

MANUAL

INSTRUCTIONS | OPERATION | MAINTENANCE

INTELLIGENT PRESSURE TRANSMITTER WITH CONTROL CAPABILITY LD301





MAY/25 - VERSION 8



LD301

Intelligent Pressure Transmitter With Control Capability



Consult our subsidiary

























Rua Dr. Antônio Furlan Junior, 1028 - Sertãozinho, SP - CEP: 14170-480 insales@smar.com.br | +55 (16) 3946-3599 | www.smar.com

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INTRODUCTION

LD301 is a smart pressure transmitter for differential, absolute, gauge, level and flow measurements. It is based on a field-proven capacitive sensor that provides reliable operation and high performance. The digital technology used in **LD301** enables the choice of several types of transfer functions, an easy interface between the field and the control room and several interesting features that considerably reduce installation, operation and maintenance costs.

Besides all the functions offered by other smart transmitters, LD301offers the following functions:

- $\sqrt{(\Delta P)^3}$ used for trapezoidal weirs in open channel flow measurement.
- $\checkmark \quad \sqrt{\left(\Delta P\right)^5}$ used for V-notch weirs in open channel flow measurement.
- ✓ TABLE the pressure signal is linearly customized according to a 16-point table, freely configurable.
- ✓ CONTROLLER the Process Variable is compared to a set point. The deviation acts on the output signal according to an optional PID algorithm.
- ✓ PID OUTPUT CHARACTERIZATION the PID output signal (MV) follows a curve that is
 determined by 16 points, which can be freely configured
- ✓ **BIDIRECTIONAL FLOW FUNCTION** used to measure the flow in the piping in both directions.
- ✓ LOCAL ADJUSTMENT It adjusts the lower and upper value using the magnetic key, input/output function, operating mode, indication, setpoint and PID parameters;
- ✓ PASSWORD three levels for different functions.
- ✓ OPERATION COUNTER shows the number of changes in each function.
- ✓ TOTALIZATION flow totalization in volume or mass.
- ✓ USER-UNIT indication in engineering unit of the property measured, e.g., level, flow, or volume.
- ✓ WRITE-PROTECT via hardware

Get the best results of the LD301 by carefully reading these instructions.

Smar pressure transmitters are protected by U.S. patents 6,433,791 and 6,621,443.

NOTE

This manual is compatible with version 8.XX.YY, where 8 indicates software version, XX software release, and YY software emission. The indication 8.XX means that this manual is compatible with any release of version 8 software

WARNING

To ensure that our products are safe and without risk to health, the manual must be read carefully before proceeding and warning labels on packages must be observed. Installation, operation, maintenance, and servicing must only be carried out by suitably trained personnel and in accordance with the **Operation and Maintenance Instruction Manual.**

Waiver of responsibility

The contents of this manual abides by the hardware and software used on the current equipment version. Eventually there may occur divergencies between this manual and the equipment. The information from this document are periodically reviewed and the necessary or identified corrections will be included in the following editions. Suggestions for their improvement are welcome.

Warning

For more objectivity and clarity, this manual does not contain all the detailed information on the product and, in addition, it does not cover every possible mounting, operation or maintenance cases.

Before installing and utilizing the equipment, check if the model of the acquired equipment complies with the technical requirements for the application. This checking is the user's responsibility.

If the user needs more information, or on the event of specific problems not specified or treated in this manual, the information should be sought from Smar. Furthermore, the user recognizes that the contents of this manual by no means modify past or present agreements, confirmation or judicial relationship, in whole or in part.

All of Smar's obligation result from the purchasing agreement signed between the parties, which includes the complete and sole valid warranty term. Contractual clauses related to the warranty are not limited nor extended by virtue of the technical information contained in this manual.

Only qualified personnel are allowed to participate in the activities of mounting, electrical connection, startup and maintenance of the equipment. Qualified personnel are understood to be the persons familiar with the mounting, electrical connection, startup and operation of the equipment or other similar apparatus that are technically fit for their work. Smar provides specific training to instruct and qualify such professionals. However, each country must comply with the local safety procedures, legal provisions and regulations for the mounting and operation of electrical installations, as well as with the laws and regulations on classified areas, such as intrinsic safety, explosion proof, increased safety and instrumented safety systems, among others.

The user is responsible for the incorrect or inadequate handling of equipments run with pneumatic or hydraulic pressure or, still, subject to corrosive, aggressive or combustible products, since their utilization may cause severe bodily harm and/or material damages.

The field equipment referred to in this manual, when acquired for classified or hazardous areas, has its certification void when having its parts replaced or interchanged without functional and approval tests by Smar or any of Smar authorized dealers, which are the competent companies for certifying that the equipment in its entirety meets the applicable standards and regulations. The same is true when converting the equipment of a communication protocol to another. In this case, it is necessary sending the equipment to Smar or any of its authorized dealer. Moreover, the certificates are different and the user is responsible for their correct use.

Always respect the instructions provided in the Manual. Smar is not responsible for any losses and/or damages resulting from the inadequate use of its equipments. It is the user's responsibility to know and apply the safety practices in his country.

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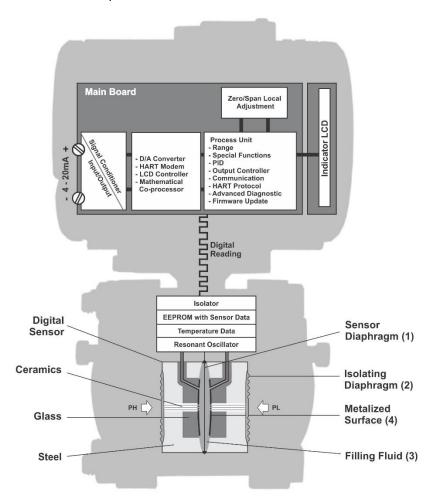
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TRANSMITTER GENERAL VIEW

The **LD301** uses a highly proven technique for pressure measuring by capacitance reading. The block diagram of the **LD301** HART® pressure transmitter is shown below.



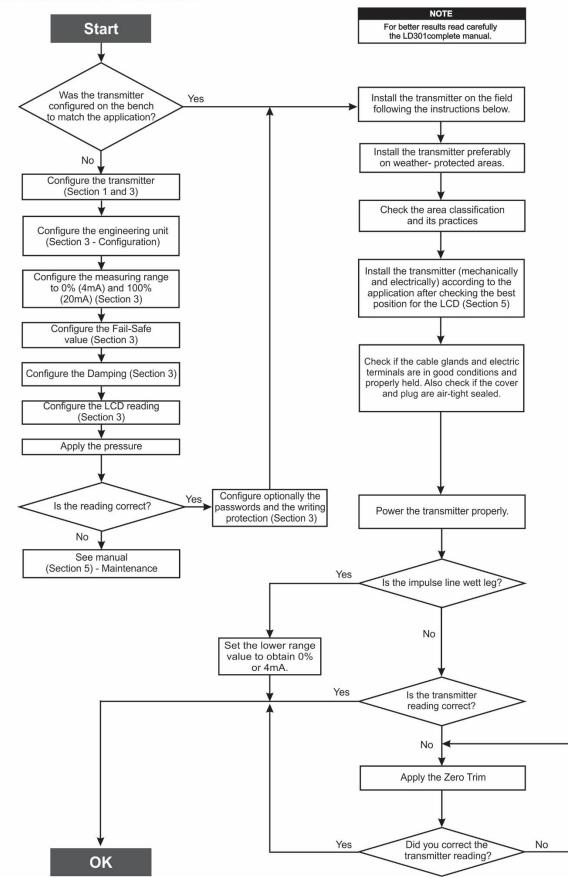
In the cell center is the sensor diaphragm (1). This diaphragm flexes in response to the different pressures applied on the LOW and HIGH sides of the cell (PL and PH). These pressures are directly applied on the isolator diaphragms (2), whose function is to isolate the sensor from the process and provides high resistance against corrosion caused by process fluids. The pressure is transmitted directly to the sensor diaphragm through the filling fluid (3) and causes its deflection. The sensor diaphragm is a mobile electrode whose two metal surfaces (4) are fixed electrodes. A deflection on the sensor diaphragm is read by the capacitance variation between both fixed and mobile electrodes.

The resonant oscillator reads the capacitance variations between the mobile and the fixed boards and generates a pressure output equivalent to the detected capacitance variation. This pressure value is informed in compliance with the transmitter communication protocol. As the conversion process does not involve an A/D converter, errors or deviations are eliminated during the process. Temperature compensation is done by a sensor, which combined with a precision sensor, results in high accuracy and range.

The process variable, as well as the diagnostic monitoring and information, are provided by the digital communication protocol. The **LD301** is available in the HART communication protocol.

Read carefully these instructions for better use of the LD301.

Installation Flowchart



INSTALLATION

General

NOTE

Installations in hazardous areas must follow the recommendations of the applicable standards. Refer to Appendix A for this information.

The overall accuracy of a flow, level, or pressure measurement depends on several variables. Although the transmitter has an outstanding performance, proper installation is essential to maximize its efficiency.

Among all factors, which may affect transmitter accuracy, environmental conditions are the most difficult to control. There are, however, ways of reducing the effects of temperature, humidity and vibration.

The **LD301** has a built-in temperature sensor to compensate for temperature variations. At the factory, each transmitter is submitted to a temperature cycle, and the characteristics under different temperatures are recorded in the transmitter memory. At the field, this feature minimizes the temperature variation effect.

Mounting

Putting the transmitter in areas protected from extreme environmental changes can minimize temperature fluctuation effects.

In warm environments, the transmitter should be installed to avoid, as much as possible, direct exposure to the sun. Installation close to lines and vessels subjected to high temperatures should also be avoided. Use longer sections of impulse piping between tap and transmitter whenever the process fluid is at high temperatures. When necessary, use thermal insulation to protect the transmitter from external heat sources.

Installations where the process fluid can freeze inside the transmitter chamber, should be avoided. This could cause permanent damage to the capacitive cell.

Although the transmitter is virtually insensitive to vibration, installation close to pumps, turbines or other vibrating equipment should be avoided.

The transmitter has been designed to be both rugged and lightweight at the same time. This makes its mounting easier. The mounting positions are shown in Figure 1.1.

Existing standards for the manifolds have also been considered, and standard designs fits perfectly to the transmitter flanges.

Should the process fluid contain solids in suspension, install valves or rod-out fittings regularly to clean out the pipes. The pipes should be internally cleaned by using steam or compressed air, or by draining the line with the process fluid, before such lines are connected to the transmitter (blow-down).

NOTE

When installing or storing the level transmitter, the diaphragm must be protected to avoid scratching-denting or perforation of its surface. The process flange of the level transmitters can be rotated $\pm 45^{\circ}$. To do this just loosen the two screws (Figure 1.1) and rotate the flange. Do not take the screws out. There is a label (Figure 1.1) on the transmitter with these instructions.

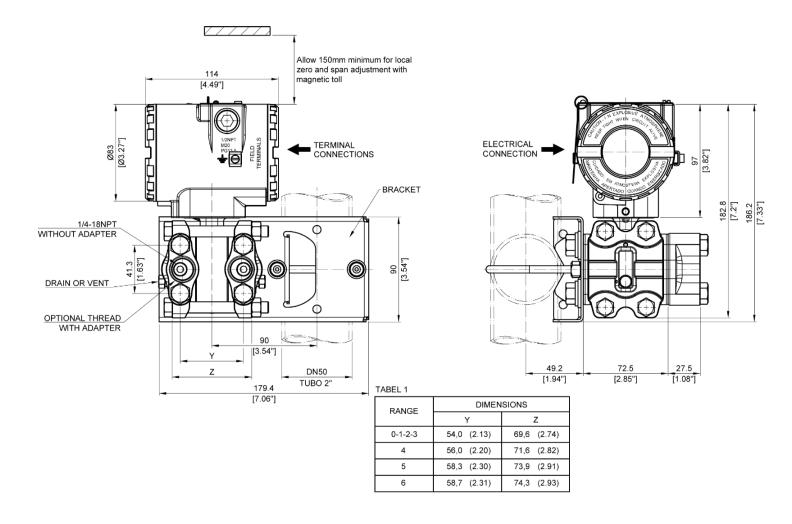
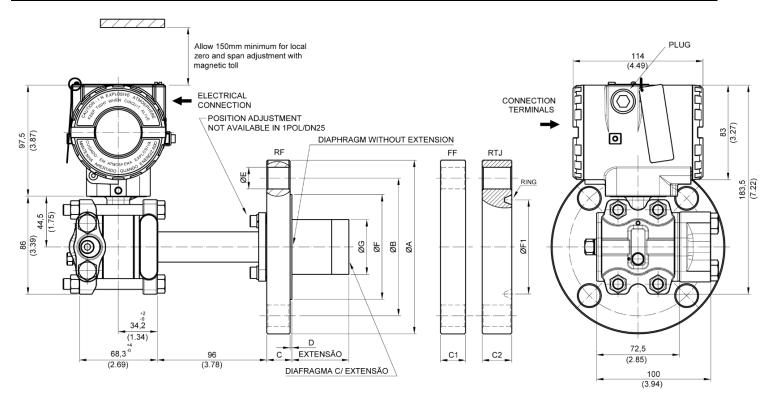


Figure 1.1 (a) – Dimensional Drawing and Mounting Position - Differential, Flow, Gage, Absolute and High Static Pressure

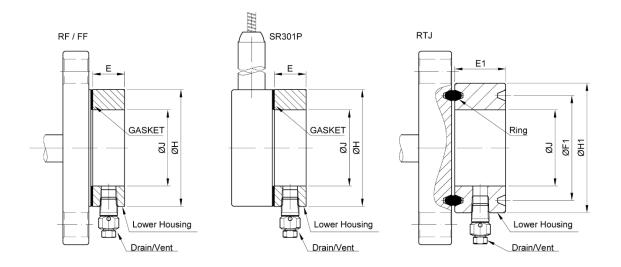
Transmitters with Mounting Bracket



DIMENSIONS IN mm (inch)
EXTENSION LENGHTS: 0 , 50 , 100 , 150 or 200
EXTENSIONS AVAILABLE IN RF ONLY

	ASME-B 16.5 - 2017 DIMENSIONS																					
DN	CLASS	А		В	,	С	C1 ((FF)	C2 (RTJ)		D		E	F		F1 (F	RTJ)	RING		G	HOLES
	150	110 (4.33	79,	2 (3.12)	17	(0.67)	17	(0.67)	21	(0.83)	2	(0.06)	16	(0.63)	50,8	(2)	47,6	(1.87)	R15			4
1"	300	125 (4.92) 88,	9 (3.50)	19	(0.75)	19	(0.75)	25	(0.98)	2	(0.06)	19	(0.75)	50,8	(2)	50,8	(2)	R16	/		4
	600	125 (4.92) 88,9	9 (3.50)	25	(0.96)			25	(0.98)	7	(0.25)	19	(0.75)	50,8	(2)	50,8	(2)	R16			4
	150	125 (4.92	98,6	6 (3.88)	20	(0.78)	20	(0.79)	24,4	(0.96)	2	(0.06)	16	(0.63)	73,2	(2.88)	65,1	(2.56)	R19	40	(1.57)	4
1.1/2"	300	155 (6.10) 114,	3 (4.5)	21	(0.83)	20	(0.79)	28,7	(1.13)	2	(0.06)	22	(0.87)	73,2	(2.88)	68,3	(2.68)	R20	40	(1.57)	4
	600	155 (6.10) 114,	3 (4.5)	29,3	(1.15)			28,7	(1.13)	7	(0.25)	22	(0.87)	73,2	(2.88)	68,3	(2.68)	R20	40	(1.57)	4
	150	150 (5.90) 120,	7 (4.75)	20	(0.79)	20	(0.79)	23,9	(0.94)	2	(0.06)	19	(0.75)	92	(3.62)	82,6	(3.25)	R22	48	(1.89)	4
2"	300	165 (6.50) 127	7 (5)	22,7	(0.89)	20,7	(0.81)	28,6	(1.13)	2	(0.06)	19	(0.75)	92	(3.62)	82,6	(3.25)	R23	48	(1.89)	8
	600	165 (6.50) 127	7 (5)	32,3	(1.27)			33,3	(1.31)	7	(0.25)	19	(0.75)	92	(3.62)	82,6	(3.25)	R23	48	(1.89)	8
	150	190 (7.48) 152,	,4 (6)	24,3	(0.96)	22,3	(0.88)	28,7	(1.13)	2	(0.06)	19	(0.75)	127	(5)	114,3	(4.5)	R29	73	(2.87)	4
3"	300	210 (8.27) 168,	1 (6.62)	29	(1.14)	27	(1.06)	34,9	(1.37)	2	(0.06)	22	(0.87)	127	(5)	123,8	(4.87)	R31	73	(2.87)	8
	600	210 (8.27) 168,	1 (6.62)	38,8	(1.53)			39,7	(1.56)	7	(0.25)	22	(0.87)	127	(5)	123,8	(4.87)	R31.	73	(2.87)	8
	150	228,6 (9)	190,	,5 (7.5)	24,3	(0.96)	22,3	(0.88)	28,7	(1.13)	2	(0.06)	19	(0.75)	157	(6.19)	149,2	(5.87)	R36	89	(3.50)	8
4"	300	255 (10	200	(7.87)	32,2	(1.27)	30,2	(1.19)	38,1	(1.50)	2	(0.06)	22	(0.87)	157	(6.19)	149,2	(5.87)	R37	89	(3.50)	8
	600	275 (10.8	3) 215,	9 (8.5)	45,1	(1.77)			46	(1.81)	7	(0.25)	25	(1)	157	(6.19)	149,2	(5.87)	R37	89	(3.50)	8
								EN 1	1092	-1-20	800	DIM	ENS	SION	S							
DN	PN	Α		В	(0	C1 ((FF)				D	j	E	F						G	HOLES
25	10/40	115 (4.53	85	(3.35)	19	(0.75)	19	(0.75)			2	(80.0)	14	(0.55)	68	(2.67)						4
40	10/40	150 (5.91) 110	(4.33)	20	(0.78)	20	(0.78)			3	(0.12)	18	(0.71)	88	(3.46)				40	(1.57)	4
50	10/40	165 (6.50	125	5 (4.92)	20	(0.78)	20	(0.78)			3	(0.12)	18	(0.71)	102	(4.01)				48	(1.89)	4
80	10/40	200 (7.87) 160	(6.3)	24	(0.95)	24	(0.95)] /	/	3	(0.12)	18	(0.71)	138	(5.43)				73	(2.87)	8
100	10/16	220 (8.67	180	(7.08)	20	(0.78)		$\overline{}$] /		3	(0.12)	18	(0.71)	158	(6.22)	/			89	(3.50)	8
100	25/40	235 (9.25) 190	(7.5)	24	(0.95)					3	(0.12)	22	(0.87)	162	(6.38)				89	(3.50)	8
								J	IS B	2220) DI	MEN	SIO	NS								
	CLASS	Α		В	(0						D		E	, F	-					G _i	HOLES
40A	20K	140 (5.5) 105	(4.13)	20	(0.78)					2	(0.08)	19	(0.75)	81	(3.2)				40	(1.57)	4
	10K	155 (6.1) 120	(4.72)	20	(0.78)					2	(0.08)	15	(0.59)	96	(3.78)				48	(1.89)	4
50A	20K	155 (6.1) 120	(4.72)	20	(0.78)					2	(0.08)	19	(0.75)	96	(3.78)				48	(1.89)	8
	40K	165 (6.5) 130	(5.12)	26	(1.02)		/	/		2	(0.08)	19	(0.75)	105	(4.13)		/		48	(1.89)	8
004	10K	185 (7.2	3) 150	(5.9)	22	(0.87)					2	(0.08)	19	(0.75)	126	(4.96)				73	(2.87)	8
80A	20K	200 (7.8	7) 160	(6.3)	22	(0.87)	/				2	(80.0)	19	(0.75)	132	(5.2)	/			73	(2.87)	8
100A	10K	210 (8.2	7) 175	(6.89)	20	(0.78)					2	(0.08)	19	(0.75)	151	(5.95)				89	(3.50)	8

Figure 1.1 (b) - Dimensional Drawing and Mounting Position - Flanged Pressure Transmitter with Integral Flange



		DIMENS	SIONS - RF / FF	- mm (inch)		
STANDARD	DN	CLASS	Н	J		Ε
STANDARD	DIN CEASS III 3	J	1/4"NPT	1/2"NPT		
	1"		50,8 (2,00)	35 (1,38)	25	
	1.1/2"		73,2 (2,88)	48 (1,89)	25	35
ASME B16.5	2"	ALL	91,9 (3,62)	60 (2,36)	25	35
	3"		127 (5,00)	89 (3,50)	25	35
	4"		158 (6,22)	115 (4,53)	25	35
	25	ALL	68 (2,68)	35 (1,38)	25	35
	40		88 (3,46)	48 (1,89)	25	35
DIN EN 1092-1	50		102 (4,02)	60 (2,36)	25	35
	80		138 (5,43)	89 (3,50)	25	35
	100		158 (6,22)	115 (4,53)	25	35
	40A	20K	81 (3,19)	48 (1,89)	25	35
	504	10K	96 (3,78)	60 (1,36)	25	35
JIS B 2220	50A	40K	105 (4,13)	60 (1,36)	25	35
0.0 0 2220	204	10K	126 (4,96)	89 (3,50)	25	35
	80A	20K	132 (5,20)	89 (3,50)	25	35
	100A	10K	151 (5,94)	115 (4,53)	25	35

