z" and "S" on the TP301.

ORIFICE	ACTION	
Z	Browsing the programming tree function.	
S	Selects the displayed function.	

The digital display is necessary for local adjustment programming.

Jumper Connection

Simple Local adjustment - W2 Jumper connected in SI

If the W2 jumper is connected in SI (see Figure 3.2), simple local adjustment enabled; the calibration can be done at the position of 0% inserting the cable of the tool in the Z orifice and 100% inserting it in the S orifice.

Complete Local adjustment - W2 Jumper Connected in COM

With the jumper connected in COM (see Figure 3.2), complete local adjustment enabled, allowing to change the displayed unit direct or reverse indication and to calibrate the lower position (LOPOS) or the upper position (UPPOS).

NOTE

After configuring these parameters, we recommend to leave the W1 jumper in OFF (disabled) to avoid accidental mis-configuration.

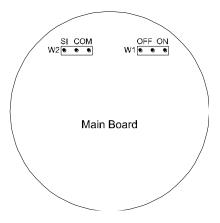


Figure 3.2 - W2 and W1 Jumpers

Local Adjustment

Local Configuration Tree

The Local Adjustment Configuration Tree, as per Figure 3.3, shows possesses the available functions in the equipment.

Step 1

To configure the functions, it is enough to maintain the magnetic tool in Z; in that way it will browse all the available functions. See the available functions in the figure 3.3.

Step 2

When the indicator shows the function the user wants to change, remove the tool and insert it in the orifice S. If there are more options on this particular function, just keep the magnetic tool in that orifice, to browse the functions submenus.

Step 3

To select an option of this submenu, remove the magnetic tool and to insert it again in the orifice Z.

To act in other functions, wait until the display shows the main tree branch and remove the tool to exit the Local Adjustment.

NOTE

Remove the Magnetic Tool of the orifice to Save (to execute) the selected option. When the display shows the symbol ACK: option was accepted.

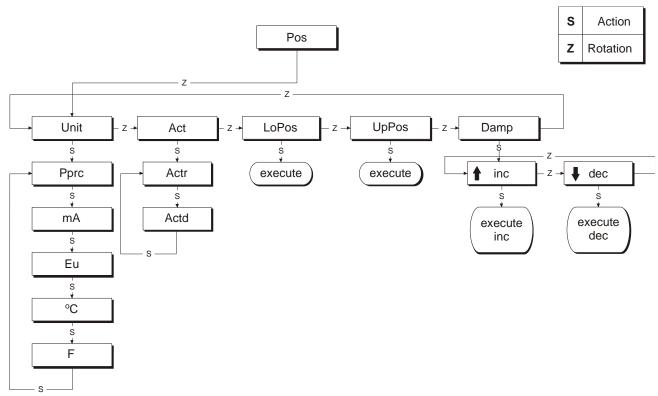


Figure 3.3 - Local Adjustment Configuration Tree

Description of the Parameters of the Local Adjustment Configuration Tree

POS - Position in Percentage

UNIT

Engineering Unit or Percentage.

Pprc

Position in Percentage.

mA (Milliampere)

Current.

Eu (End User's choice)

Position.

°C (Degrees Celsius)

Temperature.

F (Degrees Fahrenheit)

Temperature.

ACT

Action.

Actr

Reverse action.

Actd

Direct action.

LOPOS (0% Position)

TRIM of inferior position.

UPPOS (100% Position)

TRIM of Superior Position.

DAMP (Damping)

Reduction function.

Inc

Increment.

Dec

Decrement.

NOTE

Every parameter configuration shall be performed judiciously, since it writes the configuration parameters on permanent basis and does not ask for confirmation by the user. Once it is performed it is assumed to be the desired configuration.

Procedure to Calibrate the Position Transmitter

Calibration using the jumper in simple local adjustment

If the simple local adjustment is enabled, only the lower and upper position can be adjusted.

See the steps:

Step 1

Place the magnet at the lower point and insert the magnet tool in the Z orifice.

Step 2

To adjust the upper value, place the magnet in the upper point and insert the tool in the S orifice.

After this, move the device to the upper and lower position and check the measurement on the display.

Calibration for the complete local adjustment

When the complete local adjustment is enabled the can be configured,

- the Display Indication in:
 - Position in % (Perc);
 - Current in mA (mA);
 - Temperature in °C (C);
 - Temperature in F (F).
- the indication Direct or Reverse;
- the Lower and Upper Position.

NOTE

To change from percentage indication (factory default) to any available engineering units, refer to the configuration through configurators (see the programming tree at the configurator manual).

Configuration via Configurators

TP301 can be configured through the manual portable configurator portable manual based on PalmOS platform. Besides, the **TP301** has connectivity with FDT/DTM, CONF401 and DDCON configuration application for desk and laptop.

NOTE

For detailed information on how to install and operate the configurations software, please consult www.smar.com for downloading the current instructions manuals.

Configuration via manual configurator

See below the programming tree for the portable configurator based on PalmOS platform.

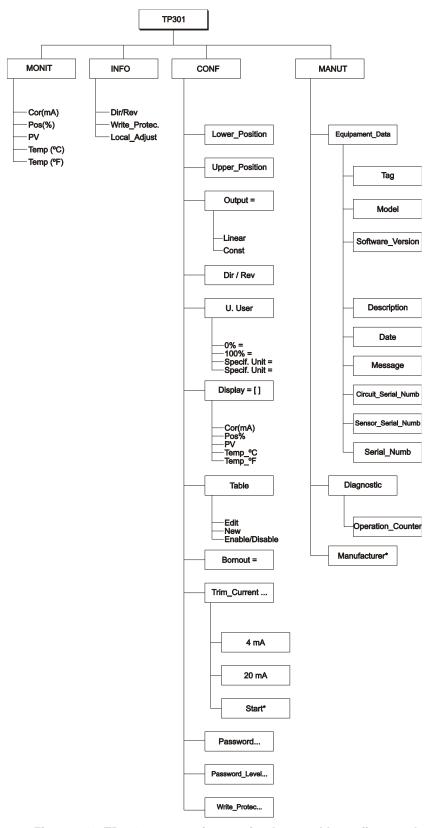


Figure 3.4 – TP301 programming tree for the portable configurator based on PalmOS platform

TABLE OF POINTS - LINEARIZATION

The output signal follows a curve determined by 16 points freely configurable.