						F	1
DN	CLASS	F1	RING	H1	J	1/4"NPT	1/2"NPT
	150	47,6 (1,87)	R15	63,5 (2,50)	35 (1,38)	40	45
	300	50,8 (2,00)	R16	70 (2,75)	35 (1,38)	40	45
1"	600	50,8 (2,00)	R16	70 (2,75)	35 (1,38)	40	45
	1500	50,8 (2,00)	R16	71,5 (2,81)	35 (1,38)	40	45
	2500	60,3 (2,37)	R18	73 (2,88)	35 (1,38)	40	45
	150	65,1 (2,56)	R19	82,5 (3,25)	48 (1,89)	40	45
	300	68,3 (2,69)	R20	90,5 (3,56)	48 (1,89)	40	45
1.1/2"	600	68,3 (2,69)	R20	90,5 (3,56)	48 (1,89)	40	45
	1500	68,3 (2,69)	R20	92 (3,62)	48 (1,89)	40	45
	2500	82,6 (3,25)	R23	114 (4,50)	48 (1,89)	40	45
	150	82,6 (3,25)	R22	102 (4,00)	60 (2,36)	40	45
	300	82,6 (3,25)	R23	108 (4,25)	60 (2,36)	40	45
2"	600	82,6 (3,25)	R23	108 (4,25)	60 (2,36)	40	45
	1500	95,3 (3,75)	R24	124 (4,88)	60 (2,36)	40	45
	2500	101,6 (4,00)	R26	133 (5,25)	60 (2,36)	40	45
	150	114,3 (4,50)	R29	133 (5,25)	89 (3,50)	40	45
3"	300	123,8 (4,87)	R31	146 (5,75)	89 (3,50)	40	45
	600	123,8 (4,87)	R31	146 (5,75)	89 (3,50)	40	45
	150	149,2 (5,87)	R36	171 (6,75)	115 (4,53)	40	45
4"	300	149,2 (5,87)	R37	175 (6,88)	115 (4,53)	40	45
	600	149,2 (5,87)	R37	175 (6,88)	115 (4,53)	40	45

LOWER HOUSING 1/2NPT SUPPLIED WITH PLASTIC PROTECTION NOT LOWER HOUSING 1/2 NPT FOR 1 INCH

Figure 1.1 (c) - Dimensional Drawing and Mounting Position - Lower Housing

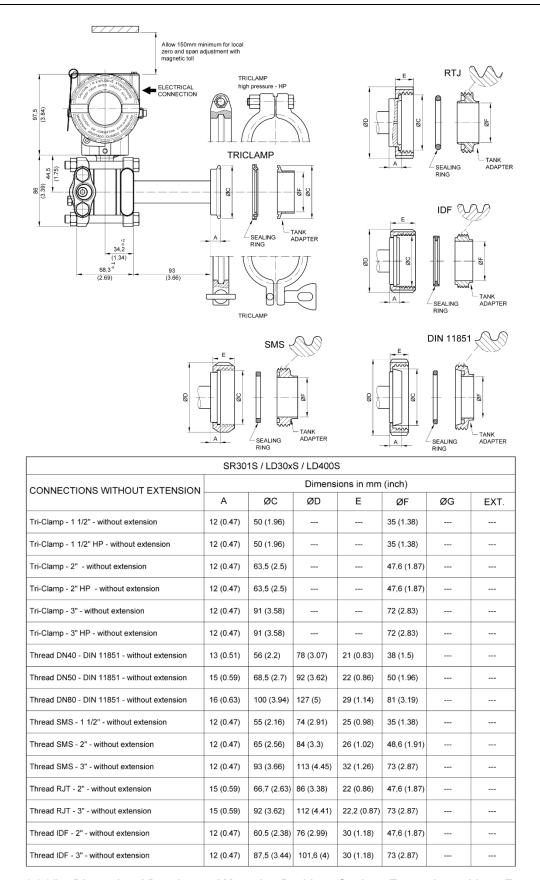


Figure 1.1 (d) – Dimensional Drawing and Mounting Position - Sanitary Transmitter without Extension

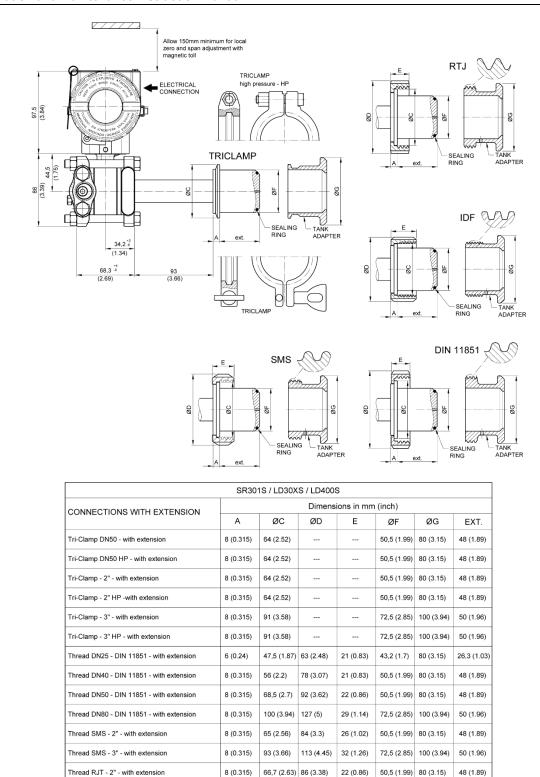


Figure 1.1 (e) - Dimensional Drawing and Mounting Position - Sanitary Transmitter with Extension

92 (3.62)

60.5 (2.38) 76,2 (3)

87,5 (3.44) 101,6 (4)

112 (4.41)

22,2 (0.87)

30 (1.18)

30 (1.18)

72,5 (2.85) 100 (3.94)

50,5 (1.99) 80 (3.15)

72,5 (2.85) 100 (3.94)

50 (1.96)

48 (1.89)

50 (1.96)

8 (0.315)

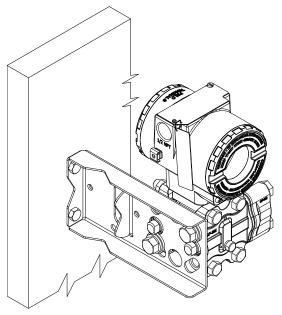
8 (0.315)

8 (0.315)

Thread RJT - 3" - with extension

Thread IDF - 2" - with extension

Thread IDF - 3" - with extension



WALL OR PANEL MOUNTING

(See Section 5 – spare parts list for mounting brackets available)

Figure 1.2 - Drawing of LD301 Mounted on the Panel or Wall

Observe operating safety rules during wiring, draining or blow-down.

WARNING

Normal safety precautions must be taken to avoid the possibility of an accident occurring when operating in conditions of high pressure and/or temperature.

Electrical shock can result in death or serious injury.

Avoid contact with the leads and terminals.

Process leaks could result in death or serious injury.

Do not attempt to loosen or remove flange bolts while the transmitter is in service.

Replacement equipment or spare parts not approved by Smar could reduce the pressure retaining capabilities of the transmitter and may render the instrument dangerous.

Use only bolts supplied or sold by Smar as spare parts.

Some examples of installation, illustrating the transmitter position in relation to the taps, are shown in Figure 1.3. The pressure taps location and the relative positions of the transmitter are indicated in Table 1.1.

Process Fluid	Location of	Location of LD301 in Relation to the Taps
Gas	Top or Side	Above the Taps
Liquid	Side	Below the Taps or at the Piping Centerline
Steam	Side	Below the Taps using Sealing (Condensate) Pots

Table 1.1 - Location of Pressure Taps

NOTE

For liquids, condensates, wet vapors and gases the impulse lines must be tilted on the ratio 1:10 to prevent bubbles from accumulating;

The transmitter and its impulse lines must be tightly fixed;

If necessary, install the condensate and mud pots:

Use manifold valves to facilitate maintenance and adjustments.

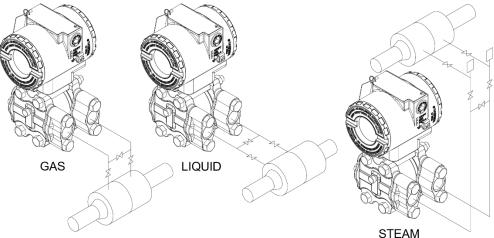
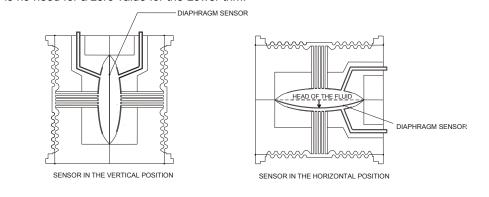


Figure 1.3 – Position of the Transmitter and Taps

NOTE

The transmitters are calibrated in the vertical position and a different mounting position displaces the zero point. Consequently, the indicator will indicate a different value from the applied pressure. In these conditions, it is recommended to do the zero pressure trim. The zero trim compensates the final assembly position and its performance, when the transmitter is in its final position. When the zero trim is executed, make sure the equalization valve is open and the wet leg levels are correct.

For the absolute pressure transmitter, the assembly effects correction should be done using the Lower trim, due to the fact that the absolute zero is the reference for these transmitters, so there is no need for a zero value for the Lower trim.



Electronic Housing

Humidity is fatal to electronic circuits. In areas subjected to high relative humidity, the O-rings for the electronic housing covers must be correctly placed and the covers must be completely closed by tighten them by hand until you feel the O-rings being compressed. Do not use tools to close the covers. Removal of the electronics cover in the field should be reduced to the minimum necessary, since each time it is removed; the circuits are exposed to the humidity.

The electronic circuit is protected by a humidity proof coating, but frequent exposures to humidity may affect the protection provided. It is also important to keep the covers tightened in place. Every time they are removed, the threads are exposed to corrosion, since painting cannot protect these parts. Sealing methods should be employed on conduit entering the transmitter. The unused outlet connection should be properly plugged.

WARNING

The unused cable entries should be plugged and sealed accordingly to avoid humidity entering, which can cause the loss of the product's warranty.

The electronic housing can be rotated to adjust the digital display on a better position. To rotate it, loose the Housing Rotation Set Screw, see Figure 1.4 (a). To prevent humidity entering, the electric housing and the sensor joint must have a minimum of 6 fully engaged threads. The provided joint allows 1 extra turn to adjust the position of the display window by rotating the housing clockwise. If the thread reaches the end before the desired position, then rotate the housing counterclockwise, but not more than one thread turn. See Section 5, Figure 5.2.

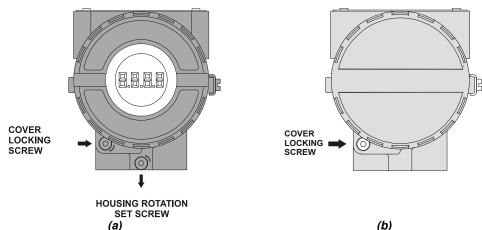


Figure 1.4 - Cover Locking and Housing Rotating Set Screw (a) Electronic Board Side
(b) Terminal Connection Side

Wiring

To access the wiring block, loosen the cover locking screw to release the cover. See Figure 1.4 (b).

Test and **Communication terminals** allow, respectively, to measure the current in the 4 - 20 mA loop, without opening the circuit, and also to communicate with the transmitter. The "Test Terminals" must be used to measure the current. The "COMM" terminal must be used for HART communication. The terminal block has screws where fork-type or ring-type terminals can be fastened. See Figure 1.5.

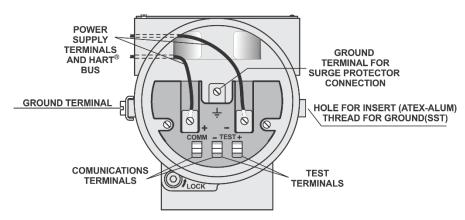


Figure 1.5 – Terminal Block

The **LD301** is protected against reverse polarity.

For convenience there are three ground terminals: one inside the cover and two external, located close to the conduit inlets.

Use of twisted pair (22 AWG or greater than) cables is recommended. For sites with high electromagnetic levels (EMI above 10 V/m) shield conductors are recommended. Ground the shield only at one end.

Avoid routing signal wiring near to power cables or switching equipment.

The Figure 1.6 shows the correct conduit installation, to avoid penetration of water or other substance, which may cause equipment malfunction.

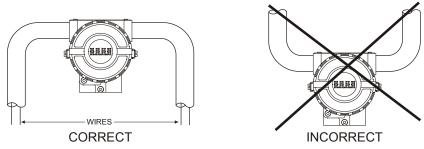


Figure 1.6 - Conduit Installation

Loop Connections

Figures 1.7 and 1.8 show **LD301**'s wiring diagrams to work as transmitter and controller, respectively.

Figure 1.9 shows the **LD301**'s wiring diagrams to work in the multidrop network. Note that a maximum of 15 transmitters can be connected on the same line, in parallel, if the HART protocol is version 5. For HART 7 version, up to 63 transmitters can be connected. Take care to the power supply as well, when many transmitters are connected on the same line. The current through the 250 Ohm resistor will be high causing a high voltage drop. Therefore make sure that the power supply voltage is sufficient.

The Hand-Held Terminal can be connected to the communication terminals of the transmitter or at any point of the signal line by using the alligator clips. It is also recommended to ground the shield of shielded cables at only one end. The ungrounded end must be carefully isolated. On multidrop connections, the circuit loop integrity must be assured, with special care to prevent short-circuit between the shield and the housing.

NOTE

For HART transmitters to operate in multidrop mode each transmitter must be configured with a different identity Device ID. In addition, if the transmitter identification mode on the loop is done through the Command 0 address, the HART address must also be different. If it is done through the Tag (Command 11) the tags must be similar.

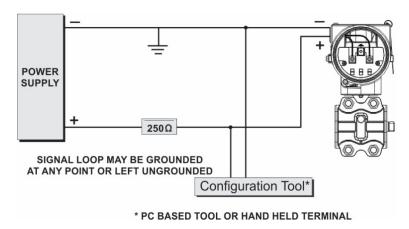


Figure 1.7 - Wiring Diagram for the LD301 Working as a Transmitter

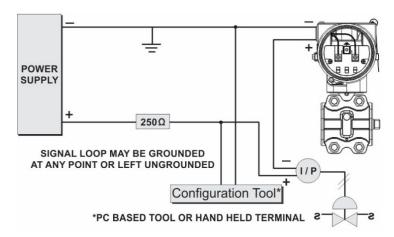


Figure 1.8 - Wiring Diagram for the LD301 Working as a Controller

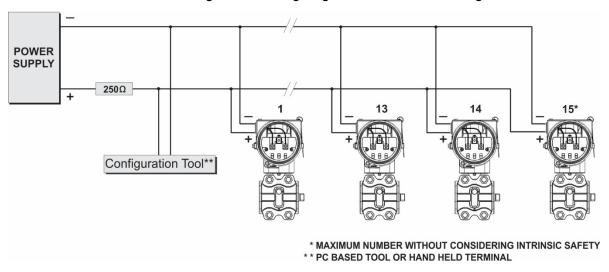


Figure 1.9 - Wiring Diagram for the LD301 in Multidrop Configuration for HART protocol version 5

NOTE

Make sure that the transmitter is operating within the operating area as shown on the load curve (Figure 1.10). Communication requires a minimum load of 250 Ohm and voltage equal to 17 Vdc.

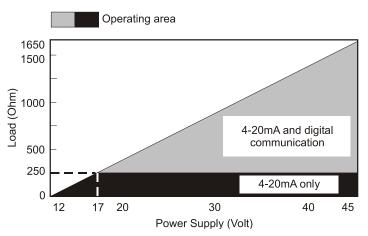


Figure 1.10 - Load Limitation

Installation in Hazardous Areas

Consult the Appendix A for Hazardous Location Approvals.

OPERATION

Functional Description - Sensor

The **LD301** Series Intelligent Pressure Transmitters use capacitive sensors (capacitive cells) as pressure sensing elements, as shown in Figure 2.1.

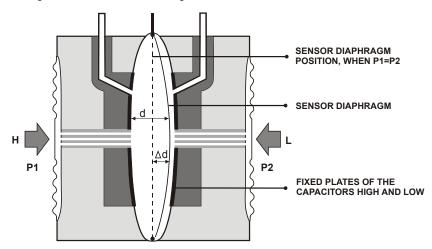


Figure 2.1 – Capacitive Cell

Where,

P₁ and P₂ are the pressures in chambers H and L.

CH = capacitance between the fixed plate on P_1 side and the sensing diaphragm.

CL = capacitance between the fixed plate on the P_2 side and the sensing diaphragm.

d = distance between **CH** and **CL** fixed plates.

 Δd = sensing diaphragm's deflection due to the differential pressure $\Delta P = P_1 - P_2$.

Knowing that the capacitance of a capacitor with flat, parallel plates may be expressed as a function of plate area (A) and distance (d) between the plates as:

$$C = \frac{\in A}{d}$$

Where,

∈= dielectric constant of the medium between the capacitor's plates.

Should **CH** and **CL** be considered as capacitances of flat and parallel plates with identical areas, then:

$$CH = \frac{\in A}{(d/2) + \Delta d}$$
 and $CL = \frac{\in A}{(d/2) - \Delta d}$

However, should the differential pressure (ΔP) apply to the capacitive cell not deflect the sensing diaphragm beyond d/4, it is possible to assume ΔP as proportional to Δd , that is:

 ΔP is proportional Δd .

By developing the expression (CL - CH)/(CL + CH), it follows that:

$$\Delta P = \frac{CL - CH}{CL + CH} = \frac{2\Delta d}{d}$$

As the distance (d) between the fixed plates CH and CL is constant, it is possible to conclude that the expression (CL - CH)/(CL + CH) is proportional to Δd and, therefore, to the differential pressure to be measured.

Thus it is possible to conclude that the capacitive cell is a pressure sensor formed by two capacitors whose capacitances vary according to the applied differential pressure.

Functional Description - Hardware

Refer to the block diagram Figure 2.2. The function of each block is described below.

SENSOR MAIN BOARD PRESSURE SENSOR LOCAL ADJUSTMENTS ZERO / SPAN HART MODEM **ELECTRONIC** PROCESSING UNIT IN/OUT CONVERTER RANGES D/A CONVERTER SPECIAL FUNCTIONS HART PID DIGITAL REA 4-20 mA MATH **OUTPUT CONTROL** COPROCESSOR OUTPUT \dot{P}_{L} SERIAL COMMUNICATION HART PROTOCOL DISPLAY CONTROLLER TEMPERATURE CONVERTER ELECTRONIC CONVERTER

Figure 2.2 - LD301 Block Diagram Hardware

Oscillator

This oscillator generates a frequency as a function of sensor capacitance.

Signal Isolator

The Control signals from the CPU are transferred through optical couplers, and the signal from the oscillator is transferred through a transformer.

DIGITAL

Central Processing Unit (CPU) and PROM

The CPU is the intelligent portion of the transmitter, being responsible for the management and operation of all other blocks, linearization and communication.

The program is stored in an external PROM. For temporary storage of data the CPU has an internal RAM. The data in the RAM is lost, if the power is switched off, although the CPU also has an internal nonvolatile EEPROM where data that must be retained is stored. Examples of such data are: calibration, configuration and identification data.

EEPROM

Another EEPROM is located within the sensor assembly. It contains data pertaining to the sensor's characteristics at different pressures and temperatures. This characterization is done for each sensor at the factory.

D/A Converter

It converts the digital data from the CPU to an analog signal with 16-bits resolution.

Output

It controls the current in the line that powers the transmitters.

It acts as a variable resistive load whose value depends on the voltage from the D/A converter.

Modem

This system provides the data exchanged between the Master-Slave digital communications. The transmitter demodulates information from the current line, and after treating it adequately, modulates over the line the answer to be sent. A "1" is represented by 1200 Hz and "0" by 2200 Hz. The frequency signal is symmetrical and does not affect the DC-level of the 4-20 mA signal.

Power Supply

Power shall be supplied to the transmitter circuit using the signal line (2-wire system). The transmitter quiescent consumption is 3.6 mA; during operation, consumption may be as high as 21 mA,

depending on the measurement and sensor status.

The **LD301** in the transmitter mode shows failure indication at 3.6 mA if configured for low signal failure; at 21 mA, if configured for high signal failure; 3.8 mA in the case of low saturation; 20.5 mA in the case of high saturation and measurements proportional to the applied pressure in the range between 3.8 mA and 20.5 mA. 4 mA corresponds to 0% of the working range and 20 mA to 100 % of the working range.

Power Supply Isolation

The sensor power supply is isolated from the main circuit by this module.

Display Controller

It receives the data from the CPU and actives the LCD segments. It also activates the backplane and the control signals for each segment.

Local Adjustment

Two switches on the main board are activated by inserting the magnetic tool.

Functional Description - Software

Refer to the block diagram Figure 2.3. The function of each block is described below.

Digital Filter

The digital filter is a low pass filter with an adjustable time constant. It is used to smooth noisy signals. The Damping value is the time required for the output reaching 63.2% for a step input of 100%. This value (in seconds) may be freely configured by the user.

Factory Characterization

The actual pressure obtained from the sensor's capacitance and temperature readings, can be calculated by using the factory characterization data stored in the sensor EEPROM.

User Linearization

The characterization TRIM points P1 - P5 can be used to complement the transmitter original characterization.

Pressure Trim

It corrects the measured pressure due to possible deviation caused by overpressure, over temperature or mounting position. The correction can be made for both zero offset and span offset.

Ranging

It is used to set the pressure values corresponding to the 4-20 mA output. In transmitter mode the LOWER-VALUE is the point corresponding to 4 mA, and the UPPER-VALUE is the point corresponding to 20 mA. In PID mode the LOWER-VALUE corresponds to MV = 0% and the UPPER-VALUE corresponds t

Function

Depending on the application, the transmitter output or controller PV may have the following characteristics according to the applied pressure: *Linear* (for pressure, differential pressure and level measurement); *Square-root* (for flow measurement with differential pressure producers) and *Square-root* of the *Third* and *Fifth* power (for flow measurements in open channels). The function is selected with FUNCTION. In addition, a 16-point table is available so that the percentage value can be linearized before or after the application of the above mentioned function.

Points Table

This block relates the output (4-20 mA or Process Variable) to the input (applied pressure) according to a table from 2 to 16 points. The output is calculated by the interpolation of these points. The points are given in the function "TABLE POINTS" in percent of the range (X_i) and in percent of the output (Y_i) . It may be used to convert, e.g., a level measurement to volume or mass. In flow measurement it can be used to correct varying Reynolds numbers.

Setpoint

Is the desired value in the process variable when the controller is activated. The operator in the \CONTR\INDIC option adjusts it.

PID

First, the error is calculated: PV-SP (DIRECT ACTION) or SP-PV (REVERSE ACTION), then the MV (manipulated value) is calculated, according to the algorithm of the PID. The PID output signal may follow a user-determined curve, in up to 16 configurable points. If the table is enabled, there will be a display indication with the F(X) character

Auto/Manual

The Auto/Manual mode is configured in CONTR/INDIC. With the PID in Manual, the MV can be adjusted by the user in the LOW LIMIT to HIGH LIMIT range in the CONTR/LIM-SEG option. The POWER-ON option is used here to set in which mode (AUTO or MANUAL) the controller will return after a power failure.

Limits

This block makes sure that the MV does not go beyond its minimum and maximum limits as established by the HIGH-LIMIT and LOW-LIMIT.

Output

It calculates the current proportional to the process variable or manipulated variable to be transmitted on the 4-20 mA output depending on the configuration in OP-MODE. This block also contains the constant current function configured in OUTPUT. The output is physically limited to 3.6 to 21 mA. The current output complies with NAMUR NE-43.

Current Trim

The 4 mA TRIM and 20 mA TRIM adjustment is used to make the transmitter current comply with a current standard, should a deviation arise.

User Unit

It converts 0 and 100% of the process variable to the desired engineering unit reading available for display and communication. It is used, e.g., to get a volume or flow indication from a level or differential pressure measurement, respectively. A unit for the variable can also be selected.

Totalization

Used for flow application to totalize the accumulated flow since the last reset, getting the volume or mass transferred. In the lack of power, the totalized value is saved and continues totalizing after its re-establishment. Only the residual value of the totalization is discarded.

Display

The two indications configured in the DISPLAY alternates between the primary and secondary variable as configured by the user. Extensive units with more than 5 letters are rotated.

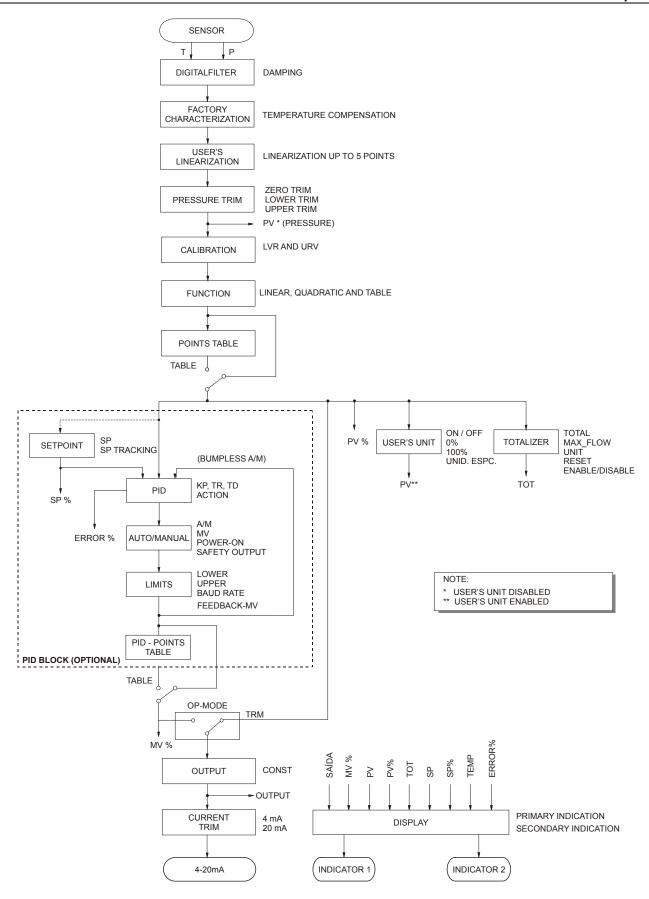


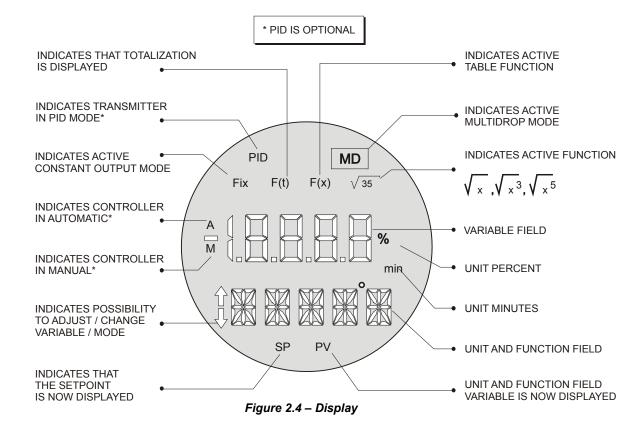
Figure 2.3 – LD301 – Software Block Diagram

The Display

The local indicator is able to display one or two variables, which are user-selected. When two variables are chosen, the display will alternate between both with an interval of 3 seconds.

The liquid crystal display includes a field with 4 $\frac{1}{2}$ numeric digits, a field with 5 alphanumeric digits and an information field, as shown on Figure 2.4.

When the totalization is displayed, the most significant part appears in the numeric field (upper) and the least significant part in the alphanumeric field (lower). See Total Value in Section 3.



Monitoring

During normal operation, the **LD301** is in the monitoring mode. In this mode, the indication alternates between the primary and the secondary variable as configured by the user. See Figure. 2.5. The display indicates engineering units, values and parameters simultaneously with most status indicators.

The monitoring mode is interrupted when the user does complete local adjustment.

The LCD may also display errors and other messages (See table 2.1).



Figure 2.5 – Typical Monitoring Mode Display Showing PV, in this case 25.00 mmH₂0

INDICA	TOR	DESCRIPTION		
Numeric	Alphanumeric	DESCRIPTION		
Version and protocol address	LD301	The LD301 is initialized after powering.		
	CHAR	The LD301 is on characterization mode (see Section 3 – TRIM)		
Variable Value	SAT / Unit	Output current saturated on 3.8 or 20.5 mA. (see section 5 – Maintenance).		
CH / CL alternating with current value.	SFAIL / Unit	Failure on one sensor side or on both.		
FAIL and Init		Transmitter failed on initialization (sensor memory failure or sensor is disconnected).		

Table 2.1 – Messages Displayed

CONFIGURATION

The **LD301** Intelligent Pressure Transmitter is a digital instrument with the most up-to-date features a measurement device can possibly have. Its digital communication protocol (HART®) enables the instrument to be connected to a computer to be configured in a very simple and complete way. Such computers connected to the transmitters are called HOST computers. They can either be Primary or Secondary Masters. Therefore, even the HART® being a master-slave protocol, it is possible to work with up to two masters in a bus. The Primary HOST plays the supervisory role, and the Secondary HOST plays the configuration tool role.

The transmitters may be connected in a point-to-point or multidrop type network. In a point-to-point connection, the equipment must be in its "0" address so that the output current may be modulated in 4 to 20 mA, as per the measurement. In a multidrop network, if the devices are recognized by their addresses, the transmitters shall be configured with a network address between "1" and "15". In this case, the transmitter output current is kept constant, with a consumption of 4 mA each. If the acknowledgement mechanism is via Tag, the transmitter addresses may be "0" while their output current is still being controlled, even in a multidrop configuration.

In the case of the **LD301**, which can be configured both as Transmitter and as a Controller; the HART® addressing is used as follows:

TRANSMITTER MODE - The "0" address causes the **LD301** to control its output current and addresses "1" through "15" place the **LD301** in the multidrop mode with current control, for HART protocol version 5. If it is HART protocol version 7, the addresses range from "1" to "63".

CONTROLLER MODE - The **LD301** always controls the output current, in accordance with the value calculated for the Controlled Variable, regardless of its network address.

The **LD301** Intelligent Pressure Transmitter includes a very encompassing set of HART Command functions that make it possible to access the functionality of what has been implemented. Such commands comply with the HART® protocol specifications, and are grouped as Overall Commands, Common Practice Controls Commands and Specific Commands. A detailed description of such commands may be found in the manual entitled HART® Command Specification - **LD301** Intelligent Pressure Transmitter.

Smar has developed the **DEVCOMDROID** (Android DDL Interpreter) software, used with HART interfaces, such as the **HI331** (Bluetooth Interface), in addition to **AssetView** (based on DTM) to configure the HART® equipment.

However, the old **PALM** with **HPC301** or **CONF401**, which are obsolete, remains operable even with the latest updates in HART transmitters.

They provide easy configuration and monitoring of field devices, capability to analyze data and to modify the performance of these devices. The operation characteristics and use of each one of the configuration tools are stated on their respective manuals.

It is also compatible to use configurators that support DDL (Device Description Language) or DTM (Device Type Manager).

See the following figure for an example of the **DEVCOMDROID** configurator interface.

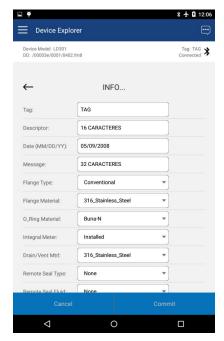


Figure 3.1 – DEVCOMDROID configurator

Configuration Features

By means of the HART® configuration tool, the **LD301** firmware allows the following configuration features to be accessed:

- ✓ Transmitter Identification and Manufacturing Data;
- ✓ Primary Variable Trim Pressure;
- ✓ Primary Variable Trim Current;
- ✓ Transmitter Adjustment to the Working Range;
- ✓ Engineering Unit Selection;
- ✓ Transference Function for Flow Measurement;
- ✓ Linearization Table;
- ✓ Totalizer Configuration;
- ✓ PID Controller Configuration and MV% Characterization Table;
- ✓ Device Configuration;
- ✓ Equipment Maintenance.

The operations, which take place between the configuration tool and the transmitter do not interrupt the Pressure measurement, and do not disturb the output signal. The configuration tool can be connected on the same pair of wires as the 4-20 mA signals, up to 2 km away from the transmitter.

Programming Tree

The programming tree is a tree-shaped structure with all available software resources, as shown in Figure 3.2.

ON_LINE_TRM_SINGLE: is used when the programmer is connected in parallel with a single transmitter and this transmitter has address 0 (Zero).

ON_LINE_MULTIDROP: is used when the programmer is connected in parallel with several transmitters and these transmitters are configured with different addresses (See Multidrop).

ATTENTION

All transmitters are factory configured without passwords. To avoid bad operation at some critical levels of the programming tree, it is recommended to configure all passwords before the operation. See the "PASSWORD" option in the maintenance section.

The following figure shows the menu tree used for configuration with DDL.

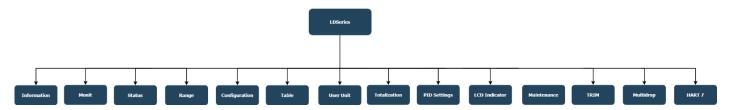


Figure 3.2 - Menu tree used for configuration with DDL

INFORMATION - The main information about the transmitter can be accessed here. These include Tag, Description, Message, and Unique ID.

MONIT - This is the option that allows the user to monitor four of the transmitter's dynamic variables and the current output.

STATUS – Allows the user to check transmitter status information, for example, whether the primary variable is out of the equipment's operational limits, whether maintenance is required, whether there is an electronic failure, etc.

RANGE – Allows the configuration of lower and upper range values, minimum span, unit, and damping.

CONFIGURATION - This option allows the user to configure burnout, write protection, transfer function and output.

TABLE – This option allows the user to define points in a table so that the output follows a curve created according to the values entered.

USER UNIT – This option allows the user to configure engineering units.

TOTALIZATION - This option allows totaling the accumulated flow since the last reset, thus obtaining the volume or mass transferred.

PID SETTINGS- It is the option where the controller function can be turned on and off and all control parameters can be adjusted and monitored.

LCD INDICATOR - The LD301 accepts up to two display configurations that are shown alternately, every 3 seconds. The parameters that can be selected for viewing are: OUT, OUT%, PRES, PV%, PV, TEMP, TOT, SP, SP% and ER%. Some are only available in PID mode.

MAINTENANCE - This option allows the user to test the current loop, restart the equipment, view the operations counter, configure write protection, enable or disable local adjustment, etc.

TRIM - This is the option used to adjust the transmitter indication with a standard.

MULTIDROP - This option allows the user to view the current address of the equipment and designate a new one, if necessary.

HART 7 – In this tab, in Dynamic Variable, the variables selected for PV, SV, TV, and QV are shown, with their current values and units. PV will always be the pressure. The Change Dynamic Variable option allows the user to change what the SV, TV and QV will be, if desired. In Device Variables there are eight selectable boxes for the user to choose the variables they want to monitor. Just choose and click on Monitor Device Variables. The Lock/Unlock Device option is used to lock a device temporarily or permanently, preventing any changes from being made from a local panel or another master.

Information - Manufacturing Data and Identification

The following information about the **LD301** manufacturing and identification data is available:

- ✓ TAG 8 characters alphanumeric field for transmitter identification
- ✓ DESCRIPTOR 16-character alphanumeric field for additional transmitter identification. May be used to identify service or location.

- MESSAGE 32-character alphanumeric field for any other information, such as the name of the person who made the last calibration, some special care to be taken, or if a ladder is needed for accessing.
- ✓ **DATE** The date may be used to identify a relevant date as the last calibration, the next calibration or the installation. The date is presented in the form of bytes where DD = [1,..31], MM = [1..12], AA = [1900..2155].
- ✓ LONG TAG Field with 32 alphanumeric characters to identify the transmitter (HART7);
- ✓ ORDERING CODE Field that shows the equipment ordering code.
- ✓ UNIQUE ID Shows the unique identifier of the equipment. Read-only information, therefore it cannot be modified.
- ✓ DEVICE INFORMATION Manufacturer, type, ID, revision of HART commands, hardware revision and type of communication signal.
- ✓ SOFTWARE VERSION Version of the equipment's firmware.
- ✓ SECOND CPU VERSION Secondary CPU information.
- ✓ **DATASHEET INFORMATION** Installed, None, Undefined;
- SENSOR INFORMATION Shows type, filling fluid and sensor isolation diaphragm.
- ✓ SENSOR RANGE Shows the sensor range in the engineering unit chosen by the user. See the Unit Configuration section for more information;
- ✓ REMOTE SEAL INFORMATION Shows the type of remote seal, filling fluid, diaphragm, and
 the number of remote seals;
- ✓ FLANGE INFORMATION Shows the type and material of the flange, material of the rings and material of the purge valve;

Monit - Monitoring

This section shows which variables are selected for PV, SV, TV, and QV, with their current values and units. PV will always be the pressure.

Specific Monitor is the functionality that allows simultaneous monitoring of up to four transmitter variables. See the following table to see which variables can be monitored.

VARIABLE	DESCRIPTION				
OUT	Output in milliamperes.				
PV%	Process Variable in percentage.				
PV	Process Variable in engineering units.				
OUT% (*)	Output in percentage.				
PRES	Pressure in pressure unit.				
TEMP	Ambient temperature.				
TOT	Total accumulated by the totalizer.				
SP% ^(*)	Setpoint in percentage.				
SP (*)	Setpoint in engineering units.				
ERR% (*)	Error in percentage (PV% - SP%).				

Table 3.1 - Monitored Variables

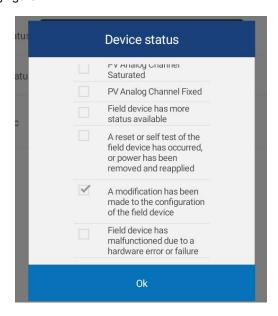
NOTE

Items marked with asterisks in table 3.1 can only be selected in PID mode. The TOT item can only be selected when it is enabled.

Status

Allows the user to check transmitter status information, for example, whether the primary variable is out of the equipment's operational limits, whether maintenance is required, whether there is an electronic failure, etc.

In **Device Status**, **Extended Device Status** (Ext dev status) and **Device Diagnostic Status 0** available statuses are shown. The options that appear marked are those currently active. See an example in the following figure:



Range - Calibration

In this option, the lower and upper values of the operating range are configured, selecting the unit that will represent the process variable, the transmitter damping and the calibration with reference.

The **PV DAMP** option enables electronic damping adjustment. The input filter, also referred to as Damping, is a first-order digital filter, implemented by the firmware, where the time constant can be adjusted to any value from zero to 128 seconds in addition to the total intrinsic sensor response time (100 ms), via digital communication.

PV Unit modifies the pressure unit, used in the variables **PRES** (primary variable related to measured pressure), **PV** (process variable in engineering units) and **SP** (Setpoint in engineering units).

If User Unit is enabled, the PV and SP units are controlled by the selected User Unit.

Transmitter Adjustment to the Working Range

This function directly affects the transmitter 4-20 mA output. It is used to define the transmitter working range; in this document it is referred to as the transmitter calibration. The **LD301** transmitter includes two calibration features:

- ✓ CALIBRATION WITH REFERENCE: this is used to adjust the transmitter working range, using a pressure standard as reference;
- ✓ CALIBRATION WITHOUT REFERENCE: this is used to adjust the transmitter working range, simply by having user-informed limit values.

Both calibration methods define the Working Range Upper and Lower values, in reference to some applied pressure or simply informed by entered values. CALIBRATION WITH REFERENCE differs from the Pressure Trim, since CALIBRATION WITH REFERENCE establishes a relationship between

the applied pressure and the 4 to 20 mA signal, and the Pressure Trim is used to correct the measurement.

In the transmitter mode, the Lower Value always corresponds to 4 mA and the Upper Value to 20 mA. In the controller mode, the Lower Value corresponds to PV=0% and the Upper Value to PV=100%.

The calibration process calculates the LOWER and the UPPER values in a completely independent way. The adjustment of values does not affect one another. The following rules shall, however, be observed:

- ✓ The Lower and Upper values shall be within the range limited by the Minimum and Maximum Ranges supported by the transmitter. As a tolerance, values exceeding such limits by up to 25% are accepted, although with some accuracy degradation.
- ✓ The Working Range Span, determined by the difference between the Upper and Lower Values. Values up to 0.90 of the minimum span are acceptable with slight accuracy degradation.

NOTE

Should the transmitter operate with a very small span, it will be extremely sensitive to pressure variations. Keep in mind that the gain will be very high and that any pressure change, no matter how small, will be amplified.

If it is necessary to perform a reverse calibration, that is, to work with an UPPER VALUE smaller than the LOWER VALUE, proceed as follows:

✓ Place the Lower Limit in a value as far as possible from the present Upper Value and from the new adjusted Upper value, observing the minimum span allowed. Adjust the Upper Value at the desired point and then, adjust the Lower Value.

This type of calibration is intended to prevent the calibration from reaching, at any moment, values not compatible with the range. For example: lower value equals to upper value or separated by a value smaller than the minimum span.

This calibration procedure is also recommended for zero suppression or elevation in those cases where the instrument installation results in a residual measurement in relation to a certain reference. This is the specific case of the wetted tap.

NOTE

In most applications with wetted taps, indication is usually expressed as a percentage. Should reading in engineering units with zero suppression be required, it is recommended to use the User Unit feature for such conversion.

Configuration

This function affects the 4-20 mA output of the transmitter and the display indication. In this option the user can change the burnout (Lower and Upper), check the status of write protection and the transfer function.

In **Alarm Selection** the user configures the Burnout characterized when the sensor reading is out of range or the sensor is open, that is, it is the configuration to say in which state the primary variable must go in case of equipment failure. In this case, the transmitter can be adjusted to output at the maximum limit of 21 mA by setting it high or the minimum limit at 3.6 mA by setting it low.

It only works if the PID is disabled and the device is not in multidrop, as in this case the current is fixed at 4mA. If the LD301 is to work as a controller, PID enabled, the Power-On Output safety output must be configured.