	TABLE OF POINTS - LINEARIZATION			
Points %	Actual Value (process Out) X(%)	Desired position value (of the process) Y(%)		
1	0	0		
2	26.4	25	5 Points	
3	48.6	50	(See figure: Position graphic of the	
4	74.2	75	magnet)	
5	100	100		
6	-	-		
			Not used	
16	-	-		

Table function (Linearization)

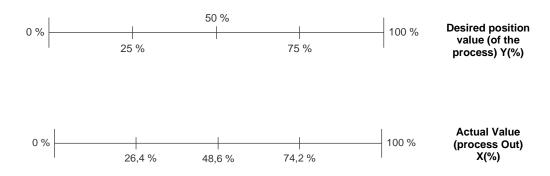
Depending on the application and according with the process, the transmitter output or PV is shown in one linear characteristic curve (position, level, opening etc.). TP also has the option for adjust this curve of linear output, to that the value in percentage can be linearized, you have to uses a table 16 points at maximum and minimum points 2. The output is calculated by interpolating these points. The user can set the total of points desired.

To configure the feature table:

- The user must choose the item "function" to "table" option.
- Select the number of points, according to you need, 2-16 points.
- Create the table and indicate the current position value in the "X" (%) column and the desired position value in the "Y" (%) column. Once created the table, send the points for the position transmitter.
- Done, this configured.

Position Graphic of the Magnet

Exemple:



NOTE: If the table is enabled there will be an indication on the Display LCD with the F(X) icon.

Figure 3.5 - Position Graphic of the Magnet

- Applications with base in FDT/DTM (Field Device Tool/Device Type Manager)
The TP301 comes with the factory default connectivity with FDT/DTM systems.

The FDT (Field Device Tool) it is a digital communication technology between field devices and systems. It is a non proprietary communication protocol (open) and its use has been growing quickly, as a result of the user's search for an independence in relation to the suppliers.

The DTM (Device Type Manager) it is an application based on the DD - device description, and it is responsible to link all the device information for instance the TP301, with the FDT. This

system is interactive, in other words, not only it reads the **TP301** parameters, but also it "writes" information into the **TP301**.

To configure the **TP301** with the FDT/DTM tool, please refer to the TP301DTM manual - Device Type Manager downloadable from www.smar.com. The Figure 3.5 is an example of one of the available screens for the **TP301**.

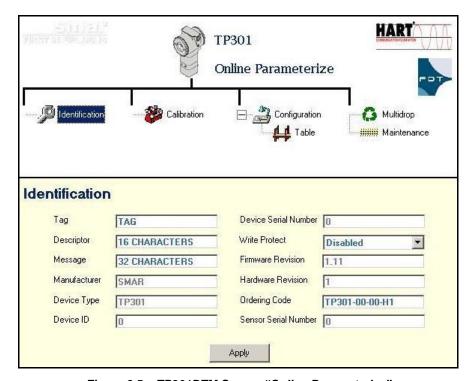


Figure 3.5 – TP301DTM Screen "Online Parameterize"

- CONF401

The CONF401 is a configurator HART for PC allowing easy configuration and field devices monitoring. It also of analyzes device data and modify its performance. The graphic interface is intuitive and easy to learn and to use, doing with that is not necessary the use.

CONF401 is compatible with Windows 95/98/ME/NT/2000 and XP.

CONF401 is compatible with the interfaces: HI311, HI321, HFI400, DDCON100 and any interface HART $^{\odot}$ based on the protocol RS232 <->HART.

Minimum configuration:

- 1. Pentium 350 MHz processor;
- 2. Windows 95/98/ME/NT/2000/XP operating system;
- 3. 128 MB RAM;
- 4. At least a door serial (HI311) or it carries USB (HI321, HFI400 or DDCON100) available.

To configure see the Manual of the User of CONF401 - CONFIGURADOR HART®, in the site http://www.smar.com or http://www.smarresearch.com.

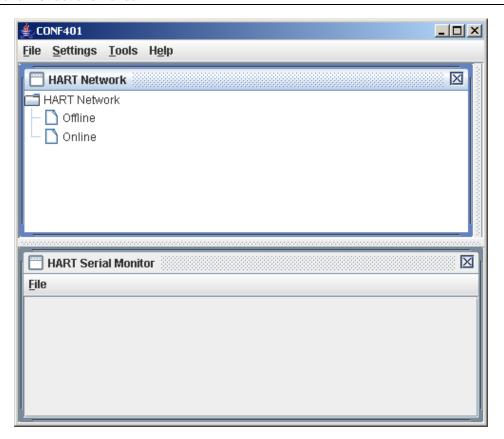


Figure 3.6 - CONF401 Screen

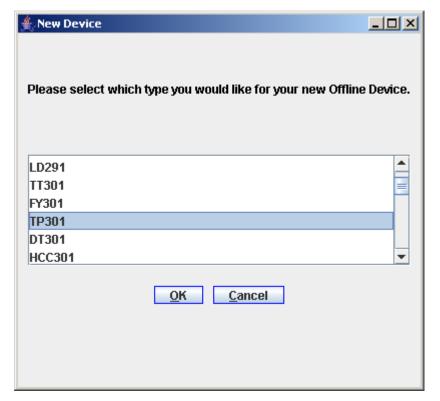


Figure 3.7 - New Device

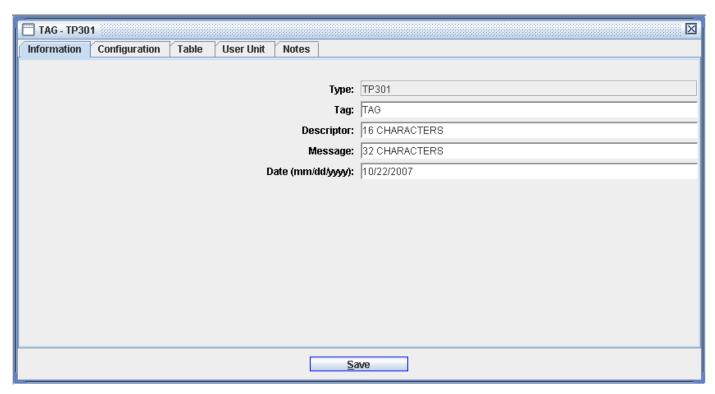


Figure 3.8 - TP301 Configuration Screen

DDCON 100 - DDL Based HART Configurator
 To configure see the manual in the site: http://www.smarresearch.com.



Figure 3.9 - DDCON 100 - DDL Based HART Configurator

FAIL SAFE (Alarm Selection)

The Fail Safe parameter is set by using the configurators only. It allows to the user to configure the **TP301** to alarm when the current is as lows as 3.6 mA or as high as 21 mA.