Transfer Function for Flow Measurement

The transfer function can be used to convert the measured pressure to flow or volume. The following functions are available:

NOTE

- Use the lowest required damping to prevent measurement delays;
- If the square root extraction for flow measurement is carried out externally by other loop element, do not enable this function on the transmitter

SQRT - Square Root. Considering the pressure input **X** varying between 0 and 100%, the output will be $10\sqrt{x}$. This function is used in flow measurement with, e.g., orifice plate or Venturi tube etc.

The Square Root has an adjustable cutoff point. Below this point the output is linear, if the cutoff mode is bumpless with the differential pressure as indicated by the Figure 3.5. If the cutoff mode is hard the output will be 0% below the cutoff point. The default value for Cutoff is 6% of ranged pressure input. The maximum value for cutoff is 100%. Cutoff is used to limit the high gain, which results from square root extraction on small values. This gives a more stable reading at low flows.

In order to find the square root, the **LD301** configurable parameters are: cutoff point defined at a certain pressure expressed as % and the cutoff mode, hard or bumpless.

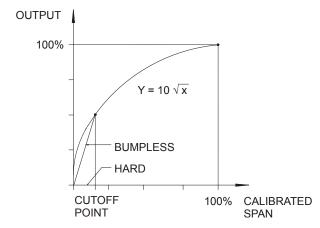


Figure 3.3 - Square Root curve with Cutoff point

NOTE

In bumpless cutoff mode the gain below the cutoff point is given by the equation:

$$G = \frac{10}{\sqrt{cutoff}}$$

For example, at 1% the gain is 10, i.e., a 0.1% error in differential pressure, gives a 1% error in Flow reading. The lower the cutoff, the higher is the gain.

The measurement of the bidirectional flow is useful when it is needed to measure the flow in the pipe in both directions. For example, in tank there are several pipes where the direction of the fluid may vary. In this case, **LD301** has the bidirectional flow measurement function. This function treats the flow, no matter what its direction is, as if it were positive. Thus, it is possible to extract the square root and measure the bidirectional flow.

- **SQRT**3** Square Root of the Third Power; The output will be $0.1\sqrt{x^3}$. This function is used in open channel Flow measurement with weirs or flumes.
- ✓ **SQRT**5** Square Root of the Fifth Power. The output will be $0.001\sqrt{x^5}$. This function is used in open channel Flow measurement with V-notch weirs.

It is possible to combine the previous functions with a table. The flow can be corrected according to the table to compensate, for example, the variation of Reynolds number at the flow measurement.

- ✓ TABLE The output is a curve formed by 16 points. These points may be edited directly on the XY Table of the LD301. For example, it may be used as a camber table for tanks in applications where the tank volume is not linear in relation to the measured pressure;
- ✓ **SQRT & TABLE** Square root and Table. Same application as square roots, but also allows additional compensation of, e.g., varying Reynolds number.

- ✓ SQRT**3 & TABLE Square Root of the Third Power and table;
- ✓ SQRT**5 & TABLE Square Root of the Fifth Power and table.
- ✓ TABLE & SQRT This function provides bidirectional flow measurement (piping flow measurement in both ways). This function is available for version 6.05 or above firmware.

Example:

There is a flow on the positive direction (high pressure on the H side) with a 0 to 400 mbar ΔP and a flow on the negative direction (high pressure on the L side) from 0 to 100 mbar. For these data make the range lower value equal to -100 mbar, and higher value +400 mbar. Always including the 0 per cent pressure value, namely 20 per cent. Insert the data on the transmitter.

X	Υ
0 % (-100 mbar)	100 %
20 % (0 mbar)	0 %
100 % (400 mbar)	100 %

NOTE

To configure a symmetrical bidirectional flow, double the number of calibration points to get a better performance.

Next, configure the cutting point. Refer to the previous Root item.

Table Points

If the option **TABLE** is selected, the output will follow a curve given in the option TABLE POINTS. If the user wants to have the 4-20 mA proportional to the fluid volume or mass inside a tank, the user must transform the pressure measurement "X" into volume (or mass) "Y" using the tank strapping table, as the example shown in Table 3.3.

POINTS	LEVEL (PRESSURE)	Х	VOLUME	Y
1	-	-10 %	1	-0.62 %
2	250 mmH ₂ O	0 %	0 m ³	0 %
3	450 mmH ₂ O	10 %	0.98 m ³	5.22 %
4	750 mmH ₂ O	25 %	2.90 m ³	15.38 %
5	957.2	35.36 %	4.71 m ³	25 %
6	1050	40 %	7.04 m ³	37.36 %
7	1150	45 %	8.23 m ³	43.65 %
8	1250	50 %	9.42 m ³	50 %
:	:	:	:	:
15	2250	100 %	18.85 m ³	100 %
16	-	110 %	-	106 %

Table 3.2 - Tank Strapping Table

As shown on the previous example, the points may be freely distributed for any desired value of X. To achieve a better linearization, the distribution should be concentrated in the less linear parts of the measurement.

The LD301 includes an internal feature to enable and disable the Linearization Table.

User Unit - Engineering Unit Selection

Transmitter **LD301** includes a selection of engineering units to be used in measurement indication.

For pressure measurements, the **LD301** includes an option list with the most common units. The internal reference unit is inH₂O @ 20 °C; should the desired unit be other than this one, it will be

automatically converted using conversion factors included in Table 3.3.

CONVERSION FACTOR	ENGINEERING UNITS	RECOMMEND RANGE
1,00000	inH₂O @20 °C	1, 2, 3 and 4
0,0734241	inHg @ 0 °C	all
0,0833333	ftH₂O @ 20 °C	all
25,4000	mmH₂O @ 20 °C	1 and 2
1,86497	mmHg @ 0 °C	1, 2, 3 and 4
0,0360625	psi	2, 3, 4, 5 and 6
0,00248642	bar	3, 4, 5 and 6
2,48642	mbar	1, 2, 3 and 4
2,53545	gf/cm ²	1, 2, 3 and 4
0,00253545	kg/cm ²	3, 4, 5 and 6
248,642	Pa	1
0,248642	kPa	1, 2, 3 and 4
1,86947	Torr @ 0 °C	1, 2, 3 and 4
0,00245391	atm	3, 4, 5 and 6
0,000248642	MPa	4, 5 and 6
0,998205	inH₂O @ 4 °C	1, 2, 3 and 4
25,3545	mmH₂O @ 4 °C	1 and 2
0,0254	mH₂O @ 20 °C	1, 2, 3 and 4
0,0253545	mH₂O @ 4 °C	1, 2, 3 and 4

Table 3.3- Available Pressure Units

In applications where the **LD301** will be used to measure variables other than pressure or in the cases where a relative adjustment has been selected, the new unit may be displayed by means of the **User Unit** feature. This is the case of measurements such as level, volume, and flow rate or mass flow obtained indirectly from pressure measurements.

The User Unit is calculated adopting the working range limits as a reference, which is, defining a value corresponding to 0% and another corresponding to 100% of the measurement:

- ✓ 0% Desired reading when the pressure is equal to the Lower Value (PV% = 0%, or transmitter mode output equal to 4 mA);
- ✓ **100%** Desired reading when the pressure is equal to the Upper Value (PV% = 100%, or transmitter mode output equal to 20 mA).

The user unit may be selected from a list of options included in the **LD301**. Table 3.4 makes it possible to associate the new measurement to the new unit so that all supervisory systems fitted the HART® protocol can access the special unit included in this table. The user will be responsible for the consistency of such information. The **LD301** does not verify if the values corresponding to the 0% and 100% inserted by the user are compatible with the selected unit.

VARIABLE	UNITS	
Pressure	inH ₂ O, inHg, ftH ₂ O, mmH ₂ O, mmHg, psi, bar, mbar, gf/cm ² , kgf/cm ² , Pascal, Torriceli, atm, Mpa, inH ₂ O @ 4 °C, mmH ₂ O @ 4 °C, mH ₂ O, mH ₂ O @ 4 °C.	
Volumetric Flow	ft³/min, gal/min,Gal/min, m³/h, gal/s, l/s, Ml/d, ft³/d, m³/s, m³/d, Ga/h, Ga/d, ft³/h, m³/min, bbl/s, bbl/min, bbl/d, gal/s, l/h, gal/d.	
Velocity	ft/s, m/s, m/h.	
Volume	gal, I, Gal, m³, bbl, bush, Yd³, ft³, In³, hl.	
Level	ft, m, in, cm, mm.	
Mass	g, kg, Ton, lb, Sh ton, Lton.	
Mass Flow	g/s, g/min, g/h, kg/s, kg/min, kg/h, kg/d, Ton/min, Ton/h, Ton/d, lb/s, lb/min, lb/h, lb/d	
Density	SGU, g/m³, kg/m³, g/ml, kg/l, Twad, Brix, Baum L, API, % Solw, % Solv, Ball.	
Others	CSo, cPo, mA, %.	
Special	5 characters. (See HART® Special Units in section 5).	

Table 3.4 - Available User Units

If a special unit other than those presented on previous be required, the **LD301** allows the user to create a new unit by entering up to 5 alphanumeric digits of the name with 253 code. The **LD301** includes an internal feature to enable and disable the User Unit.

The measure resulting from the user unit is called PV, different from the primary measure which is pressure (pressure subjected to a transfer function). Thus, if the user unit is not enabled, the PV measurement will display its value in percentage. To discern between the display of a pressure from a PV, the display will activate the PV icon when the PV is being displayed.

Example: transmitter **LD301** is connected to a horizontal cylindrical tank (6 meters long and 2 meters in diameter), linearized for volume measurement using camber table data in its linearization table. Measurement is done at the high-pressure tap and the transmitter is located 250 mm below the support base. The fluid to be measured is water at 20 °C. Tank volume is: $[(\pi.d2)/4].I = [(\pi.22)/4]\pi.6 = 18.85 \text{ m}3$.

The wet tap shall be subtracted from the measured pressure in order to obtain the tank level. Therefore, a calibration without reference shall be carried out, as follows:

In Calibration:

Lower = 250 mm H_2O Upper = 2250 mm H_2O Pressure unit = mm H_2O

In User Unit:

User Unit 0% = 0 User Unit 100% = 18.85 m³ User Unit = m³

When activating the User's Unit, LD301 it will start to indicate the new measurement.

Totalization Configuration

When the **LD301** works in flow applications it is often desirable to totalize the flow to know the accumulated volume or mass that has flown through the pipe/channel.

The totalizer integrates the PV% along time, working with a time scheduling based on seconds, as per the following formula:

$$TOT = \int \frac{MAXIMUM\ FLOWRATE}{TOTALIZATION\ INCREMENT}\ PV\%\ dt$$

The method uses such totalization and, through three parameters (MAXIMUM FLOWRATE, TOTAL INCREMENT and TOTAL UNIT), converts it to the user-defined totalizing unit:

- ✓ Max Flow (maximum flow rate) this is the maximum flow rate expressed in volume or mass units per second, corresponding to the measurement (PV%=100%). For example: m3/s, bbl/s, kg/s, lb/s;
- ✓ **Total Factor (totalization increment)** this is used to convert the flow rate base unit into a multiple unit of mass or volume. For example, a flow rate totalized in gallons/s may be converted to a volume in m3; a mass flow rate of g/s may be converted to kilos, etc.
- ✓ **Total Unit (totalization unit) -** this is the engineering unit associated to the totalized value. It may be a standard unit or a special unit with up to five characters.

WARNING

The totalizer shall be disabled so that any of these parameters can be configured.

The largest totalized value is 99.999.999 totalizing units. When the totalization is displayed, the most significant part is shown on the numeric field, and the less significant part is shown on the alphanumeric field. Figure 3.4 shows a typical display indication.

NOTE

F(t) indication is activated every time the totalized value is shown on the digital display.

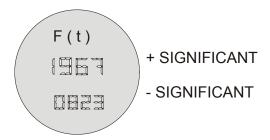


Figure 3.4 – Typical Monitoring Mode Display Showing the Total, in this case 19.6708.23

The following services are associated with the Totalizer:

- ✓ Reset Totalization Totalization is reinitialized from value "0";
- ✓ ON / OFF this allows the totalization function to be enabled or disabled.

WARNING

From Version V6.00 on, with the use of the new main board, the totalized value is persistent, i.e., there is no longer the risk of losing this information in case of power failure.

Example: A differential pressure of 0 - 20 inH₂O represents a flow of 0 - 6800 dm³/minute.

Set the Lower value = $0 \text{ inH}_2\text{O}$ and Upper value = $20 \text{ inH}_2\text{O}$. Select the engineering unit as inH $_2\text{O}$

To adjust the MAX._FLOW, the maximum flow must be converted to cubic decimeters per second: 6800 / 60 = 113.3 dm³ /s.

The selection of the totalization unit is done in function of the maximum flow and the minimum time allowable for the counter overrun, i.e., the totalization must be less than 99.999.999 in a reasonable observation time.

In the example, if TOTALIZATION INCREMENT = 1, the totalization increment is 1 dm³. The time required for the overrun with maximum flow rate (113.3 dm³/s) is 10 days, 5 hours, 10 minutes and 12.5 seconds.

On the other hand, in case a TOTALIZATION INCREMENT equal to 10 is used, the totalized unit will be deciliter (dal) and the totalizer will receive one increment at every 10 dm³. Considering the maximum flow rate (113.3 dm³/s), the totalizer will reach its maximum value and return to zero in 102 days, 3 hours, 42 minutes, and 5.243 seconds.

PID Controller Configuration

The **LD301** may be factory -configured to work as Transmitter only or as Transmitter / Controller. In case the **LD301** is configured as a Transmitter / Controller, the end user may change its operation mode at any time simply by configuring an internal status variable.

As a PID Controller, the **LD301** may run a PID type control algorithm, where its 4 to 20 mA will represent the status of the Manipulated variable (MV). In such a mode, output is 4 mA when the MV = 0% and 20 mA when MV= 100%.

The PID implementation algorithm is:

$$MV = Kp (e + 1/Tr \int e dt + Td dPV/dt)$$

Where:

e(t) = PV-SP (direct) SP-PV (reverse)

SP = Setpoint

PV = Process Variable (Pressure, Level, Flow, etc.)

Kp = Proportional Gain

Tr = Integration Time

Td = Derivative Time

MV = Manipulated Variable (output)

The three configuration groups below are pertinent to the PID controller:

✓ Safety Limits - this group enables the configuration of: Safety Output, Output Rate and Output Lower and Upper Limits.

The **Safety Out** defines the value of the output in the case of equipment failure.

Output Rate (**Out Chg/s**) is the maximum variation rate allowed for the output, expressed in %/s. The Lower (**Low limit**) and Upper (**High limit**) Limits define the output range.

✓ PID Information - this group enables the PID tuning to be performed. The following parameters may be adjusted: Kp, Tr and Td. It also allows the user to configure SP, PV and MV and read ERR%.

The **Kp** parameter is the proportional gain (not the proportional band) that controls the PID proportional action. It may be adjusted from 0 to 100.

The **Tr** parameter is the integral time that controls the PID integral action. It may be adjusted from 0 to 999 minutes per repetition.

The **Td** parameter is the derivative time controlling the PID derivative action. It may be adjusted from 0 to 999 seconds.

The **Power_On** option, when the PID is enabled, allows the user to adjust the control mode that the PID should return to when the equipment is turned on again, which may be due to a power lack, restart, etc.: Manual mode, Automatic mode or in the last mode before of the power lack.

NOTE

All these parameters accept zero as input. Such value simply nullifies the corresponding PID control actions.

✓ OPERATION MODES - this group enables the configuration of: Control Action, Setpoint Tracking and Auto or Manual mode.

In **Operation Mode**, it is defined whether the LD301 will work as a transmitter or controller.

The Output Action option enables the selection of the desired output action: direct or reverse. In direct action, a PV increase causes an output increase; in reverse action, a PV increase causes an output decrease.

The **SP Tracking is** option enables or disables the mode which allows the Setpoint value to follow the PV while in Manual Control. Thus, when control passes to Auto, the Setpoint value will be the last PV prior to the switching.

PID Type - The type of control algorithm determines whether the proportional, integral, and derivative contribution acts on the error or process variable.

✓ PID table – If the table option is selected, the MV output will follow a curve according to the values typed in the LD301's characterization table. The points can freely be configured as percentage values. For a better linearization, it is recommendable that the points are the closest possible, in the less linear regions of the curve. The LD301 has an internal variable to enable and disable the characterization table of the MV output of the PID.

LCD Indicator - Display Indication

The **LD301** digital display has three distinct fields: an information field with icons indicating the active configuration status, a 4 ½ digit numeric field for value indication and a 5 digits alphanumeric field for units and status information.

The **LD301** may work with up to two display configurations to be alternately displayed at 3 second intervals. Parameters that may be selected for visualization are **First Var=** and **Second Var=**. The available variables are OUT, MV(%), PRES, PV(%), PV, TEMP, *SP(%), *SP, *ER(%), TOT and None.

PARAMETER	DESCRIPTION	
OUT	Current in milliamperes.	
PV%	Process Variable in percentage.	
PV	Process Variable in engineering units.	
MV% ^(*)	Output in percentage.	
PRES	Pressure in pressure unit.	
TEMP	Ambient temperature.	
TOT	Total accumulated by the totalizer.	
SP% ^(*)	Setpoint in percentage.	
SP (*)	Setpoint in engineering units.	
ERR% (*)	Error in percentage (PV% - SP %).	
NONE	Used to cancel the second indication.	

Table 3.5 - Variables for Display Indication

NOTE
Items marked with an asterisk in table 3.5 can only be selected in the PID mode.

Equipment Maintenance

Here are grouped maintenance services related with the collection of information required for equipment maintenance. The following services are available: Order Code, Serial Number, Operation Counter, Loop current test, Local Adjustment and Backup.

✓ Hardware Write Protect - This feature is used to protect the transmitter configuration from changes via communication. All configuration data are writing-protected.

The **LD301** includes two write protection mechanisms: software and hardware locking. When the **LD301** writing software protection mechanism is enabled, it is possible, by means of specific commands, to enable or disable the write protection.

Local Adjust: Enables and disables write protection using a magnetic switch via local adjustment.

Local Adjust Mode: Defines whether local adjustment is simple or complete.

- ✓ Loop Test: The current output can be adjusted to any desired value between 3.6 and 21 mA without regard to the input value. There are also some fixed current values for loop testing. The available options are: 4 and 20 mA.
- ✓ **Format** Contains equipment order code, sensor and transmitter information. The Order Code is the one used for purchasing the equipment, in accordance with the User specification. There are 22 characters available in the **LD301** to define this code.

EXAMPLE:

#	OPTION	DESCRIPTION	
1	L		
2	D		
3	3	Differential pressure transmitter	
4	0	Differential pressure transmitter	
5	1		
6	D		
7	2	Range 2: -50 to 50 kPa	
8	1	SST 316L diaphragm – Silicon oil	
9	I	SST 316 Flanges, adapters and Drain/vent	
10	В	Nitrile O'ring	
11	U	Upper Drain/vent	
12	1	Local indicator	
13	0	Process connection 1/4NPT	

#	OPTION	DESCRIPTION		
14	0	Electrical connection 1/2NPT		
15	1	Local adjust Z S		
16	1	Carbon Steel bracket and accessories		
17;18	A0	Flange's Bolts and Nuts in Carbon steel		
19;20	C5	Materials conforming NACE standard		
21;22	D0	Flange thread: 7/16"UNF (Smar default)		
	G0	Output signal: 4-20mA		
	H0	Aluminum Housing Material		
	16	Identification Plate without certification		
	M0	Configuration Memory With PID		
	P0	Electronic Housing and covers with gray paint		
	S0	Manufacturing Standard: Smar		
	Y2	LCD1: pressure (engineering units)		
	J0	With Tag plate		
	Z0	Without special standard		
	E0	Electronic Housing Standard		
	BD	Initial scale		
	OP	Standard performance		
	X0	Without certification		
	R0	Standard flange position		

Table 3.6 - Differential Pressure Transmitter Ordering Code

Three serial numbers are stored on LD301:

Assembly - The final assembly number is used to identify the materials and electronic components that make up the field device.

Sensor Serial Number - The serial number of the sensor connected to the LD301 and cannot be changed. This number is read from the sensor every time a new sensor is inserted in the main board.

Device ID – It is the number used to identify each transmitter.

NOTE

The transmitter number must be changed whenever there is the main electronic board change to avoid communication problems.

✓ Operation Counter - Every time a change is done, there is an increment in the respective change counter for each monitored variable. The counter is cyclic, from 0 to 255. The monitored items are:

VARIABLE	DESCRIPTION
Lower Value/Upper Value	When any type of calibration is done.
Function	When any change in the transference function is done, e.g., linear,
1 direction	square root, constant, or table.
Trim_4mA	When the current trim is done at 4mA.
Trim_20mA	When the current trim is done at 20mA.
Trim_Zero/Lower	When pressure trim is done at Zero or Lower Pressure.
Trim Upper Pressure	When the trim is done at Upper Pressure.
Temperature Trim	When the Temperature Trim is done.
TRM/PID	When the operation mode is changed, i.e., from PID to TRM or vice-
TRIVI/FID	versa.
Characterization	When any change occurs at any point of the pressure characterization
Characterization	table in trim mode.
Auto Clamp	When there is a change in the enabling or disabling of this function
Write Protection	When there is a change in enabling or disabling the write protection
Write i rotection	mode
Multidrop	When the communication mode is changed, for example, multidrop or
manual op	single transmitter.
Password/Configuration	When any change occurs in the password or the level configuration.
Level	
Totalization	When any change occurs in unit, configuration or totalization reset.

Table 3.6 – Functions Monitored by the Operation Counter

✓ Backup

Read_Sensor - When the main board is changed, after assembling and powering it, the data saved in the sensor memory are automatically copied to the main board memory, allowing its operation.

Most of the parameters are transferred automatically, however, the calibration parameters remain intact on the main board, so as not to risk inadvertently changing the working range. If the replaced part is the sensor, there is a need to transfer the calibration from the main board to the sensor and vice versa if the main board was exchanged.

Write_on_Sensor - This option allows copying the data saved in the sensor memory to the main board memory. It also allows restoring to the main board the data stored in the sensor.

✓ Overload Parameters – This option informs the limits that have already been measured by the sensor. Maximum Applied and Minimum Applied report, respectively, the maximum and minimum pressures measured by the sensor in use.

Similarly, **Max Temperature** and **Min Temperature** inform, respectively, the maximum and minimum temperatures read by the sensor.

- ✓ Number of overpressures informs the number of times there was overpressure.
- ✓ Passwords This service allows the user to modify the operating passwords used by the LD301. Each password defines access to a priority level (1 to 3) and this configuration is stored in the LD301's EEPROM. The level_3 password is hierarchically superior to the level_2 password, which is superior to the level_1 password. Levels 1 and 2 are available for external access for configurators to create their own access structure.

Trim

Primary Variable Trim - Pressure

Pressure, defined as a Primary Variable, is determined from the sensor reading by means of a conversion method. Such a method uses parameters obtained during the manufacturing process. They depend on the electric and mechanical characteristics of the sensor, and on the temperature change to which the sensor is submitted. These parameters are recorded in the sensor's EEPROM memory. When the sensor is connected to the transmitter, such information will be available to the transmitter microprocessor, which sets a relationship between the sensor signal and the measured pressure.

Sometimes, the pressure shown on the transmitter display is different from the applied pressure. This may be due to several reasons, among which the following:

- ✓ The transmitter mounting position;
- ✓ The user pressure standard differs from the factory standard;
- ✓ Sensor original characteristics shifted by overpressure, over temperature or by other special conditions of use.

NOTE

Some users prefer to use this feature for zero elevation or suppression when the measurement refers to a certain point of the tank or tap (wet leg). Such practice, however, is not recommended when frequent laboratory calibrations are required, because the equipment adjustment refers to a relative measurement, and not to an absolute one, as per a specific pressure standard.

The Pressure Trim, as described on this document, is the method used to adjust the measurement both in relation to the applied pressure and the user's pressure standard. The most common discrepancy found in transmitters is usually due to Zero displacement. This may be corrected by means of the zero trim or the lower trim.

There are four types of pressure trim available:

✓ **Lower Trim**: Is used to trim the reading at the lower range. The user informs the transmitter the correct reading for the applied pressure via HART® configuration tool.

NOTE

Check on section 1, the note on the influence of the mounting position on the indicator.

For better accuracy, the trim adjustment should be made in the lower and upper values of the operation range values.

✓ **Upper Trim:** Is used to trim the reading at the upper range. The user informs the transmitter the correct reading for the applied pressure via HART® configuration tool.

WARNING

The upper pressure trim shall always be applied after the zero trim.

✓ **Zero Trim:** is similar to the lower trim but is assumed that the applied pressure is zero. The reading equal to zero must be active when the pressures of differential transmitter cameras are equalized or when a gage transmitter opens to atmosphere or when the absolute transmitter is applied to the vacuum. Therefore, the user does not need to enter with any value.

NOTE

The pressure taps on the transmitter must be equalized when zero trim is applied.

✓ Characterization Trim: this is used to correct any possible intrinsic non-linearity to the conversion process. Characterization is done by means of a linearization table, with up to five points. The user shall apply pressure and use the HART® configuration tools to inform the pressure value applied to each point of the table. In most cases, characterization is not required, due to the efficiency of the production process. The transmitter will display "CHAR", thus indicating that the characterization process has been activated. The LD301 is fitted with an internal feature to enable or disable the use of the Characterization Table.

WARNING

The characterization trim changes the transmitter characteristics. Read the instructions carefully and make sure that you work with a pressure standard that is accurate to your metrological system. A pressure standard that is compatible with the transmitter or its application need is recommended. Calibrations performed with inadequate accuracy standards will seriously affect the accuracy of the transmitter.

Current Trim

When the microprocessor generates a 0% signal, the Digital to Analog converter and associated electronics are supposed to provide a 4 mA output. If the signal is 100%, the output should be 20 mA.

There might be differences between the Smar current standards and your current plant Standard. In this case, the Current Trim adjustment shall be done with a precision ammeter as measurement reference. Two Current Trim types are available:

- ✓ 4 mA TRIM: this is used to adjust the output current value corresponding to 0% of the
 measurement:
- ✓ 20 mA TRIM: this is used to adjust the output current value corresponding to 100% of the measurement;

The Current Trim shall be carried out as per the following procedure:

- ✓ Connect the transmitter to the precision ammeter;
- ✓ Select one of the Trim types;
- ✓ Wait a while for the current to stabilize and inform the transmitter the current reading of the precision ammeter.

NOTE

The transmitter presents a resolution that makes it possible to control currents as low as microamperes. Therefore, when informing the current reading to the transmitter, it is recommended that data input consider values up to tenths of microamperes.

Temperature Trim

The LD301 transmitter allows the user to monitor the temperature submitted to the capacitive sensor through a temperature sensor located close to the process output. Typically, this temperature is adjusted to ambient temperature during the manufacturing process. If any deviation is noticed in the temperature measurement, a Temperature Trim is performed to correct the measurement.

Multidrop

The LD301 contains a variable that defines the equipment address in a HART® network. HART version 5 addresses range from 0 to 15 and version 7 addresses range from 0 to 63. 1 to 15 and 1 to 63 are specific addresses for multidrop connection (multipoint) for HART 5 and HART 7, respectively. When configured in multidrop, the display will indicate the MD icon. The LD301 leaves the factory configured with address 0.

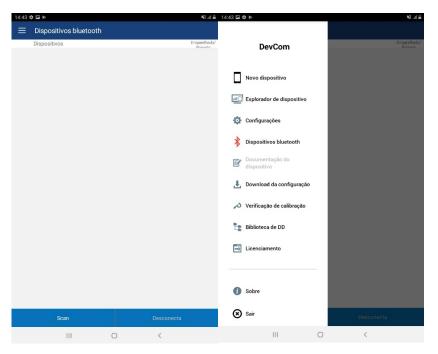
NOTE

The output current will be constant at 4 mA as soon as the LD301 address, in Transmitter mode, is changed to a value other than "0" (this does not occur when the LD301 is configured for Controller mode).

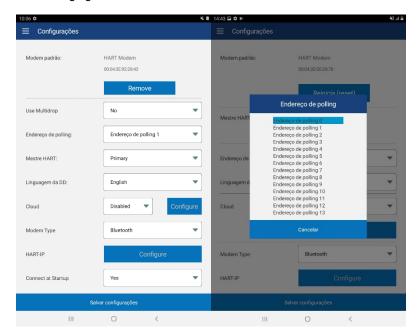
In the **Multidrop** tab, the user can change the address of the equipment with which it is already communicating. Select **ONLINE MULTIDROP** to access the multidrop network. After the configurator identifies the transmitter, in **Select Address** the user must choose the desired address for it. Please note that no other transmitter on the same line (regardless of manufacturer, model and type) must have the same address. Repeat this procedure for all equipment that will participate in the multidrop connection.

Before communicating with the equipment, it is necessary to configure the tablet to the current address where the equipment is located. This address is shown on the equipment's LCD at startup.

Using **DevComDroid**, click the three bars in the top left corner and select **Settings (Configurações)**. See following figures.



Modify the pooling address (endereço de polling) value to the equipment address. In this example the transmitter is at address 0, select it. After selecting the correct address, the DD for the equipment will be loaded. See following figures.

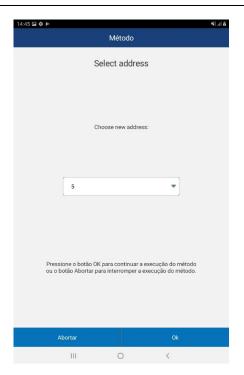


In the **Multidrop** tab it is possible to see the current address (0) and it is also possible to change the equipment address. To change, simply select **Select Address**.



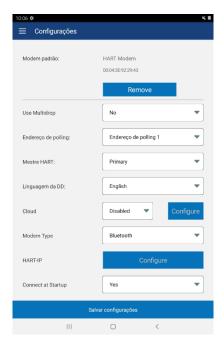


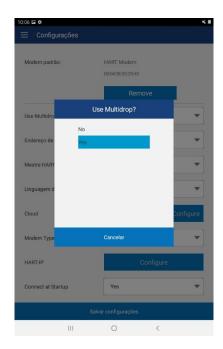
If the user wants to change the address to 5, for example, just choose 5 and then click **Ok**. The **Pooling Address** value will change to the current address of the equipment.



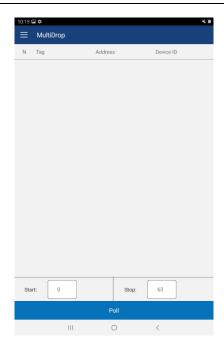


As of version 2.2.5 of **DevComDroid**, there is a scanning option where the user can discover the address of each device on the network. To do this, in the **DevComDroid** settings tab, under the **Use Multidrop** option, select **Yes** and click **Save Settings (Salvar Configurações)**. Open the application again.

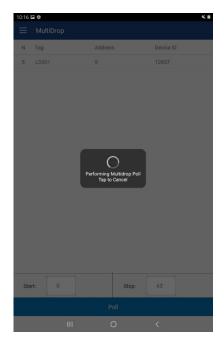




When opening the application, the scanning screen will appear, select the starting address of the scan in **Start** and the ending address in **Stop**. After selecting the track for scanning, click **Poll**. See following figure.

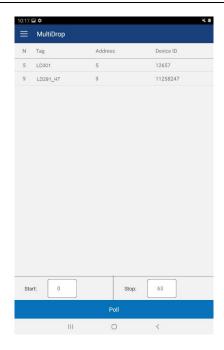


A pop-up will open indicating that the scan is running. During this scan, as the equipment is found, it is possible to view the address, tag, and ID of each one, as in the example below: Address = 5 Tag = LD301 ID = 12657 and Address = $9 \text{ Tag} = \text{LD291_H7 ID} = 11258247$





When the scan finishes, the user can see all the equipment found. On this screen it is possible to select which equipment the user wants to start communication with.



HART 7

The user can select which revision of the HART protocol the LD301 will work with, starting from firmware version 8. This can be done in the local adjustment, **SPEC REV** option. For more information on how to proceed, check the Programming Using Local Adjustment section in this manual.

Typical differences between these HART protocol revisions are listed below:

- Long Tag Supports up to 32 alphanumeric characters to identify the transmitter;
- ✓ Burst Mode Burst mode includes a variety of transmission settings, specifying burst variables, update period and message trigger mode;
- ✓ Multidrop Communication 4-20mA Up to 63 transmitters can be connected;
- ✓ Remapping of HART dynamic variables;
- ✓ Locking device implemented;
- ✓ Advanced diagnostics available.

The user can identify the HART protocol revision during equipment initialization.

Burst Mode

When Burst Mode is enabled, the transmitter sends data continuously according to the burst message configuration. The parameters for Burst Message are as follows:

- ✓ Burst command;
- ✓ Update period and maximum update period;
- ✓ Burst message trigger mode (Trigger Mode).

Burst Command 1 - Burst Command Cmd9 Cmd33 Burst Burst Variable Code (DD) 2 - Burst Variable Code Device Variable Code (DTM) Update Period 3 - Update period e Max Max Update Period . Update period 4 - Burst message trigger Burst Message mode Trigger Mode Window Rising Failing Burst Message Burst Trigger Level Trigger Mode? Continuous On-Change 5 - Burst message Burst Mode

Burst Mode configuration procedure

Figure 3.5 – Burst mode configuration diagram

Follow the steps below to configure Burst Mode, referring to figure 3.5.

1 - Burst Command

Select the HART command that will be transmitted by the burst message.

Burst Command	Command Description	Command Parameter	
1	Read Primary Variable (PV)	Pressure, differential pressure	
2	Read current loop (OUT) and range percentage (PV%)	Percentage of range, loop current	
3	Read dynamic variables and current loop	Loop current, pressure, differential pressure, static pressure, temperature	
9	Read equipment variables with status	Process variables, range/current percentage, mapping by user	
33	Read equipment variables	Process variables, range/current percentage, mapping by user	
48	Read additional status of equipment	Auto diagnostic information	

2 - Burst variable code / Device variable code

This parameter needs to be defined when the Burst Command is Command 9 (read up to 8 equipment variables with status) or Command 33 (read up to 4 equipment variables).

When command 33 is selected, the last 4 variable codes will not be used. It is important to note that the variable in slot 0 (the first) will be used for triggering purposes.

3 - Minimum Update period and Maximum update period

These parameters are used together with the selected trigger mode. When the trigger condition is met, the device will send burst data, using the minimum update period as a reference. If the trigger condition is not met, the equipment will send burst data, using the maximum update period.

The minimum time must be less than or equal to the maximum time. The update period should be selected as: 1, 2, 4, 8, 16, 32, 60-3600 seconds. If the user selects a different value, it will be adjusted to the closest available time value.

4 - Burst message trigger mode

Set the burst message trigger mode from the parameters shown below. When the burst message trigger mode is Window, Rising or Falling the burst trigger level is required. Are they:

Continuous: Burst message is transmitted continuously:

Window: In this mode the trigger value must be a positive number and is the symmetric window around the last communicated value.

Rising: In this mode, the burst message must be published when the source value exceeds the limit established by the trigger value;

Falling: In this mode, the burst message must be published when the source value falls below the limit established by the trigger value;

On-change: In this mode, the burst message must be published when the source value changes, when there is one in the HART frame since the last time it was sent;

Lock/Unlock Device

Used to block a device temporarily or permanently, preventing any changes from being made from a local panel or another master.

The following actions are available:

Unlock: Used to unlock the equipment when this is allowed for the master in question;

Temporary Lock: Used to temporarily lock the equipment to another master, that is, the equipment is unlocked after a reset. Only the master (primary or secondary) that made the lock can unlock it without resetting;

Lock Permanent: Used to lock the equipment permanently to another master, that is, the equipment is locked again after a reset. Only the master (primary or secondary) which made the lock can unlock it

Lock AII: No configuration, by any master, is allowed. Equipment remains locked after a reset. Any master can remove the equipment from this condition.

By clicking on the lock/unlock button it will be possible to check which lock status the equipment is in.

Process mapping variable commands

In this tab, in **Dynamic Variable**, the variables selected for PV, SV, TV and QV are shown, with their current values and units. PV will always be the pressure. The **Change Dynamic Variable** option allows the user to change what the SV, TV and QV will be, if desired. In **Device Variables** there are eight selectable boxes for the user to choose the variables that wants to monitor. Just choose and click on **Monitor Device Variables**. The **Lock/Unlock Device** option is used to lock a device temporarily or permanently, preventing any changes from being made from a local panel or another master.

All HART compatible field devices are required to return one or more dynamic variables, that is, the primary, secondary, tertiary, and quaternary variables.

Additionally, all HART-compliant field devices contain device variables.

It is possible for the user to configure what the dynamic variables of the equipment will be (PV, SV, TV, and QV), selecting any device variable. The equipment has only one analog channel and this must accompany the PV. Therefore, the PV cannot be mapped and will always remain with the pressure variable, as the 4-20 mA output current of the equipment will always be proportional to this measurement.

For the other variables (SV, TV, and QV) it is possible to select any of the device variables. See following table.

PARAMETER	DESCRIPTION	
OUT	Current in milliamperes.	
PV%	Process Variable in percentage.	
PV	Process Variable in engineering units.	
MV%	Output in percentage.	
PRES	Pressure in pressure unit.	
TEMP	Ambient temperature.	
TOT	Total accumulated by the totalizer.	
SP%	Setpoint in percentage.	
SP	Setpoint in engineering units.	
ERR%	Error in percentage (PV% - SP %).	

HART FIELD DEVICE EQUIPMENT VARIABLES OUT DYNAMIC VARIABLES PV% DYNAMIC VARIABLES MAPPING PV PV PROCESS OUT% CONTROL SYSTEM s٧ PRES TV TEMP TOT SP% SP ERR%

Figure 3.6 – Dynamic variables mapping diagram

PROGRAMMING USING LOCAL ADJUSTMENT

The Magnetic Tool

The local adjustment function can be used only through the digital display. The **LD301** on transmitter mode, without display and jumper-configured for simple mode, executes only the calibration function.

Figure 4.1 shows the location of the local adjustment female pins to connect the Local Adjustment Jumpers.

NOTE

Smar has developed the **DEVCOMDROID** (Android DDL Interpreter) software, used with HART interfaces, such as the **HI331** (Bluetooth Interface), in addition to **AssetView** (based on DTM) to configure the HART® equipment.

However, the old **PALM** with **HPC301** or **CONF401**, which are obsolete, remains operable even with the latest updates in HART transmitters.

They provide easy configuration and monitoring of field devices, capability to analyze data and to modify the performance of these devices. The operation characteristics and use of each one of the configuration tools are stated on their respective manuals.

It is also compatible to use configurators that support DDL (Device Description Language) or DTM (Device Type Manager).

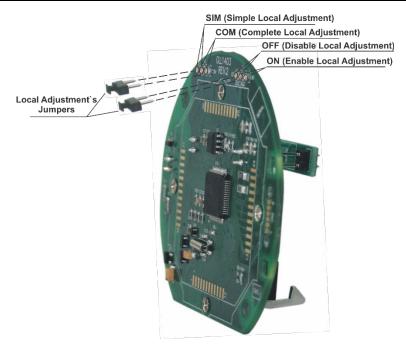


Figure 4.1 - Main Board with Jumpers

To select the function mode of the magnetic switches, configure the jumpers located at the top of the main circuit board as indicated in Table 4.1.

SIM/COM OFF/ON	NOTE	WRITE PROTECT	SIMPLE LOCAL ADJUSTMENT	COMPLETE LOCAL ADJUSTMENT
• • • • •		Disables	Disables	Disables
0 • • • 0	1	Enables	Disables	Disables
Disables Disables		Disables		
0 • • 0 • •		Disables	Disables	Enables

Notes: 1 - If the hardware protection is selected, the writing in memory will be protected.

2 - The local adjustment default condition is simple enabled and write protect disabled.

Table 4.1 - Local Adjustment Selection

The transmitter has, under the identification plate, holes for two magnetic switches activated by the magnetic tool (See Figure 4.2).

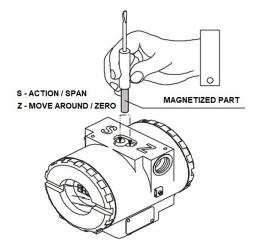


Figure 4.2 – Local Zero and Span Adjustment holes and Local Adjustment Switches

The holes are marked with **Z** (Zero) and **S** (Span) and from now on will be designated simply by (**Z**) and (**S**), respectively. Table 4.2 shows the action performed by the magnetic tool while inserted in (**Z**) and (**S**) in accordance with the selected adjustment type.

Browsing the functions and their branches works as follows:

- 1 Inserting the handle of the magnetic tool in (Z), the transmitter passes from the normal measurement state to the transmitter configuration state. The transmitter software automatically starts to display the available functions in a cyclic routine. The set of functions displayed depends on whether or not the PID is selected for the LD301.
- 2 In order to reach the desired option, browse the options, wait until they are displayed and move the magnetic tool from (Z) to (S). Refer to Figure 4.3 – Local Adjustment Programming Tree, in order to know the position of the desired option. By placing the magnetic tool once again in (Z), it is possible to browse other options within this new branch.
- **3** The procedure to reach the desired option is similar to the one described on the previous item, for the whole hierarchical level of the programming tree.

ACTION	SIMPLE LOCAL ADJUSTMENT	COMPLETE LOCAL ADJUSTMENT
Z	Selects the Lower Range Value	Moves among all the options
s	Selects the Upper Range Value Activates the selected Functions	Activates the selected Functions

Table 4.2 - Local Adjustment Description

Simple Local Adjustment

The Simple Local Adjustment is as follows:

- ✓ Zero Adjustment: when placing the magnetic key in the hole marked with (Z), the measured pressure will be the pressure corresponding to the current of 4 mA;;
- ✓ **Span Adjustment:** when placing the magnetic key in the hole marked (S), the measured pressure will be the pressure corresponding to the current of 20 mA.

NOTE

In order for the calibration to occur properly, it is necessary to pay attention to the minimum span for each range and types of measurement defined in the Technical Specification (Section 3).

Zero calibration with reference shall be done as follows:

- ✓ Apply the Lower Value pressure.
- ✓ Wait for the pressure to stabilize.
- ✓ Insert the magnetic tool in the ZERO adjustment hole. (See Figure 4.2)
- ✓ Wait 2 seconds and soon the transmitter should be reading 4 mA.
- Remove the tool.