MAINTENANCE PROCEDURES

General

Smar **TP301** Position Transmitters are extensively tested and inspected before delivered to the end user. Nevertheless, during their design and development, Smar considered the possibility of repairs by the end user, if necessary.

In general, it is recommended that the end user do not try to repair printed circuit boards. Instead, he should have spare circuit boards, ordered from Smar whenever necessary.

Recommendations for mounting Approved Equipment with the IP66/68 W certifications ("W" indicates certification for use in saline atmospheres)

NOTE

The certification is valid for stainless steel transmitter manufactured, approved with the certification IP66/68 W. All transmitter external material, such as plugs, connections etc., should be made in stainless steel.

The electrical connection with 1/2" – 14NPT thread must use a sealant. A non-hardening silicone sealant is recommended.

The instrument modification or replacement parts supplied by other than authorized representative of Smar is prohibited and will void the certification.

Diagnostic with Configurator

In case any malfunction related to the transmitter output, investigation may be carried out with the configurator, as long as the transmitter is powered, the communication and the processing unit are operating normally.

Connect the configurator to the transmitter according to the wiring diagram shown on Section 1.

ERROR MESSAGES

When communicating using the configurator the user will be informed about any problem found by the transmitter self diagnostics.

The messages always alternate with the information on the top line. The table below lists the error messages, potential source of malfunction and more details on corrective action.

ERROR MESSAGES	POTENTIAL SOURCE OF PROBLEM	
PARITY ERROR	The line resistance is not according to technical characteristics.	
OVERRUN ERROR	Excessive noise or ripple.	
CHECK SUM ERROR	Low level signal.	
FRAMING ERROR	Interface damaged.	
FRAMING ERROR	Power supply or battery voltage of the configurator lower than 9 V.	
	Transmitter line resistance is not according to technical characteristics.	
	Transmitter not powered.	
	Transmitter not connected or damaged.	
NO RESPONSE	Transmitter configured in multidrop mode being accessed by "ON LINE SINGLE UNIT".	
	Transmitter reversely powered (Polarity is reversed).	
	Interface damaged.	
	Power supply or battery voltage of the configurator lower than 9 V.	
LINE BUSY	Other device using the line.	
CMD NOT IMPLEMENTED	Software version not compatible between configurator and position transmitter.	
DEVICE BUSY	Transmitter carrying out an important task, e.g., local adjustment.	

ERROR MESSAGES	POTENTIAL SOURCE OF PROBLEM			
POSITION TRANSMITTER MALFUNCTION	Transducer disconnected.			
FOSITION TRANSMITTER MALFONCTION	Transducer failure.			
COLD START	Start-up or reset due to power supply failure.			
OUTPUT FIXED	Operating in local mode with fix position.			
OUT OT TIXED	Connected in burnout.			
OUTPUT SATURATED	Position out of calibrated span or in fail-safe (Output current in 3.9 or 21.0 mA).			
SV OUT OF LIMITS	Temperature out of operating limits.			
3V OUT OF LIMITS	Temperature sensor damaged.			
	Position out of operation transmitter range.			
PV OUT OF LIMITS	Transducer damaged or transducer not connected.			
	Position transmitter with error configuration.			
LOWER RANGE VALUE TOO HIGH	The lower range value > (Upper limit of range - minimum span).			
LOWER RANGE VALUE TOO LOW	• The lower range value < (Upper limit of range).			
UPPER RANGE VALUE TOO HIGH	The upper range value > 110%. (Upper limit of range).			
UPPER RANGE VALUE TOO LOW	The upper range value < -10%. (Lower limit of range).			
UPPER AND LOWER RANGE VALUES OUT OF LIMITS	Both the upper and lower points were outside the transmitter range limit.			
SPAN TOO SMALL	The difference, between the upper and lower points, is less than the allowed by the transmitter.			
ACTUAL POSITION	The actual position is above of the upper range limit.			
ACTUAL POSITION	The actual position is below of the lower range limit.			
PASSED PARAMETER TOO LARGE	Parameter above operating limits.			
PASSED PARAMETER TOO SMALL	Parameter below operating limits.			
CONTROL LOOP SHOULD BE IN MANUAL	Indicates the operation could affect the output.			
CONTROL LOOP MAY BE RETURNED TO AUTO	After the operation is completed, you are reminded to return the loop to automatic control.			

Table 4.1 - TP301 Diagnostics with Configurator

Diagnostics without Configurator

ERROR MESSAGES

The Table 4.2 presents a list of possible diagnosis for the TP301.

SYMPTOM	CAUSES / SOLUTION
SAT	When the Indicator presents FAIL, the output current 3.6 mA, the default value for FAIL SAFE configuration. If the position may be either below or above the limits. Check if the magnet this installed correctly.
FAIL	The configurator allows the user to configure FAIL, the value of the current, 3.6 mA or 21 mA, it is defined in agreement with FAIL SAFE chosen: Up or Down. Verify electrical connection between the circuit boards.
NO OUTPUT SIGNAL VARIATION	Verify if the Magnet it is not stuck or loosen.

Table 4.2 - TP301 Diagnostics without Configurator

Disassembly Procedure

Refer to **TP301** Exploded View figure (Figure 4.3). Make sure to disconnect power supply before disassembling the position transmitter.

NOTE
NOTE
The numbers indicated between parentheses refer to Figure 4.3 – Exploded View.

Transducer

To remove the transducer from the electronic housing, disconnect before the electrical connections (in the field terminal side) and the main board.

Loosen the hex screw (6) and carefully unscrew the electronic housing from the transducer, observing that the flat cable is not excessively twisted.

Electronic Circuit

To remove the circuit board (5) and indicator (4), first loose the cover locking (7) on the side not marked "Field Terminals", then unscrew the cover (1).

WARNING

The boards have CMOS components which may be damaged by electrostatic discharges. Observe correct procedures for handling CMOS components. It is also recommended to store the circuit boards in electrostatic-proof cases.

CAUTION

Do not rotate the electronic housing more than 270° without disconnecting the electronic circuit from the power supply.



Figure 4.1 - Transducer Rotation

Loosen the two screws (3) that anchor the indicator and the main circuit board. Gently pull out the indicator, and then the main board (5).

Reassembly Procedure

WARNING

Do not assemble the main board with power on.

Transducer

Mount the transducer to the housing turning clockwise until it stops. Then turn it counterclockwise until it faces the square of electronic housing to the square of transducer. Tighten the hex screw **(6)** to lock the housing to the transducer.