Zero calibration with reference does not affect the span. In order to change the span, the following procedure shall be observed:

- ✓ Apply the Upper Value pressure.
- ✓ Wait for the pressure to stabilize.
- ✓ Insert the magnetic tool in the S adjustment hole.
- ✓ Wait 2 seconds. The transmitter should be reading 20 mA.
- Remove the tool.

Zero adjustment causes zero elevation or suppression and a new upper value (URV) are calculated in accordance with the effective span. In case the resulting URV is higher than the Upper Limit Value (URL), the URV will be limited to the URL value, and the span will be automatically affected.

NOTE

On elevation or suppression measuring configure the user unit to facilitate the local reading

Complete Local Adjustment

The Complete Local Adjustment is as described in the Local Adjustment Programming Tree below.

WARNING

When programming using local adjustment, the transmitter will not prompt "Control loop should be in manual!" as it does when using the HART® configurator for programming. Therefore it is a good idea, before configuration, to switch the loop to manual. And do not forget to return to auto after configuration is completed.

Local Programming Tree

The local adjustment uses a tree structure where, by placing the magnetic tool in (**Z**) it is possible to browse the options of a branch and, by placing it in (**S**); details of the chosen option are shown. Figure 4.3 - Local Adjustment Programming Tree shows the **LD301** available options.

NOTA

From version 7.00.00 of LD301 the local adjustment tree has been changed to that shown in figure 4.3.

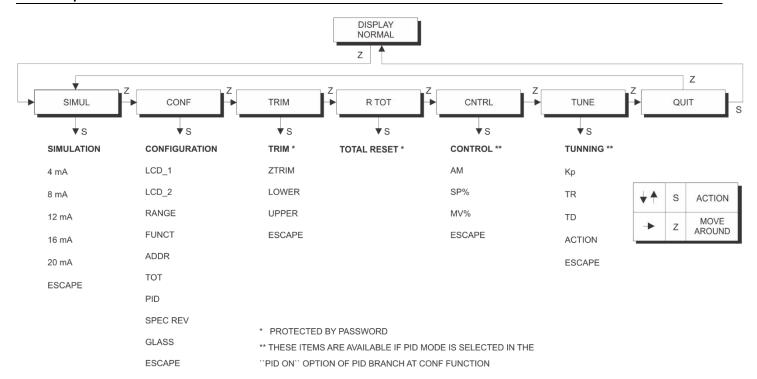


Figure 4.3 – Local Adjustment Programming Tree – Main Menu

Actuating in (\mathbf{Z}) activates local adjustment. With the PID disabled, CNTRL and TUNE options are unavailable.

SIMULATION (SIMUL) – Is the current simulation option for loop test. Options: 4 mA, 8 mA, 12 mA, 16 mA or 20 mA.

CONFIGURATION (CONF) - Is the option where the output and display related parameters are configured: unit, primary and secondary display, calibration, function, operation mode, address, totalization, device revision version, and display type.

TRIM (TRIM) - Is the option used to transmitter characterization, adjusting its digital reading.

TOTAL RESET (R TOT) – The totalization value is zeroed.

CONTROL (CNTRL) - Is the option where the operation related parameters of the controller are configured: Auto/Manual, Setpoint and Manual output.

TUNNING (TUNE) - Is the option where the PID-Algorithm related parameters are configured: Action, Kp, Tr and Td.

QUIT (QUIT) - Is the option used to go back to normal monitoring mode.

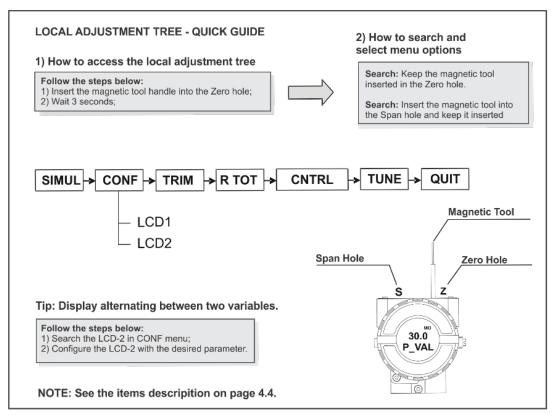


Figure 4.4 - Quick guide of Local Adjustment

Simulation [SIMUL]

This operation has the function of simulating the output current for the loop test. Value options to be simulated: 4 mA, 8 mA, 12 mA, 16 mA or 20 mA.

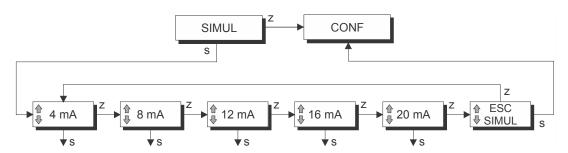
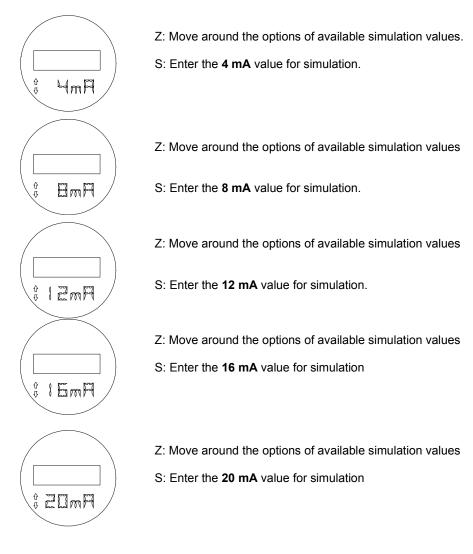


Figure 4.5 – Simulation branch Local Adjustment Programming Tree

SIMULATION BRANCH (SIMUL)







- Z: Move to simulation current value 4 mA.
- S: Escapes to the Configuration option (CONF).

Configuration [CONF]

This branch is common for both PID enabled and disabled condition. Configuration functions affect directly the 4-20 mA output current and the display indication. The configuration options implemented in this branch are the following:

- ✓ Selection of the variable to be shown on Display 1 and on Display 2.
- ✓ Working range calibration for PID enabled or disabled. Options With and Without Reference options are available.
- Digital filter damping time configuration of the reading signal input.
- ✓ Selection of the transference function to be applied to the measured variable.
- ✓ Selection of PID enabled or disabled for the LD301.

- ✓ Address selection.
- ✓ Totalization
- ✓ Selection of Device Revision
- ✓ Selection of Display option

The next figure shows CONF branch with the available options.

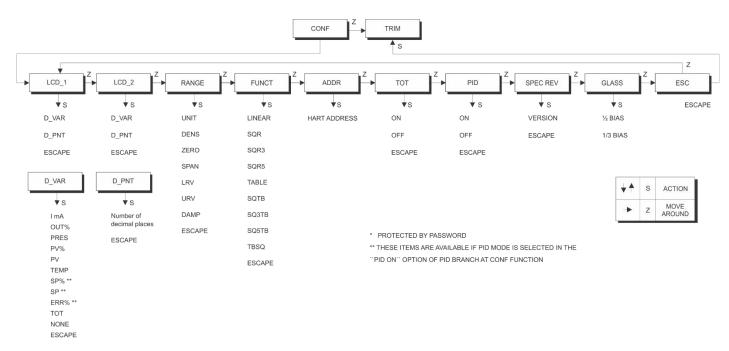
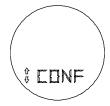


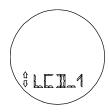
Figure 4.6 - Local Adjustment Configuration Tree

CONFIGURATION BRANCH (CONF)



- Z: Moves to the PRESSURE TRIM (TRIM) branch.
- **S:** Enters the CONFIGURATION branch, starting with function display (LCD 1).

Display 1 (LCD_1)



- **Z**: Moves to the function Display 2 (LCD_2).
- S: Activates the LCD_1 function, allowing the operation in (S) to go through the functions Display Variables D_VAR and Decimal Places D_PNT .

Display Variables (D_VAR)



- Z: Moves to the function Decimal Place D_PNT.
- S: Actuating with the magnetic tool in (S) once activates the Display Variables function D_VAR, allowing with the operation in (Z) to pass through the variables available for the LCD_1. The desired variable is activated using (S). Escape ESC SEL_VAR leaves the primary display unchanged. See Table 4.3.

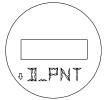
Decimal Place (D_PNT)



- Z: Moves to Escape ESC SEL_VAR.
- S: Moves to the Increase Decimal Place option D_PNT.



- Z: Moves to the **Decrease Decimal Place** option **D_PNT**.
- S: Increase the number of decimal places until the magnetic tool is removed or the upper limit of decimal places is reached.



- Z: Moves to the **SAVE D_PNT** function.
- S: Decrease the number of decimal places until the magnetic tool is removed or the lower limit of decimal places is reached.



- Z: Moves to the **ESC INC** function.
- S: Saves the **D_PNT** value on the transmitter main electronic bord memory.



- Z: Moves to the Increase Decimal Place option D PNT.
- S: Returns to the **Decimal Point** (**D_PNT**).

Variables Selection Escape (ESC SEL_VAR)



- Z: Moves to **Display Variables** option **D_VAR**.
- S: Returns to the Display LCD_2 function.

Display 2 (LCD_2)



- **Z:** Moves to the RANGE function.
- **S:** Activates the **LCD_2** function, allowing the operation in (S) to go through the functions Display Variables **D_VAR** and Decimal Places **D_PNT**. The procedure for selection is the same as for LCD_1, above.

Display LCD_1/LCD_2 (D_VAR)	Description
ImA	Analog Output Current in mA
OUT %	Output in percentage
PRES	Pressure in pressure unit
PV %	Process Variable in percentage
PV	Process Variable in user unit
TEMP	Temperature in Celsius degree
SP %	Setpoint in percentage
SP	Setpoint in user unit
ERR%	Error in percentage
ТОТ	Totalization
NONE*	No variable on display (only LCD_2)
ESCAPE	Escape

^{*}In this condition only one variable is indicated in the Display, in this case the parameter configured for LCD_1

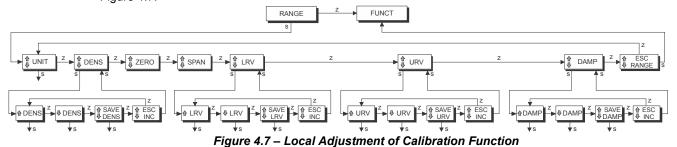
Table 4.3 - Display Indication

NOTE

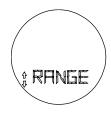
With the PID disabled, only the ImA, OUT%, PRES, PV%, PV, TEMP and TOT can be displayed. Besides, it is also possible to select option **None** for **Display 2**.

Calibration (RANGE)

Function Calibration (RANGE) presents the calibration options as a tree branch, as described on Figure 4.7.

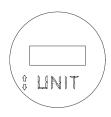


RANGE BRANCH (RANGE)



- **Z**: Moves to the **FUNCT** function, **CONF** branch.
- **S:** Enters the **RANGE** branch, starting with the function **UNIT**.

Unit (UNIT)



- Z: Moves to the **Density** function (**DENS**).
- **S:** Starts selection of engineering unit for process variable and setpoint indication. The user can move around the options available in the table below by activating (**Z**).

Unit Escape (ESC UNIT)



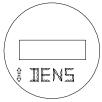
- **Z**: Moves to the first unit option.
- S: Escapes to the **Density** function (**DENS**).

UNIT		
DISPLAY	DESCRIPTION	
InH ₂ O	inches water column at 20 °C	
InHg	inches mercury column at 0 °C	
ftH₂O	feet water column at 20 °C	
mmH₂O	millimeter water column at 20 °C	
mmHg	millimeter mercury column at 0 °C	
psi	pounds per square inches	
bar	Bar	
mbar	millibar	
Kgf/cm ²	Kilogram-force per square centimeter	
kPa	Kilopascal	
mH2O	meter water column	
atm	atmosphere	
MPa	megapascal	
ft	feet	
m	meter	
In	inches	

Table 4.4 – Units

The desired unit is activated by inserting the magnetic tool into (S).

Density (DENS)

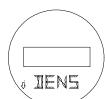


- Z: Moves to Zero Adjustment with reference (ZERO).
- S: Moves to INCREASE DENS VALUE.



Z: moves to **DECREASE DENS VALUE**.

S: increases the density value until the magnetic tool is removed or the upper limit is reached.



- Z: moves to **SAVE DENS** function.
- S: decreases the density value until the magnetic tool is removed or the lower limit is reached.



- Z: Moves to **ESC INC** function.
- S: Saves the density value on the transmitter main electronic board memory.



- Z: Moves to INCREASE DENS VALUE.
- S: Escapes to Density (DENS) function.

Zero Adjust with Reference {ZERO}



- **Z:** Moves to the Span with reference **Adjustment** function (**SPAN**).
- S: Adjusts the Lower Range Value

Span with reference adjustment (SPAN)

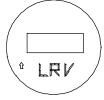


- Z: Moves to Lower range value adjustment without reference (LRV).
- S: Increases the Span value.

Lower Range Value Adjustment without Reference (LRV)



- **Z**: Moves to the Upper range value adjustment without reference function (**URV**).
- S: Moves to INCREASE LRV function.



- **Z:** Moves to the **DECREASE LRV** function.
- **S:** Increases the Lower Value until the magnetic tool is removed or the upper limit of the Lower Value is reached.



- Z: Moves to the SAVE LRV function.
- **S:** Decreases the Lower Value until the magnetic tool is removed or the minimum Lower Value is reached.



- Z: Moves to **ESC INC** function.
- S: Saves the \boldsymbol{LRV} value on the transmitter main electronic board memory.



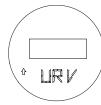
Z: Moves to INCREASE LRV option.

S: Escapes to Lower Range Value Adjustment without Reference (LRV) function.

Upper Range Value Adjust without Reference {URV}

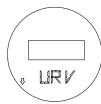


- **Z:** Moves to the **Damping** (**DAMP**) function.
- S: Moves to INCREASE URV option.



Z: Moves to the **DECREASE URV** function.

S: Moves to **INCREASE URV** and increases the Upper Value until the magnetic tool is removed or the maximum Upper Value is reached.



Z: Moves to the SAVE URV function.

S: Decreases the Upper Value until the magnetic tool is removed or the minimum Upper Value is reached.

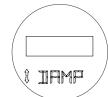


- Z: Moves to the ESC INC function.
- **S:** Saves the **URV** value on the transmitter main electronic board memory

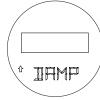


- Z: Moves to **INCREASE URV** option.
- S: Escapes to Upper Range Value Adjustment without Reference (URV) function.

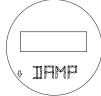
Damping (DAMP)



- Z: Moves to ESC RANGE function.
- S: Moves to INCREASE DAMPING.



- Z: Moves to **DECREASE DAMPING**.
- S: Increase the time constant of damping until the magnetic tool is removed or 128 seconds is reached.



- Z: Moves to **SAVE DAMP** function.
- S: Decrease the time constant of damping until the magnetic tool is removed or 0 seconds is reached.



- Z: Moves to **ESC INC** function.
- S: Saves the DAMPING value on the transmitter main board memory.



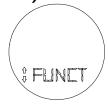
- Z: Moves to INCREASE DAMPING function.
- S: Escapes to **DAMPING (DAMP)** function.

Calibration Escape (ESC RANGE)



- Z: Returns to Unit function (UNIT).
- S: Returns to Function (FUNCT) function of Configuration branch (CONF).

Function (FUNCT)



- Z: Moves to the ADDRESS function.
- **S:** Starts selection of transfer function. After activating (**Z)**, you can move around the available options in the table 4.5.

FUNCTIONS		
DISPLAY	DESCRIPTION	
LINEAR	Linear to Pressure	
SQR	\sqrt{x}	
SQR3	$\sqrt{x^3}$	
SQR5	$\sqrt{x^5}$	
TABLE	16 Point Table	
SQTB	\sqrt{x} + 16 Point Table	
SQ3TB	$\sqrt{x^3}$ + 16 Point Table	
SQ5TB	$\sqrt{x^5}$ + 16 Point Table	
TBSQ	16 Point Table + \sqrt{x}	
ESC	escape	

Table 4.5 – Functions

The desired function is activated using (S). Escape leaves function unchanged.

Escape (ESC FUNCT)

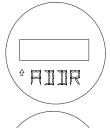


- **Z**: Moves to the first option of the transfer function.
- S: Returns to the ADDR function of the Configuration branch (CONF).

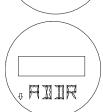
Address (ADDR)



- Z: Moves to **Totalization** (**TOT**) function.
- S: Moves to INCREASE ADDRESS ADDR option.



- Z: Moves to **DECREASE ADDRESS ADDR** option.
- S: Increases the address value until the magnetic tool is removed or until the address 15 (HART 5) or 63 (HART7) is reached.



- Z: Moves to **SAVE ADDR** function.
- S: Decrease the address value until the magnetic tool is removed or until the address 0 is reached.



Z: Moves to ESC INC function.

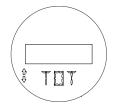
S: Saves the address value on the transmitter main electronic board memory.



- Z: Moves to INCREASE ADDRESS ADDR option.
- S: Escape to ADDRESS function (ADDR).

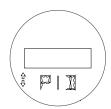
Totalization (TOT)

The totalization parameters are configured via HART configurator, as they require a more elaborate man-machine interface as described in Section 3.



- Z: Moves to Mode PID function.
- S: Switches the totalization TOT from ON to OFF or from OFF to ON.

PID Mode (PID)



- Z: Moves to **SPEC REV** function.
- S: Switches the PID mode from ON to OFF or from OFF to ON.

Specific Device Revision (SPEC REV)



- Z: Moves to GLAS function.
- S: Moves to INCREASE SPEC REV option.



- Z: Moves to **DECREASESPEC REV** function.
- S: Increase the version until the magnetic tool is removed or until the highest numbered version is reached.



- Z: Moves SAVE SPEC REV function.
- S: Decrease the version until the magnetic tool is removed or until the lowest numbered version is reached.

NOTA

- If SPEC REV is 6, the transmitter will work as HART 7.

- If SPEC REV is less than 6 the transmitter will work as HART 5



- Z: Moves to **ESC INC** function.
- S: Saves the specific revision on the transmitter main electronic board memory.



- Z: Moves to INCREASE SPEC REV function.
- S: Escapes to **SPEC REV** function.

Display type (GLAS)



- Z: Returns to ESC CONF option.
- S: Switches between **1/2 Bias** or **1/3 Bias** display options according to which display is used.

Configuration Escape (ESC CONF)



- Z: Returns to display 1 (LCD1) function.
- S: Escapes to TRIM branch.

Pressure Trim [TRIM]

This field of the tree is used to adjust the digital reading according to the applied pressure. The pressure TRIM differs from RANGING WITH REFERENCE, since the TRIM is used to correct the measure and RANGING WITH REFERENCE reach only the applied pressure with the output signal of 4 to 20 mA. Figure 4.8 shows the options available to run the pressure TRIM.

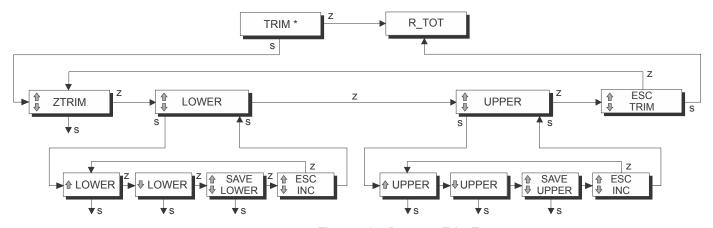
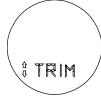


Figure 4.9 - Pressure Trim Tree

TRIM BRANCH (TRIM)



Z: Moves to R TOT function.

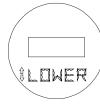
S: These functions are protected by "password." When prompted PSWRD, enter the password. The password code consists of inserting and removing the magnetic tool 2 times in (S). The first time changes the password value from 0 to 1 and the second, allows you to enter the available options, starting with the Zero Pressure Trim.

Zero Pressure Trim (ZTRIM)

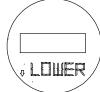


- **Z**: Moves to the lower pressure trim function (**LOWER**).
- **S**: Adjusts the transmitter internal reference to read 0 at the applied pressure.

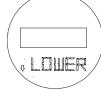
Lower Pressure Trim (Lower)



- Z: Moves to upper pressure trim option (UPPER).
- S: Moves to **INCREASE LOWER PRESSURE VALUE** and adjusts the transmitter internal reference, increasing the displayed value that will be interpreted as the Lower Pressure value corresponding to the applied pressure.



- Z: Moves to **DECREASE LOWER PRESSURE VALUE** function.
- S: Adjusts the transmitter internal reference, increasing the displayed value that will be interpreted as the Lower Pressure value corresponding to the applied pressure.



- Z: moves to **SAVE LOWER** function.
- S: Adjusts the transmitter internal reference, decreasing the displayed value that will be interpreted as the Lower Pressure value corresponding to the applied pressure.



- Z: Moves to **ESC INC** function.
- S: Saves the points of Lower trim on the transmitter main electronic board memory and updates the internal parameters of pressure measurement.



- Z: Moves to INCREASE LOWER PRESSURE VALUE option.
- S: Returns to Lower pressure trim function (LOWER)

Upper Pressure Trim (UPPER)



Z: Moves to ESC TRIM function.