Electronic Circuit

Plug transducer connector and power supply connector to main board (5). Attach the display to the main board. Observe the four possible mounting positions. The ↑ mark indicates up position.

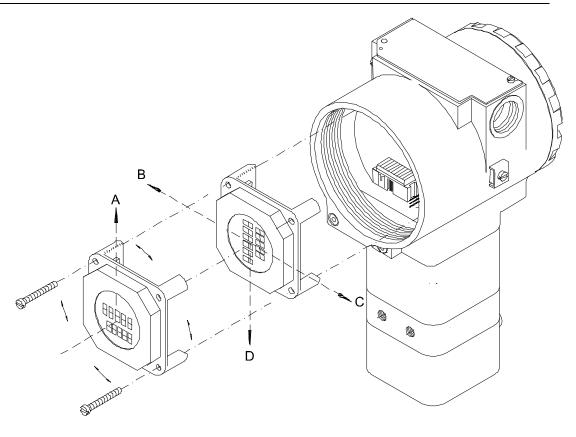


Figure 4.2 – Four Possible Positions for Indicator

Anchor the main board (5) in the housing (8) with their screws (3). After tightening the protective cover (1), mounting procedure is complete. The transmitter is ready to be energized and tested.

Interchangeability

Main board can be replaced by a similar new one keeping the operational features unchanged. The transducer EEPROM has all the information related to the TRIM and factory default configuration.

Accessories

ACCESSORIES			
ORDERING CODE	ORDERING CODE DESCRIPTION		
SD-1	Magnetic Tool for Local Adjustment.		
HPC401* Configurator in platform PalmOS, included interface, USB cable, initialization and installation software.			
400-1176	Teflon guide for linear magnet.		
400-1177	Teflon guide for rotary magnet.		

(*) For equipment updates and software, just check: http://www.smarresearch.com

Exploded View

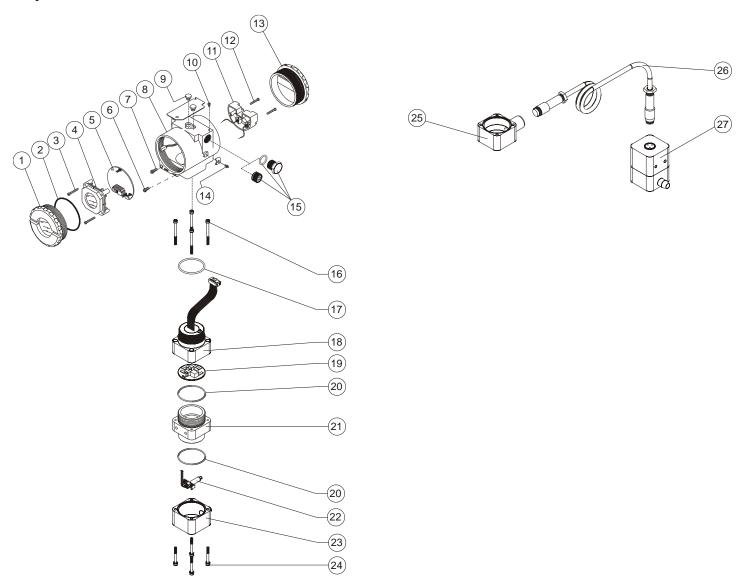


Figure 4.3 - TP301 Exploded View

Spare Parts List

SPARE PARTS LIST				
DESCRIPTION OF PARTS		POSITION	CODE	CATEGORY (NOTE 1)
COVER WITH WINDOW	. Aluminum	1	204-0103	(110121)
	. 316 SS	1	204-0106	
COVER O-RING (NOTE 3)	. Buna-N	2	204-0122	В
ALUMINUM HOUSING MAIN BOARD SCREW	. Units with indicator	3	304-0118	
	. Units without indicator	3	304-0117	
STAINLESS STEEL HOUSING MAIN BOARD SCREW	. Units with indicator	3	204-0118	
DIGITAL INDICATOR	. Units without indicator	3	204-0117	
			214-0108	^
MAIN ELECTRONIC CIRCUIT BOARD	M4.0	5 6	400-0098	Α
HOUSING LOCKING SCREW	. M4 Screw	6	204-0121	
COVED LOCKING CODEW	. M6 Without Head Screw	_	400-1121	
COVER LOCKING SCREW		7	204-0120	
HOUSING (NOTE 2)		8	(NOTE 5)	
LOCAL ADJUSTMENT PROTECTION CAP		9	204-0114	
IDENTIFICATION PLATE SCREW		10	204-0116	
TERMINAL BLOCK ISOLATOR		11	400-0058	
TERMINAL BLOCK HOLDING BOLT	. Cover Aluminum	12	304-0119	
TERMINAL BEOOKTIGEBING BOET	. Cover 316 SS	12	204-0119	
COVER WITHOUT WINDOW	. Aluminum	13	204-0102	
COVER WITHOUT WINDOW	. 316 SS	13	204-0105	
EXTERNAL GROUND BOLT		14	204-0124	
SIX-SIDED INTERNAL PLUG	. 1/2" NPT Bichromatized Carbon SteeL BR-EX D	15	400-0808	
	. 1/2" NPT 304 SST BR-EX D	15	400-0809	
SIX-SIDED INTERNAL PLUG	. 1/2" NPT Bichromatized Carbon SteeL	15	400-0583-11	
	. 1/2" NPT 304 SST	15	400-0583-12	
SIX-SIDED EXTERNAL PLUG	. M20 X 1.5 316 SST	15	400-0810	
OIX OIDED EXTERNAL LEGG	. PG13.5 316 SST	15	400-0811	
RETAINING BUSHING	. 3/4" NPT 316 SST	15	400-0812	
CONNECTION COVER SCREW		16	400-0883	
CONNECTION COVER SET	. Aluminum	16, 17, 18, 19	400-0884	
CONNECTION COVER SET	. 316 SS	16, 17, 18, 19	400-0885	
O-RING, Neck (NOTE 3)	. Buna-N	17	204-0113	В
CONNECTION COVER	. Aluminum	18	400-0074	
CONNECTION COVER	. 316 SS	18	400-0391	
ANALOG BOARD		19	400-0637	
UNION BLOCK O-RING		20	400-0085	В
UNION BLOCK	. Aluminum	21	400-0386	
ONION DECON	. 316 SS	21	400-0387	
POSITION SENSOR COVER SET	. Aluminum	22, 23, 24	400-0656	
POSITION SENSOR BRACKET + POSITION SENSOR SENSOR +	. 316 SS	22, 23, 24	400-0657 400-0090	
FLAT CABLE	<u> </u>			
POSITION SENSOR COVER	. Aluminum	23	400-0089	
	. 316 SS	23	400-0396	
POSITION SENSOR COVER BOLT		24	400-0092	
REMOTE POSITION SENSOR COVER SET(NOTE 4)	. Aluminum	25	400-0853	
(- /	. 316 SS	25	400-0854	