S: Moves to **INCREASE UPPER PRESSURE VALUE** and adjusts the transmitter internal reference, increasing the displayed value that will be interpreted as the Upper Pressure value corresponding to the applied pressure.



Z: Moves to DECREASE UPPER PRESSURE VALUE function.

S: Adjusts the transmitter internal reference, increasing the displayed value that will be interpreted as the Upper Pressure value corresponding to the applied pressure.



Z: Moves to the SAVE UPPER function.

S: Adjusts the transmitter internal reference decreasing to the value on the display, that will be interpreted as the Upper Pressure value corresponding to the applied pressure.



Z: Moves to the ESC INC function.

S: Saves the upper trim points on the transmitter main electronic board memory and updates the internal parameters of pressure measurement.



- Z: Moves to INCREASE UPPER PRESSURE VALUE option.
- S: Returns to Upper pressure trim function (UPPER)



Z: Moves to the ZERO TRIM function (ZTRIM).

S: Escapes to the MAIN menu, Reset Total branch (R TOT).

Totalization Reset [R TOT]

This is the branch which the totalization value is zeroed.

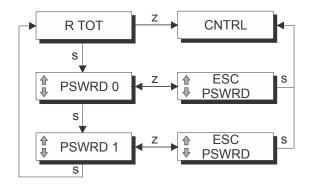
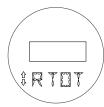
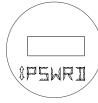


Figure 4.9 - Total Reset branch of the local adjustment tree



- Z: Moves to CONTROL function (CONTROL).
- S: Moves to password option (PSWRD) with value 0.



- Z: Moves to **ESC PSWRD** option.
- S: When the 0 PSWD appears, enter the password. The password code consists of inserting the magnetic tool in (S) and wait until the number 0 changes to 1. After that, when the magnetic tool is pressed again in (S), the totalization value will be reset to zero.



- Z: Moves between 0 or 1 PSWRD.
- S: Exits the $\mbox{\bf PSWRD}$ branch and enters the Control option $(\mbox{\bf CNTRL}).$

Control [CNTRL]

This adjustment option is applicable to the **LD301** configured with PID enabled. It allows the control state to be changed from Automatic to Manual and vice versa, and also to adjust the Setpoint and Manipulated Variable values. Figure 4.10 shows branch CNRTL with the available options.

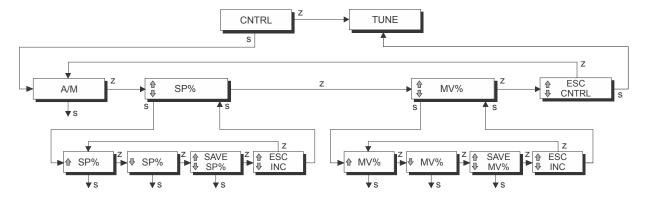
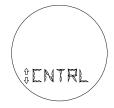


Figure 4.10 - Local Adjustment Control Tree

CONTROL BRANCH (CNTRL)



- Z: Moves to the next branch (TUNE).
- S: Enters the CONTROL branch, starting the function AUTO/ MANUAL.

Auto/Manual (A/M)



- **Z**: Moves to the setpoint adjustment function (**SP**).
- **S:** Switches the controller status, Automatic to Manual or Manual to Automatic. A and M letters indicate status.

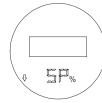
Setpoint Adjustment (SP)



- **Z**: Moves to the manipulated variable adjustment function (MV).
- S: Changes to INCREASE SETPOINT option.



- Z: Moves to the **DECREASES SETPOINT** function.
- **S:** Increases the setpoint until the magnetic tool is removed or 100% is reached.



- Z: Moves to **SAVE SETPOINT** function.
- S: Decreases the setpoint until the magnetic tool is removed or 0% is reached.



- Z: Moves to **ESC INC** function.
- S: Saves the Setpoint value on the transmitter main electronic board memory to use when the SP is requested.



- Z: Moves to INCREASE SETPOINT function.
- S: Returns to Setpoint adjustment option (SP)

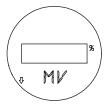
Manipulated Variable Adjustment (MV)



- **Z**: Moves to the control escape function (CNTRL).
- S: Changes to INCREASE MANIPULATED VARIABLE option.



- Z: Moves to **DECREASE MANIPULATED VARIABLE function**.
- S: Increase the manipulated variable of PID until the magnetic tool is removed or the output upper limit is reached.



- Z: Moves to the SAVE MV% function.
- **S:** Decreases the manipulated variable of PID until the magnetic tool is removed or the lower output limit is reached.



- Z: Moves to ESC INC function.
- **S:** Saves the Manipulated Variable value on the transmitter main electronic board memory to use when the MV is requested.



- Z: Moves to INCREASE MANIPULATED VARIABLE function.
- S: Returns to manipulated variable adjustment (MV).

Control Escape (ESC CNTRL)



- Z: Moves to the AUTO/ MANUAL function (A/M).
- S: Returns to the MAIN menu to the tuning branch (TUNE).

Tuning [TUNE]

This adjustment option is applicable to the **LD301** configured with the PID enabled. It allows the control loop to be tuned, acting on the Proportional, Integral and Derivative terms, and also to change the PID mode. The implemented algorithm is a PID type, with the following characteristics:

- ✓ The proportional action is given by the Proportional Gain and not by the proportional band. Range: 0 100.
- ✓ Integral action is expressed in minutes per repetition.
- The derivative constant is obtained in seconds.

It is possible to cancel the Integral and Derivative actions by adjusting Tr and Td, respectively to 0.

Figure 4.11 shows branch TUNE with the available options.

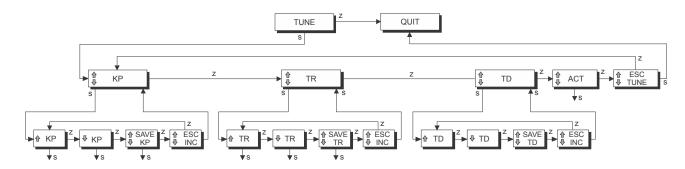
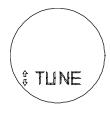


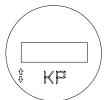
Figure 4.11 - Local Adjustment Tuning Tree

TUNING BRANCH (TUNE)



- Z: Moves to the QUIT branch.
- $\textbf{S:} \ \, \textbf{Enters the TUNE} \ \, \textbf{branch, starting with function} \ \, \textbf{KP-ADJUSTMENT} \ \, \textbf{option}.$

Kp - Adjustment (KP)



- Z: Moves to the Tr adjustment (TR).
- S: Changes TO INCREASE PROPORTIONAL GAIN option.



- Z: Moves to the **DECREASE PROPORTIONAL GAIN** option.
- **S:** Increases the proportional gain until the magnetic tool is removed or until the limit is reached.



- Z: Moves to the SAVE KP function.
- **S:** Decreases the proportional gain until the magnetic tool is removed or 0 value is reached.

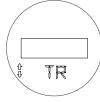


- Z: Moves to **ESC INC** function.
- S: Saves the KP constant on the transmitter main electronic board memory.

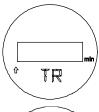


- Z: Moves to INCREASE PROPORTIONAL GAIN option.
- S: Returns to Kp Adjustment (KP) function.

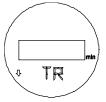
Tr - Adjustment (TR)



- Z: Moves to **TD ADJUSTMENT** (**TD**) function.
- S: Changes to INCREASE INTEGRAL TIME option.



- Z: Moves to the INTEGRAL TIME DECREASE function.
- **S:** Increases the integral time until the magnetic tool is removed or until the upper limit is reached.



- Z: Moves to the SAVE TR function.
- $\textbf{S:}\ \mbox{Decreases the integral time until the magnetic tool is removed or 0 minute per repetition is reached.}$

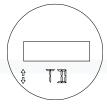


- Z: Moves to the **ESC INC** function.
- $\ensuremath{\mathsf{S}} \xspace$ Saves the TR constant on the transmitter main electronic board memory.

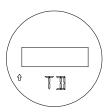


- Z: Moves to **INCREASE INTEGRAL TIME** option.
- S: Returns to **TR ADJUSTMENT** (**TR**) function.

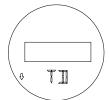
Td Adjustment (TD)



- Z: Moves to the ACTION function (Act)
- S: Switches to **DERIVATIVE TIME INCREASE** option.



- Z: Move to the **DECREMENT DERIVATIVE TIME** option.
- S: Increases the derivative time until the magnetic screwdriver is removed or until the limit is reached.



- Z: Moves to the **SAVE TD** function.
- S: Decrease DERIVATIVE TIME until the magnetic screwdriver is removed or until 0 seconds is reached.



- Z: Moves to **ESC INC** function.
- S: Records the TD constant in the transmitter's main electronic board memory.



- Z: Move to the **INCREASE DERIVATIVE TIME** option.
- S: Returns to the Td function (**TD**)

Action (ACT)



- **Z**: Moves to the **ESCAPE** function of tuning menu (**ESC TUNE**).
- **S**: Switches the direct action to reverse or reverse to direct indicated on display.

Tuning Escape (ESC TUNE)



- **Z:** Moves to the **KP-ADJUSTMENT** function.
- **S:** Escapes to the main menu (**QUIT**).

Escape Local Adjustment [QUIT]

This branch of the main tree is used to leave the Local Adjustment mode, placing the Transmitter in the monitoring mode.

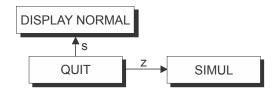


Figure 4.12 – Quit branch (QUIT) of Local Adjustment Tree



- Z: Returns to Simulation branch (SIMUL).
- **S:** Escapes to NORMAL DISPLAY mode, placing the LD301 in monitoring mode.

MAINTENANCE

General

NOTE

Installations in hazardous areas must follow the recommendations of the applicable standards. Refer to Appendix A for this information.

Below, there are some important maintenance procedures that should be followed in order to have safer plant and easy maintenance.

In general, it is recommended that end users do not try to repair printed circuit boards. Spare circuit boards may be ordered from **SMAR** whenever necessary.

The sensor has been designed to operate for many years without malfunctions. Should the process application require periodic cleaning of the transmitter, the flanges may be easily removed and reinstalled.

Should the sensor eventually require maintenance, it may not be done on the field. In this case, the possibly damaged sensor should be returned to **SMAR** for evaluation and, if necessary, repair. Refer to the "Returning Materials" item at the end of this Section.

Diagnostic using Configuration Tool

Should any problem be noticed regarding the transmitter output, the configurator can be used to verify what is the problem (see Table 5.1).

The configurator should be connected to the transmitter according to the wiring diagram shown on Section 1, Figures 1.7, 1.8 and 1.9.

Error Messages

When communicating using the CONFIGURATOR the user will be informed about any problem found by the transmitter self-diagnostics.

Table 5.1 presents a list of error messages with details for corrective actions that may be necessary.

ERROR MESSAGES	POTENTIAL SOURCE OF PROBLEM				
UART RECEIVER FAILURE:	The line resistance is not according to load limitation.				
PARITY ERROR	Excessive noise or ripple in the bus.				
OVERRUN ERROR	Low level signal.				
ERROR CHECK SUM	Interface damaged.				
FRAMING ERROR	Power supply with inadequate voltage.				
	Transmitter bus resistance is not according to load limitation.				
	Transmitter not powered.				
CONFIGURATOR DOES NOT	Interface not connected or damaged.				
RECEIVE ANSWER FROM TRANSMITTER	Repeated bus address.				
TRANSWITTER	Transmitter polarity is reversed. Interferent descriptions of the second description of th				
	Interface damaged. Payor a wards with its adaptive to the research to th				
	Power supply with inadequate voltage.				
ONE NOT IMPLEMENTED	Software version not compatible between configurator and transmitter.				
CMD NOT IMPLEMENTED	Configurator is trying to carry out a LD301 specific command in a transmitter from another manufacturer.				
TRANSMITTER BUSY					
TRANSMITTER BUSY	Transmitter carrying out an important task, e.g., local adjustment.				
TRANSMITTER FAILURE	Sensor disconnected.				
	Sensor failure.				
COLD START	Start-up or Reset due to power supplies failure.				
OUTPUT FIXED	Output in Constant Mode.				
OUTFULFIXED	Transmitter in Multidrop mode.				
OUTPUT SATURATED	Pressure out of calibrated Span or in fail-safe state (Output current in 3.8 or 20.5 mA).				

ERROR MESSAGES	POTENTIAL SOURCE OF PROBLEM
SV OUT OF LIMITS	Temperature out of operating limits.
	Temperature sensor damaged.
	Pressure out of operation limits.
PV OUT OF LIMITS	Sensor damaged or sensor module not connected.
	Transmitter with wrong configuration.
LOWER RANGE VALUE TOO HIGH	Lower value exceeds 25% of the Upper Range Limit.
LOWER RANGE VALUE TOO LOW	Lower value exceeds 25% of the Lower Range Limit.
UPPER RANGE VALUE TOO HIGH	Upper value exceeds 25% of the Upper Range Limit.
UPPER RANGE VALUE TOO LOW	Upper value exceeds 25% of the Lower Range Limit.
UPPER & LOWER RANGE VALUES OUT OF LIMITS	Lower and Upper Values are out of the sensor range limits.
SPAN TOO SMALL	The difference, between the Lower and Upper values is less than the minimum span.
APPLIED PRESURE TOO HIGH	The pressure applied was above the 25% upper range limit.
APPLIED PRESURE TOO LOW	The pressure applied was below the 25% lower range limit.
EXCESS CORRECTION	The trim value entered exceeded the factory-characterized value by more than 20%.
PASSED PARAMETER TOO LARGE	Parameter above operating limits.
PASSED PARAMETER TOO SMALL	Parameter below operating limits.

Table 5.1 - Error Messages and Potential Source

Diagnostic via Transmitter

NOTE
D0 and M0 ranges are available only for 6.05 versions or greater.

Symptom: NO LINE CURRENT

Probable Source of Trouble:

✓ Transmitter Connections

- · Check wiring polarity and continuity.
- Check short circuit or ground loops.
- Check if the power supply connector is connected to main board.

√ Power Supply

 Check power supply output. The voltage must be between 12 and 45 Vdc at transmitter terminals.

✓ Electronic Circuit Failure

• Check the main board for defect by using a spare one.

Symptom: NO COMMUNICATION

Probable Source of Trouble:

✓ Terminal Connections

- Check the terminal interface connection of the configurator.
- Check if the interface is connected to the wires leading to the transmitter or to the terminals
 [+] and [-].
- Check if the interface is HPI311 (for HART protocol).

✓ Transmitter Connections

- Check if connections are according to wiring diagram.
- Check if there is resistance in the 250 Ω line. See load limitation in Section 1.

√ Power Supply

 Check output of power supply. The voltage at the LD301 terminals must be between 12 and 45 Vdc, and ripple less than 500 mV.

✓ Electronic Circuit Failure

• Locate the failure by alternately testing the transmitter circuit and the interface with spare parts.

√ Transmitter Address

• Check if the transmitter address is compatible with the one expected by the configurator.

Symptom: CURRENT in 21.0 mA or 3.6 mA

Probable Source of Trouble:

√ Pressure Tap (Piping)

- Verify if blocking valves are fully open.
- Check for gas in liquid lines or for liquid in dry lines.
- Check the density of process fluid.
- Check for sedimentation in the transmitter chambers.
- Check the pressure connection.
- Check if bypass valves are closed.
- Check if pressure applied is not above upper limit of the transmitter range.

✓ Sensor to Main Circuit Connection

- Sensor connection to the Main Board.
- Check connection (male and female connectors).

✓ Electronic Circuit Failure

- Check the sensor circuit for damage by replacing it with a spare one.
- · Replace sensor.

Symptom: INCORRECT OUTPUT

Probable Source of Trouble:

√ Transmitter Connections

- Check power supply voltage.
- Check for intermittent short circuits, open circuits and grounding problems.

✓ Process Fluid Oscillation

Adjust damping

✓ Pressure Tap

- Check for gas in liquid lines and for liquid in steam or gases lines.
- · Check the integrity of the circuit by replacing it with a spare one.

✓ Calibration

· Check calibration of the transmitter.

NOTE

A 21.0 or 3.6 mA current indicates that the transmitter is in Burnout (TRM) or safety output (PID). Use the configurator to investigate the source of the problem.

Symptom: DISPLAY INDICATES "FAIL SENS"

Probable Source of Trouble:

✓ Sensor Connection to the Main Board

Check the connection (flat cable, male and female connectors).

√ Type of Sensor Connected to the Main Board

Check if the sensor connected to the main board is the one specified for the LD301 HART mode.

✓ Electronic Circuit Failure

Check if the sensor set is damaged, replacing it for a spare one.

Disassembly Procedure

WARNING

Do not disassemble with power on.

Figure 5.2 shows a transmitter exploded view and will help you to visualize the following:

Sensor

In order to have access to the sensor for cleaning purposes, the transmitter should be removed from its process connections. The transmitter should be isolated from the process by means of manifolds or valves; then, the drain must be opened to vent any remaining pressure.

After this, the transmitter may be removed from the standpipe. The flange bolts may now be loosened, one at a time. After removing bolts and flanges, the isolating diaphragms will be easily accessible for cleaning.

Cleaning should be done carefully in order to avoid damaging the delicate isolating diaphragms. Use of a soft cloth and a nonacid solution is recommended.

To remove the sensor from the electronic housing, the electrical connections (in the field terminal side) and the main board connector must be disconnected.

Loosen the hex screw and carefully unscrew the electronic housing from the sensor, observing if the flat cable is not excessively twisted.



Figure 5.1 - Sensor Safety Rotation

WARNING

To avoid damage do not rotate the electronic housing more than 270° starting from the fully threaded without disconnecting the electronic circuit from the sensor and from the power supply. See Figure 5.1.

Electronic Circuit

To remove the circuit board (3), loosen the two screws, that anchor the board and hold the spacers in the other side to avoid losing them.

WARNING

The board has CMOS components, which may be damaged by electrostatic discharges. Observe correct procedures for handling CMOS components. It is also recommended to store the circuit boards in electrostatic-proof cases.

Pull the main board out of the housing and disconnect the power supply and the sensor connectors.

Mounting Procedure

WARNING

Do not assemble with power on.

Sensor

When mounting the sensor, make use of a new set of o-rings compatible with the process fluid. The bolts, nuts, flanges and other parts should be inspected for corrosion or other eventual damage. Damaged parts should be replaced.

The O-rings should be lightly lubricated with silicon oil before they are fitted into place. Use halogen grease on applications having inert filling fluid. The flanges must be positioned on a flat surface. Insert the o-rings in the sensor. Set the four bolts and nuts initially with manual tightening, keeping the flanges in parallel through the whole mounting and finalize with an adequate tool, remembering to tighten them crosswise.

O'RINGS AND BACKUP RINGS FOR HIGH PRESSURE

Except for special cases, the new standard flanges do not use parbak. For specials that still use it, proceed as follows:

Do not bend the parback ring and check that it has no biting. Mount it carefully. The flat side must press the o-ring in the mounting.

Procedure for tightening the flange screws

- Tighten one nut till the flange seats;
- Tighten the nuts diagonally across with a torque of approximately 2.75 ±0.25 Kgf.m;
- Tighten the first nut with the same torque;
- Verify the flanges alignment;
- Check torque on the four bolts.

Should the adapters be removed, it is recommended to replace o-rings and to connect the adapters. Optimum torque is 2.75 ± 0.25 Kgf.m.

The fitting of the sensor must be done with the main board out of the electronic housing. Mount the sensor to the housing turning it clockwise until it stops. Then turn it counterclockwise until the cover is parallel to the process flange. Tighten the screw to lock the sensor.

Electronic Circuit

Plug sensor connector and power supply connector to main board. If there is a display, attach it to the main board by means of 4 screws (3). The display can be installed in any of the 4 possible positions (See next Figure).

The "A" mark indicates up position.

Pass the screws through the main board holes and the spacers as shown on Figure 5.2 and tighten them to the housing.

After tightening the protective cover (1), mounting procedure is complete. The transmitter is ready to be energized and tested. It is recommended that adjustment be done on the ZERO TRIM and on the UPPER PRESSURE TRIM.

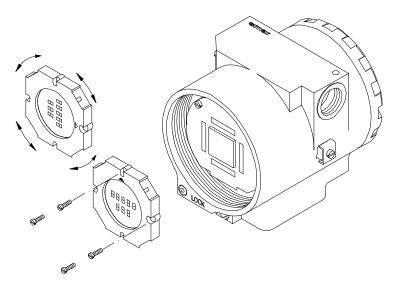


Figure 5.2 – Four Possible Positions of the Display

Interchangeability

In order to obtain an accurate and better temperature compensated response, the sensor data must be transferred to the EEPROM of the main board. This is done automatically when the transmitter is powered.

The main circuit, in this operation, reads the sensor serial number and compares it with the number stored in the main board. In case they do not match, the circuit considers that the sensor has been changed and will search in the new sensor memory for the following information:

- ✓ Temperature compensation coefficients.
- ✓ Sensor trim data, including characterization curve.
- ✓ Sensor characteristics: type, range, diaphragm material and fill fluid.