SPARE PARTS LIST					
DESCRIPTION OF PARTS			CODE	CATEGORY (NOTE 1)	
	. 5 M	26	400-0857		
OARLE OFT A CONNECTOR	. 10 M	26	400-0858		
CABLE SET + CONNECTOR	. 15 M	26	400-0859		
	. 20 M	26	400-0860		
DEMOTE EVIENCION OFT	. Aluminum	27	400-0855		
REMOTE EXTENSION SET	. 316 SS	27	400-0856		
TRANSPILOED OFT	. Aluminum	16 a 24	400-0038		
TRANSDUCER SET	. 316 SS	16 a 24	400-0400		
MOUNTING DRACKET III II . OLAMB III II TO DIDE OI	. Carbon Steel	-	400-0339		
MOUNTING BRACKET,"L" + CLAMP "U" TO PIPE 2"	. 316 SS	-	400-0340		
	. Linear up to 50 mm	-	400-0035		
MACNIFTO	. Linear up to 100 mm	-	400-0036		
MAGNETS	. Linear up to 30 mm		400-0748		
	. Rotary	-	400-0037		

NOTA

Note 1: For category **A** it is recommended to keep in stock 25 parts installed for each set and 50 for category **B**. **Nota 2:** Includes terminal block isolator, bolts (cover locking, ground and terminal block isolator) and identification plate without certification.

Note 3: O-rings are packaged with 12 units.

Nota 4: Includes cover, position sensor flat cable, and extension cable connector.

Nota 5: To specify the housing, use HOUSING ORDER CODE table.

HOUSING OF	RDER CODE
400-1314	HOUSING
	COD. Product
	5 TP301
	COD. Communications Protocol
	H HART & 4-20 mA
	COD. Electrical Connection
	0 ½ NPT
	A M20 X 1.5 B PG13.5
	COD. Housing Material
	H0 Aluminum Housing (IP/Type)
	H1 316 SST Housing (IP/Type)
	H2 Aluminum for saline atmosphere (IPW/TYPE X)
	H4 Copper Free Aluminium (IPW/TYPEX)
	COD. Painting
	P0 Gray Munsell N 6.5 Polyester
	P3 Black Polyester
	P8 Without Painting
	P9 Safety Blue Epoxy – Electrostatic Painting
	COD. Manufacturing Standard
	S0 Smar
400-1314	5 H * * * * TYPICAL MODEL NUMBER

^{*} Select item.

TECHNICAL CHARACTERISTICS

Function Specifications

	Linear Motion: 2 400 mm					
Travel	Linear Motion: 3 – 100 mm.					
	Rotary Motion: 30 – 120° rotation angle.					
Input Signal	4-20 mA, Two-wire.					
Protection against	12 to 45 Vdc.					
Reverse Polarity	12 to 45 vac.					
Communication	Light Communication Protocol (legislation and on the communication)					
Protocol	Hart® Communication Protocol (Is superimposed on the current signal).					
Indicator	LCD indicator (4½-numerical digit and 5- alphanumerical characters).					
Hazardous Area	Explosion-proof and intrinsically safe (ATEX (NEMKO and DEKRA EXAM), FM, CEPEL and CSA).					
Certifications	Designed to comply with European regulations ATEX 94/9/EC and LVD 2006/95/EC standards.					
Zero and Span						
Adjustments	Non-interactive, via local adjustment or digital communication.					
-	Ambient: - 40 to 85 °C (- 40 to 185 °F)					
	(10 10 10 1)					
Temperature Limits	Storage: -40 to 90 °C (-40 to 194 °F)					
remperature Limits	Digital Display: -10 to 75 °C (14 to 167 °F) operation;					
	- 40 to 85 °C (- 40 to 185 °F) without damage.					
	Remote Sensor: - 40 to 105°C (- 40 to 221°F)					
Failure Alarm	In case of sensor or circuit failure, the self-diagnostics drivers the output to 3.9 or 21 mA, according to					
I allule Alailli	the user's choice.					
Turn-on Time	urn-on Time Performs within specifications in less than 5 seconds after power is applied to the transmitter.					
Update Time	Approximately 150 ms.					
Humidity Limits	0 to 100% RH.					
Output Action Direct or Reverse.						
Actual Position	Position					
Sensing	Magnetic (Non-contact) via Hall Effect.					
	Configuration can be done through digital communication using the Hart® protocol or partially through					
Configuration	local adjustment.					
L	,					

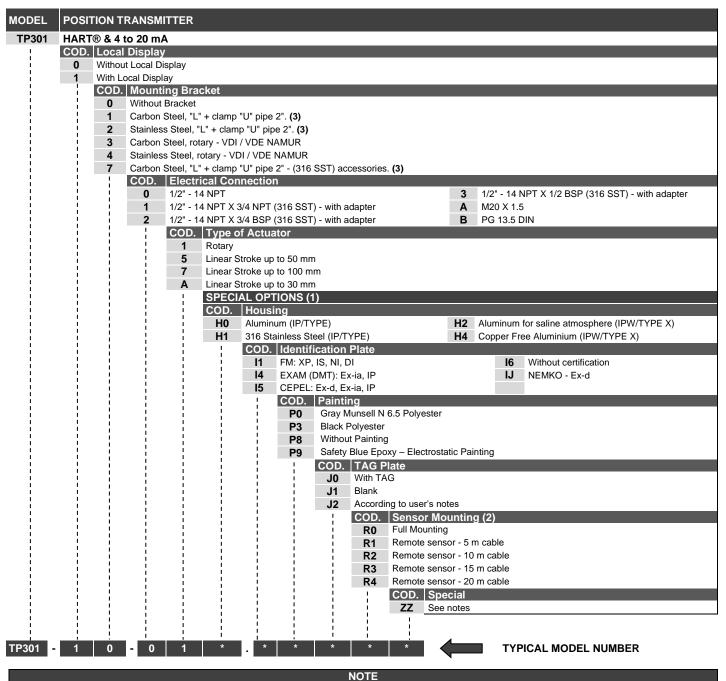
Performance Specifications

Accuracy	≤ 0.2% F. S. the effects of linearity, hysteresis and repeatability are included. (NOTE: Valid value only when used with the table of points. See configuration section in this manual).
Resolution	≤ 0.1% F.S.
Repeatability	≤ 0.5% F.S.
Hysteresis of Full Scale	≤ 0.2% F.S.
Stability	± 0.1% F.S.
Temperature Effect	± 0.8%/ 20°C F.S.
Power Supply Effect	± 0.005% F.S. Calibration.
Electromagnetic Interface Effect	Designed to comply with European Directive EMC 2004/108/EC.

Physical Specifications

Electrical Connection ½ - 14 NPT, PG 13.5, or M20 x 1.5.					
Material of	of Injected low copper aluminum with polyester painting or 316 stainless steel housing, with Buna-N o-				
Construction	rings on cover (Nema 4X FM, IP65/67 EXAM, IP66/68 CEPEL).				
Mounting Bracket	nting Bracket Plated carbon steel with polyester painting or 316 SST.				
Identification Plate	316 SST.				
Approximate Weights	TP 1.5 kg in Aluminum (without mounting bracket); 3.3 kg in Stainless Steel (without mounting bracket). Remote sensor: 0.58 kg in Aluminum; 1.5 kg in Stainless Steel. Cable and remote sensor connectors: Cable 0.045 kg/m; 0.05 kg for each connector.				

Ordering Code



1) Leave it blank when there are not optional items.

2) Consult us for classified areas applications.

3) Magnet mounting bracket not supplied with the TP.

CERTIFICATIONS INFORMATION

European Directive Information

Consult www.Smar.com for the EC declarations of conformity and certificates.

Authorized representative/importer located within the Community:

Smar Europe BV De Oude Wereld 116 2408 TM Alphen aan den Rijn Netherlands

ATEX Directive 2014/34//EU - "Equipment for explosive atmospheres"

The EC-Type Examination Certificate is released by DNV GL Presafe AS (CE2460) and DEKRA Testing and Certification GmbH (CE0158).

Designated certification body that monitors manufacturing and released QAN (Quality Assurance Notification) and QAR (Quality Assessment Report) is Nemko AS (CE0470).

LVD Directive 2014/35/EU - "Low Voltage"

According the LVD directive Annex II, electrical equipment for use in an explosive atmosphere is outside the scope of this directive.

According to IEC standard: IEC 61010-1 Safety requirements for electrical equipment for measurement, control, and laboratory use - Part 1: General requirements.

ROHS Directive 2011/65/EU - "Restriction of the use of certain hazardous substances in electrical and electronic equipment"

For the evaluation of the products the following standards were consulted: EN 50581.

EMC Directive 2014/30/EU - "Electromagnetic Compatibility"

For products evaluation, the standard IEC 61326-1 were consulted and to comply with the EMC directive the installation must follow these special conditions:

Use shielded, twisted-pair cable for powering the instrument and signal wiring.

Keep the shield insulated at the instrument side, connecting the other one to the ground.

Hazardous locations general information

Ex Standards:

IEC 60079-0 General Requirements

IEC 60079-1 Flameproof Enclosures "d"

IEC 60079-7 Increased Safe "e"

IEC 60079-11 Intrinsic Safety "i"

IEC 60079-18 Encapsulation "m"

IEC 60079-26 Equipment with equipment protection level (EPL) Ga

IEC 60079-31 Equipment dust ignition protection by enclosure "t"

IEC 60529 Classification of degrees of protection provided by enclosures (IP Code)

IEC 60079-10 Classification of Hazardous Areas

IEC 60079-14 Electrical installation design, selection and erection

IEC 60079-17 Electrical Installations, Inspections and Maintenance

IEC 60079-19 Equipment repair, overhaul and reclamation

ISO/IEC80079-34 Application of quality systems for equipment manufacture

Warning:

Explosions could result in death or serious injury, besides financial damage.

Installation of this instrument in hazardous areas must be in accordance with the local standards and type of protection. Before proceedings with installation make sure that the certificate parameters are in accordance with the classified hazardous area.

Maintenance and Repair

The instrument modification or replaced parts supplied by any other supplier than authorized representative of Smar is prohibited and will void the Certification.

Marking Label

The instrument is marked with type of protection options. The certification is valid only when the type of protection is indicated by the user. Once a particular type of protection is installed, do not reinstall it using any other type of protection.

Instrinsic Safety / Non Incendive application

In hazardous areas with intrinsic safety or non-incendive requirements, the circuit entity parameters and applicable installation procedures must be observed.

The instrument must be connected to a proper intrinsic safefy barrier. Check the intrinsically safe parameters involving the barrier and equipment including the cable and connections. Associated apparatus ground bus shall be insulated from panels and mounting enclosures. Shield is optional, when using shielded cable, be sure to insulate the end not grounded.

Cable capacitance and inductance plus Ci and Li must be smaller than Co and Lo of the Associated Apparatus. It is recommended do not remove the housing covers when powered on.

Explosionproof / Flameproof application

Only use Explosionproof/Flameproof certified Plugs, Adapters and Cable glands.

The electrical connections entries must be connected using a conduit with sealed unit or closed using metal cable gland or metal blanking plug with at least IP66.

Do not remove the housing covers when powered on.

Enclosure

The electronic housing and sensor threads installed in hazardous areas must have a minimum of 6 fully engaged threads.

The covers must be tightening with at least 8 turns, to avoid the penetration of humidity or corrosive gases, and until it touches the housing. Then, tighten more 1/3 turn (120°) to guarantee the sealing. Lock the housing and covers using the locking screw.

Degree of Protection of enclosure (IP)

IPx8: Second numeral meaning continuous immersion in water under special condition defined as 10m for a period of 24 hours (Ref: IEC60529).

IPW/ TypeX: Supplementary letter W or X meaning special condition defined as saline environment tested in saturated solution of NaCl 5% w/w at 35°C for a period of 200 hours (Ref: NEMA 250/ IEC60529).

For enclosure with IP/IPW/TypeX applications, all NPT threads must apply a proper water-proof sealant (a non-hardening silicone group sealant is recommended).

Hazardous Locations Approvals

FM Approvals

FM 3010145 / FM 3007267 IS Class I, II, III Division 1, Groups A, B, C and D, E, F, G XP Class I, Division 1, Groups A, B, C, D DIP Class II, III Division 1, Groups E, F, G NI Class I, Division 2, Groups A, B, C, D

Option: Type 4X or Type 4 Entity Parameters:

Vmax = 30 Vdc, Imax = 110 Ma, Ci = 5 nF, Li = 12 uH

Temperature Class: T4

Ambient Temperature: 60°C (-20 to 60 °C)

Drawing 102A-0604, 102A-1236, 102A-1349, 102A-1957, 102A-1958

ATEX DNV GL Presafe AS

Explosion Proof (PRESAFE 21 ATEX 17657X) II 2G Ex db IIC T6 Gb Ta -20 °C to +60 °C Options: IP66/68W or IP66/68

Options. If corcerv of it corce

Special Conditions for Safe Use

ATEX and IECEx certified cable gland to be used.

Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 3 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with:

EN 60079-0:2018 General Requirements EN 60079-1:2014 Flameproof Enclosures "d"

Drawing 102A-1450, 102A-1506 IECEx DNV GL Presafe A/S

Explosion Proof (IECEx PRE 21.0015X) Ex db IIC T6 Gb Ta -20 °C to +60 °C

Options: IP66/68W or IP66/68

Special Conditions for Safe Use

ATEX and IECEx certified cable gland to be used.

Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 3 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with:

IEC 60079-0:2017 General Requirements

IEC 60079-1:2014-06 Equipment protection by flameproof enclosures "d"

Drawing 102A2165, 102A2166

DEKRA Testing and Certification GmbH

Intrinsic Safety (DMT 00 ATEX E 085)

Group I, Category M2, Ex ia, Group I, EPL Mb

Group II, Category 2 G, Ex ia, Group IIC, Temperature Class T4/T5/T6, EPL Gb

Supply and signal circuit intended for connection to an intrinsically safe 4-20 mA current loop:

Ui = 28 Vdc, Ii = 93 mA, Ci ≤ 5 nF Li = Neg

Maximum Permissible Power:

Max. Ambient temperature Ta	Temperature Class	Power Pi	
85°C	T4	700 mW	
75°C	T4	760 mW	
44°C	T5	760 mW	
50°C	T5	700 mW	
55°C	T5	650 mW	
60°C	T5	575 mW	
65°C	T5	500 mW	
70°C	T5	425 mW	
40°C	T6	575 mW	

Ambient Temperature: -40°C ≤ Ta ≤ + 85°C

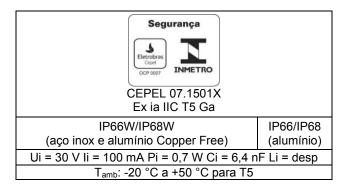
The Essential Health and Safety Requirements are assured by compliance with: EN 60079-0:2012 + A11:2013 General Requirements

EN 60079-11:2012 Intrinsic Safety "i"

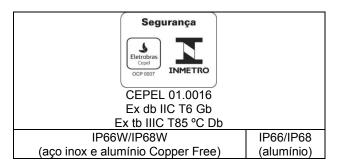
Drawing 102A-1450, 102A-1506, 102A-1580, 102A-1581

CEPEL (Centro de Pesquisa de Energia Elétrica)

Segurança Intrínseca (CEPEL 07.1501X)



Prova de Explosão (CEPEL 01.0016)



Observações:

A validade deste Certificado de Conformidade está atrelada à realização das avaliações de manutenção e tratamento de possíveis não conformidades, de acordo com as orientações do Cepel, previstas no Regulamento de Avaliação da Conformidade. Para verificação da condição atualizada de regularidade deste Certificado de Conformidade deve ser consultado o banco de dados de produtos e serviços certificados do Inmetro.

O número do certificado é finalizado pela letra "X" para indicar que para a versão do Transmissor de Posição, Intrinsecamente Seguro, modelos TP290, TP301, TP302 e TP303 equipado com invólucro fabricado em liga de alumínio, somente pode ser instalado em "Zona 0", se durante a instalação for excluído o risco de ocorrer impacto ou fricção entre o invólucro e peças de ferro/aço.

A tampa do invólucro possui uma plaqueta de advertência com a seguinte inscrição: "ATENÇÃO - NÃO ABRA ENQUANTO ENERGIZADO", ou similar tecnicamente equivalente.

O produto adicionalmente marcado com a letra suplementar "W" indica que o equipamento foi ensaiado em uma solução saturada a 5% de NaCl p/p, à 35 °C, pelo tempo de 200 h e foi aprovado para uso em atmosferas salinas, condicionado à utilização de acessórios de instalação no mesmo material do equipamento e de bujões de aço inoxidável ASTM-A240, para fechamento das entradas roscadas não utilizadas. Os materiais de fabricação dos equipamentos aprovados para letra "W" são: aço inoxidável AISI 316 e alumínio Copper Free SAE 336 pintados (Procedimento P-CQ-FAB764-10) com tinta Resina Poliéster ou Resina Epoxy com espessura da camada de tinta de 70 a 150 µm e 120 a 200 µm, respectivamente, ou pintados com o plano de pintura P1 e P2 (Procedimento P-CQ-FAB-765-05) com tinta Resina Epoxy ou Poliuretano Acrílico Alifático com espessura de camada de tinta de 290 µm a 405 µm e 185 µm a 258 µm, respectivamente.

Os planos de pintura P1 e P2 são permitidos apenas para equipamento fornecido com plaqueta de identificação com marcação para grupo de gás IIB.

O grau de proteção IP68 só é garantido se nas entradas roscadas de ½" NPT for utilizado vedante não endurecível à base de silicone conforme Procedimento P-DM-FAB277-07.

O segundo numeral oito indica que o equipamento foi ensaiado para uma condição de submersão de dez metros por vinte e quatro horas. O acessório deve ser instalado em equipamentos com grau de proteção equivalente.

Este certificado é válido apenas para os produtos dos modelos avaliados. Qualquer modificação nos projetos, bem como a utilização de componentes ou materiais diferentes daqueles definidos pela documentação descritiva dos produtos, sem a prévia autorização do Cepel, invalidará este certificado.

É responsabilidade do fabricante assegurar que os produtos fornecidos ao mercado nacional estejam de acordo com as especificações e documentação descritiva avaliada, relacionadas neste certificado.

As atividades de instalação, inspeção, manutenção, reparo, revisão e recuperação dos equipamentos são de responsabilidade dos usuários e devem ser executadas de acordo com os requisitos das normas técnicas vigentes e com as recomendações do fabricante.

A marcação é executada conforme a Norma ABNT NBR IEC 60079-0:2013 e o Requisito de Avaliação da Conformidade de Equipamentos Elétricos para Atmosferas Explosivas nas Condições de Gases e Vapores Inflamáveis (RAC), e é fixada na superfície externa do equipamento, em local visível. Esta marcação é legível e durável, levando-se em conta possível corrosão química.

Normas Aplicáveis:

ABNT NBR IEC 60079-0:2013 Atmosferas explosivas - Parte 0: Equipamentos - Requisitos gerais

ABNT NBR IEC 60079-1:2016 Atmosferas explosivas - Parte 1: Proteção de equipamento por invólucro à prova de explosão "d"

ABNT NBR IEC 60079-11:2013 Atmosferas explosivas - Parte 11: Proteção de equipamento por segurança intrínseca "i"

ABNT NBR IEC 60079-26:2016 Equipamentos elétricos para atmosferas explosivas - Parte 26: Equipamentos com nível de proteção de equipamento (EPL) Ga

ABNT NBR IEC 60079-31:2014 Atmosferas explosivas - Parte 31: Proteção de equipamentos contra ignição de poeira por invólucros "t"

ABNT NBR IEC 60529:2017 Graus de proteção para invólucros de equipamentos elétricos (Código IP)

Desenhos 102A1378, 102A1305, 102A2064, 102A2063, 102A2097

Identification Plates

HARTON CE 0470

FM Approvals

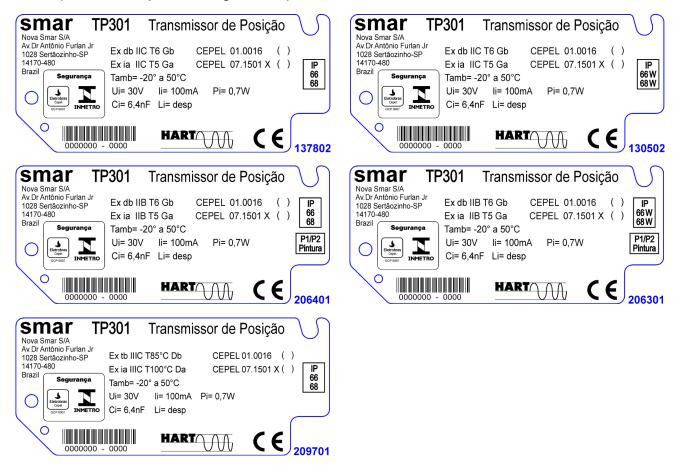


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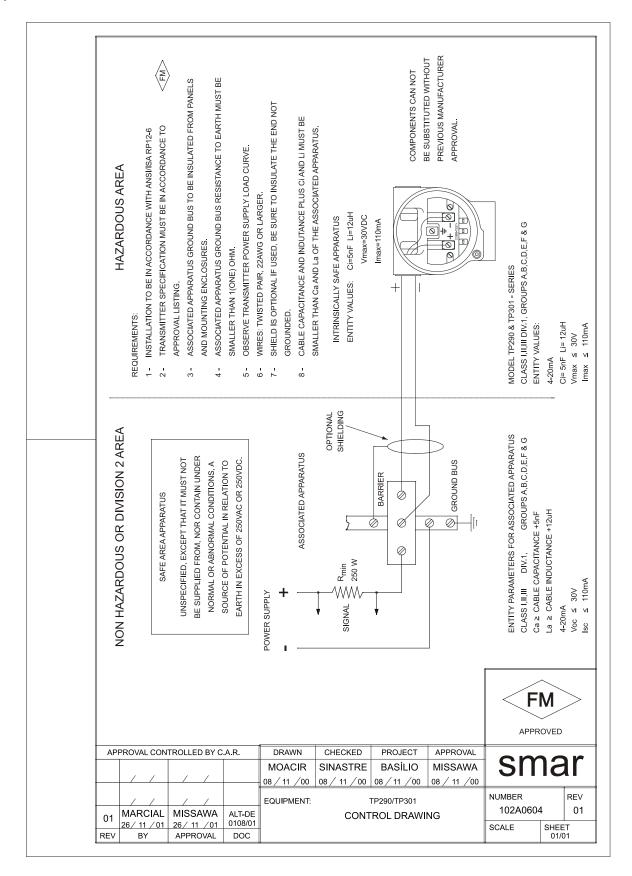
Ui = 28 VDC Ii = 93 mA Li = neg Ci \leq 5 nF

HART ← C € 0470 158101

CEPEL (Centro de Pesquisa de Energia Elétrica)



FM Approvals



E-mail:

			SE	2F_	Serv	ice R	Paupet F	orm
sm	lar	SRF – Service Request Form TP Position Transmitter						
				GENE	RAL DAT		SITIILLEI	
Model:						TP301 ()		:
Serial Number:	TP302 () Firmware Version: TP303 () Firmware Version: Sensor Number:							
TAG:								
Remote Position Sensor?	Yes ()		No ()					
Action:	Rotary ()		Linear ()					
Travel:	30 mm ()		50 mm ()	1	00 mm ()			Other: mn
Configuration	: Magnetic To	ol ()	Palm ()	Psion () P	C()	Software:	Version:
				INSTALI	LATION D	ATA		
Type: Size:	Valve + Atu	uador ()						
Travel:								
Manufacturer:								
Model:								
				PROC	CESS DAT	`A		
Hazardous Áre Classification	ea Non-Class	sified ()	Chemical (()	Explosive	:()	Other:	
Interference Types	Vibration ()	Temperatu	ıre ()	Electroma	agnetic ()	Others:	
			SI	TUATIO	N DESCRI	PTION		
			5	SERVICE	SUGGES	TION		
Adjustment ())	Cleaning	()	Pre	eventive Ma	intenance ()	Update / Up-grade ()
Other:								
				USER IN	NFORMAT	ION		
Company:								
Contact:								
Title:								
Section:								
Phone:							Extensi	on:

For warranty or non-warranty repair, please contact your representative. Further information about address and contacts can be found on www.smar.com/contactus.asp.

Date:

Returning Materials

Should it become necessary to return the transmitter and/or configurator to **SMAR**, simply contact our office, informing the defective instrument serial number, and return it to our factory.

In order to speed up analysis and solution of the problem, the defective item should be returned with a description of the failure observed, with as much details as possible. Other information concerning the instrument operation, such as service and process conditions, is also helpful.

Instruments returned or to be revised outside the guarantee term should be accompanied by a purchase order or a quote request.