Information not transferred during sensor replacement will remain unchanged in the main board memory. Thus, information such as Upper Value, Lower Value, Damping, Pressure Unit and replaceable transmitter parts (Flange, O-ring, etc.) shall be updated, depending on whether the correct information is that of the sensor or the main board. In the case of a new sensor, the main board will have the most updated information; in the opposite case, the sensor will have the correct information. Depending on the situation, the updating shall be from one or the other.

Data transference from the main board to the sensor or vice versa can also be forced by function BACKUP/RESTORE of the sensor, respectively.

Returning Materials

Should it become necessary to return the transmitter and/or configurator to SMAR, simply contact our office, informing the defective instrument serial number, and return it to our factory.

In order to speed up analysis and solution of the problem, the defective item should be returned with the Service Request Form (SRF – Appendix B) properly filled with a description of the failure observed and with as much details as possible. Other information concerning to the instrument operation, such as service and process conditions, is also helpful.

Instruments returned or to be revised outside the guarantee term should be accompanied by a purchase order or a quote request.

Application with Halar

Technical Specification

Halar® is chemically one of the most resistant fluoropolymer. It is a thermoplastic of the melting process manufactured by Solvay Solexis, Inc. For its chemical structure, a 1:1 alternating ethylene copolymer and chlorinetrifluoroethylene, Halar® (ECTFE) offers an only combination of useful properties.

The diaphragms in 316L Stainless Steel covered with Halar®, are ideal for applications in contact with aggressive liquids. They offer excellent resistance to the chemic and abrasion with a wide temperature range. Halar® does not contaminate liquids of high purity and it is not affected by most of corrosive chemists, usually found in the industries, including strong minerals, oxidant acids, alkalis, liquid oxygen and some organic solvents.

Halar® is trademark of Solvay Solexis, Inc.

TPE - Total Probable Error (Software)

Software to calculate the assembly error of the Pressure Transmitters with the possible connections to the process.

TPE was developed to a fast and effective aid of the products related the pressure measurement. The users are the Applications Engineer and Commercial Areas. The customer can request a report of performance estimate to Smar.

This product allows doing simulations of possible assemblies, verifying important data as the error estimates of the response time, capillary length analysis and diaphragms mechanical resistance with temperature variation. See an example in the next Figure.

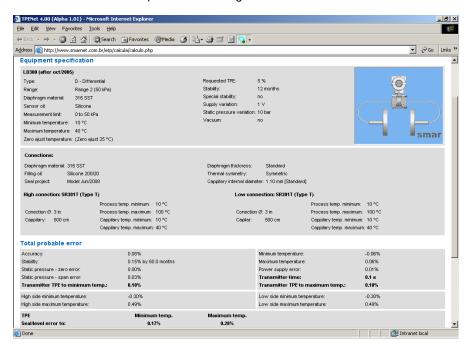


Figure 5.3 - TPE Software Screen

Use of Manifolds - Transmitter Operational Safety

Importance of using manifolds

- Use of manifolds increases safety in maintenance maneuvers on transmitters;
- Following the indicated procedures, it avoids maneuvers that can cause overpressure in differential transmitters;
- When necessary, complementary operational actions must be implemented.

2-Way Manifold



Operation

- Usually used to measure gauge or absolute pressure in which the fluid is drained through the manifold drain screw;
- During normal operation, the line valve must be opened and the drain valve closed;
- In case of dangerous, toxic, and corrosive fluids, high temperature, high pressure, etc., it is recommended to connect the drain outlet pipe, when it exists, directing the fluid to a safe place.

Maintenance

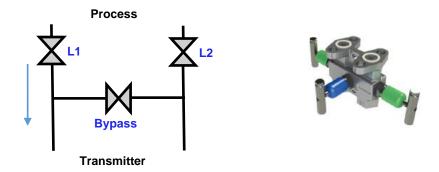
Start of operation - mounting the transmitter to the manifold

- Initial positions: L1 valve closed and D1 valve opened;
- Mount the transmitter on the manifold;
- Close D1 valve;
- · Open L1 valve.

Removing the transmitter or zero adjustment

- Close the L1 valve;
- Open valve D1, making sure that all liquid fluid has drained;
- Set the zero or remove the transmitter;
- Return the instrument to operation following the steps for starting the operation.

3-Way Manifold



Operation

- Usually used for differential pressure measurement;
- During normal operation, both L1 and L2 valves must be opened and the Bypass valve closed:
- It has a disadvantage that there are no drain valves, so it is recommended the use of transmitters with drain screws. The risk of handling hazardous fluids must be considered.

Maintenance

Start of operation - mounting the transmitter to the manifold

- Initial positions: L1 and L2 valves closed and Bypass valve opened;
- Mount the transmitter on the manifold;
- Make sure that the drain screws of the transmitter are closed;
- Open L2 valve;
- Close Bypass valve;
- Open L1 valve.

Removing the transmitter or zero adjustment (without static pressure)

NOTE

This procedure is recommended for non-high static pressures.

- Close L1 valve;
- Open Bypass valve;
- Close L2 valve;
- If the transmitter has drains, open them to atmosphere;
- Set the zero or remove the transmitter;
- Return the instrument to operation following the steps for starting the operation.

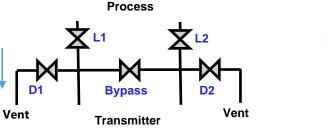
Removing the transmitter or zero adjustment (with static pressure)

NOTE

This procedure is recommended when you want to compensate the deviation caused by static pressure.

- Close L1 valve;
- Open Bypass valve;
- · Set the zero or remove the transmitter;
- Return the instrument to operation following the steps for starting the operation.

5-Way Manifold





Operation

- Usually used to measure differential pressure in which the fluid is drained through the manifold drain screws;
- During normal operation, both line valves must be opened, the Bypass valve and both drain valves must be closed;

 In case of dangerous, toxic, and corrosive fluids, high temperature, high pressure, etc., it is recommended to connect the drain outlet pipe, when it exists, directing the fluid to a safe place.

Maintenance

Start of operation - mounting the transmitter to the manifold

- Initial positions: L1 and L2 valves closed, Bypass valve opened, and D1 and D2 opened;
- Mount the transmitter on the manifold;
- Close the D1 and D2 drain valves;
- Open L2 valve;
- Close Bypass valve;
- Open L1 valve.

Removing the transmitter or zero adjustment (without static pressure)

NOTE

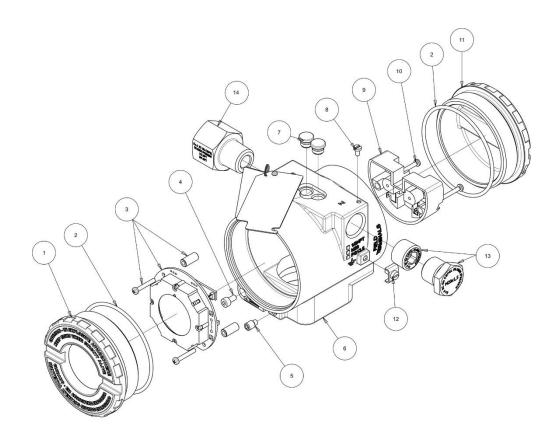
This procedure is recommended for non-high static pressures.

- This procedure **does not take into account** static pressure compensation;
- Close L1 valve;
- Open Bypass valve;
- Close L2 valve;
- Open D1 and D2 valves, making sure that all liquid fluid has drained;
- Set the zero or remove the transmitter;
- Return the instrument to operation following the steps for starting the operation.

Removing the transmitter or zero adjustment (with static pressure)

- Adjust zero;
- Close L1 valve;
- Open Bypass valve;
- Close L2 valve;
- Keep both vent valves closed;
- Set the zero of the transmitter;
- Return the instrument to operation following the steps for starting the operation.

Spare parts



The letters x, after the codes indicate continuation, see complete code in the manual.

14	1	3/4NPT AISI316 adapter BR-Exd 400-0812					
13	1	PG13.5 plug AISI 316 400-0811					
13	1	M20x1,5 plug AISI 316 BR-EXD	400-0810				
13	1	1/2NPT plug AISI316 BR-EXD	400-1484				
12	1	ground screw	204-0124				
11	1	cover without window	400-1307-0xx				
10	1	terminal block insulator screw	204-0119				
9	1	terminal block insulator	400-0058				
8	1	identitification plate screw 204-0116					
7	2	local adjust (Z e S) cover 204-0114					
6	1	Electronic Housing	400-1314-1xxxxxx				
5	1	sensor lock screw	400-1121				
4	2	cover lock screw	204-0120				
3	1	etectronic board	Note				
2	1	cover oring 204-0122					
1	1	cover with window 400-1307-1xx					
ТЕМ	QTY	DESCRIPTION	CODE				

Figure 5.4 - Exploded View

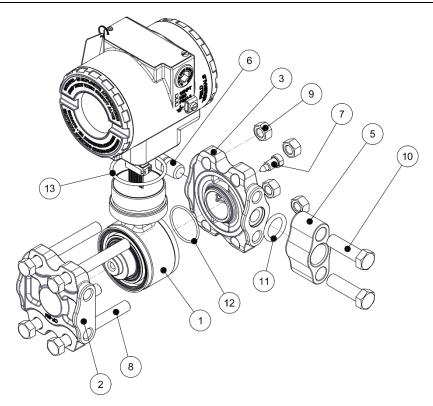
ITEM 3 NOTE

Go to www.smar.com.br/en/support

In general support, check for compatibility note and refer to the document.

ITEM 13 NOTE

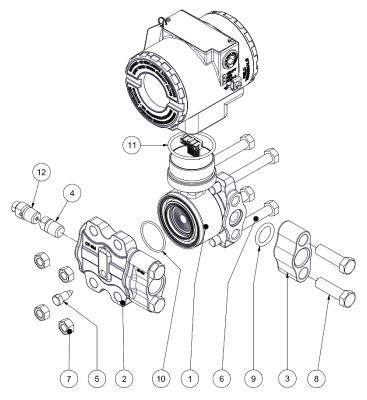
The spare part 400-1484, Internal Hexagonal Plug 1/2" NPT SST316 BR-Ex-d, was standardized in SST316 material and will be used in all line of housings (aluminum, copper free aluminum or SST316). With or without INMETRO certificate.



the campanula ID 4 only used in absolute model, welded on the sensor. the letter "x" in codes, see complete code in manual. The part numbers of electronic housing are in other figure

13	1	oring sensor / housing buna N	204-0113			
12	1	oring sensor etileno 203-0404				
12	1	oring sensor teflon 203-0403				
12	1	oring sensor viton 203-0402				
12	1	oring sensor buna N	203-0401			
11	1	oring adapter etileno	203-0704			
11	1	oring adapter teflon	203-0703			
11	1	oring adapter viton	203-0702			
11	1	oring adapter buna N	203-0701			
10	2	Adapter's screw SS316	203-0351			
10	2	Adapter's screw carbon steel bicromatized	203-0350			
9	4	Flange's Nut SS316	203-0312			
9	4	Flange's Nut carb bicromatized	203-0302			
8	4	Flange's screw SS316	203-0310			
8	4	Flange's screw carbon steel bicromatized	203-0300			
7	1	Drain Screw Monel	203-1403			
7	1	Drain Screw Hastelloy 203-1402				
7	1	Drain Screw SS 316 203-1401				
6	1	Plug 1-4NPT monel 203-0554				
6	1	Plug 1-4NPT hastelloy	203-0553			
6	1	Plug 1-4NPT SS 316	203-0552			
5	1	Adapter 1/2NPT monel 400 bar	203-0604			
5	1	Adapter 1/2NPT HS CW-12MW (hast)	203-0603			
5	1	Adapter 1/2NPT SS CF-8M (316)	203-0602			
5	1	Adapter 1/2NPT carbon steel	203-0601			
3	1	Differential Flange	400-1330-xxx			
2	1	Absolute/Gage Flange SS	204-1102			
1	1	Gage Sensor (without campanula)	204-0301-M-xxx			
1	1	Absolute Sensor	204-0301-A-xxx			
ITEM	QTY	DESCRIPTION	CODE			
			1			

Figure 5.5 – Manometric/Absolute Mounting LD301M



The letters x after codes see complete code in manual the parbak rings 203-0710 are use only flanges with sealing 45°, This new version use radial sealing, not use parbak rings.

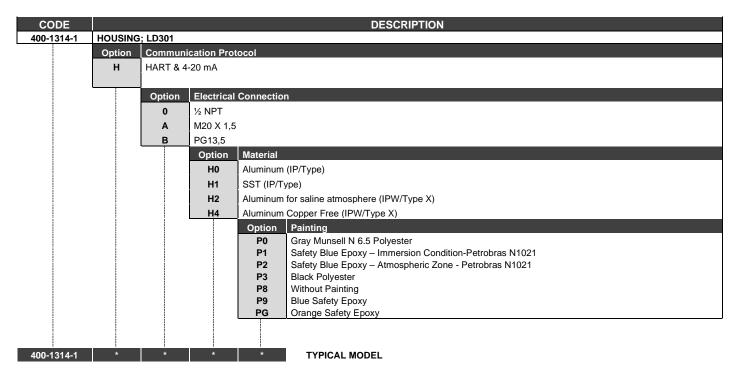
A drain valve can be used with flanges without drain, in place of 1/4NPT plug.

12	1	drain valve monel	400-0794				
12	1	drain valve hastelloy 400-0793					
12	2	drain valve SS 316	400-0792				
11	1	oring sensor / housing buna N 204-0113					
10	2	oring sensor etileno 203-0404					
10	2	oring sensor teflon	203-0403				
10	2	oring sensor viton	203-0402				
10	2	oring sensor buna N	203-0401				
9	1	oring adapter etileno	203-0704				
9	2	oring adapter teflon	203-0703				
9	2	oring adapter viton	203-0702				
9	2	oring adapter buna N	203-0701				
8	4	Adapter's screw SS316	203-0351				
8	4	Adapter's screw carbon steel bicromatized	203-0350				
7	4	Flange's Nut SS316	203-0312				
7	4	Flange's Nut carb bicromatized 203-0302					
6	4	Flange's screw SS316 203-0310					
6	4	Flange's screw carbon steel bicromatized 203-0300					
5	2	Drain Screw Monel 203-1403					
5	2	Drain Screw Hastelloy	203-1402				
5	4	Drain Screw SS 316	203-1401				
4	2	Plug 1-4NPT monel	203-0554				
4	2	Plug 1-4NPT hastelloy	203-0553				
4	2	Plug 1-4NPT SS 316	203-0552				
3	2	Adapter 1/2NPT monel 400 bar	203-0604				
3	2	Adapter 1/2NPT HS CW-12MW (hast)	203-0603				
3	2	Adapter 1/2NPT SS CF-8M (316)	203-0602				
3	2	Adapter 1/2NPT carbon steel	203-0601				
2	2	differential Flange Standard	400-1330-xxx				
1	1	Sensor	204-0301-Dxxxxx				
ITEM	QTY	DESCRIPTION	PART NUMBER				

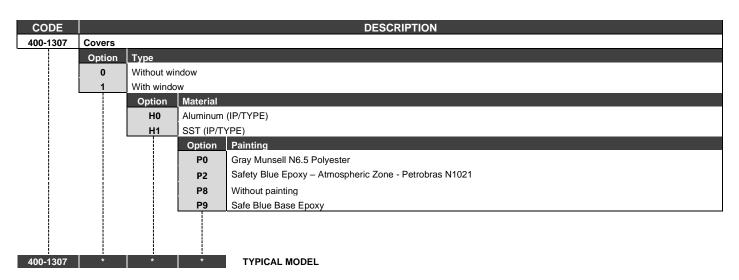
Figure 5.6 – Differential Mounting LD301D

ACCESSORIES							
ODERING CODE	DESCRIPTION						
SD-1	Magnetic Tool for local adjustment.						
DEVCODROID	Uses DDs to access the data stored in memory and configure the HART equipment.						
HPI311*	HART® interface.						

Detailed Code for Ordering Spare Parts



^{*}Select the desired option



^{*}Select the desired option

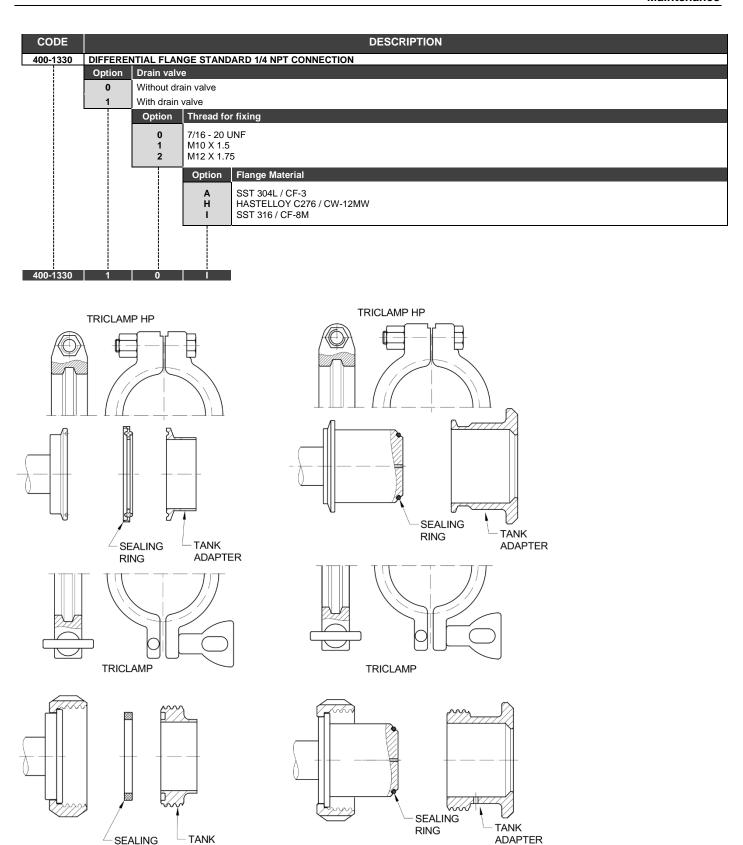
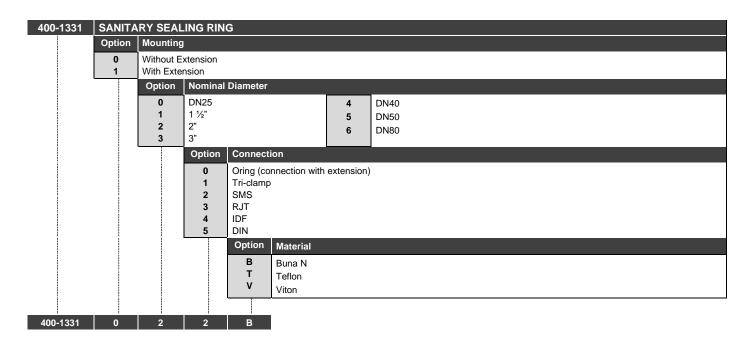
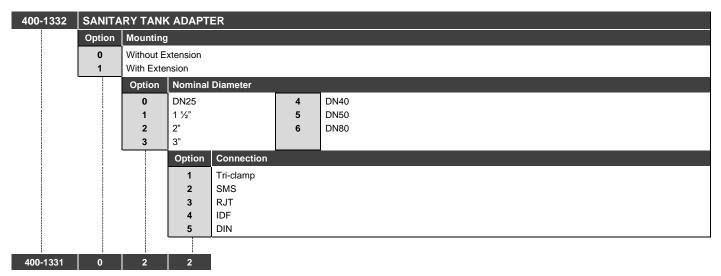


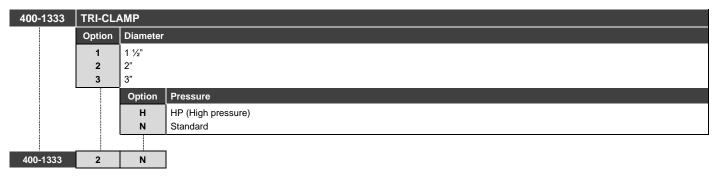
Figure 5.7 – Sanitary Connections

ADAPTER

RING







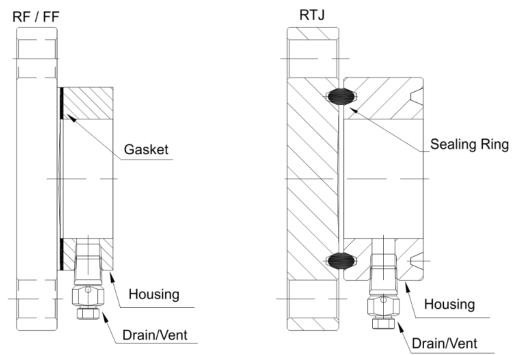


Figure 5.8 – Gaskets, RTJ rings and housings

400-1337	SEALING GASKET FOR FLANGE ASME/DIN – FACE RF-FF (PACKAGE WITH 10 UNITS);										
	Option	Diameter	Diameter								
	1	1" (ASME)	6	DN25 (DIN)						
	2	1 1/2" (AS	ME)	7	DN40 (DIN)						
	3	2" (ASME)	8	DN50 (DIN)						
	4	3" (ASME)	9	DN80 (DIN)						
	5	4" (ASME)	Α	DN100 (DIN)						
		Option	Material								
		G	Grafoil								
		Т	Teflon								
400-1337	3	Т									

Drain Valve (Plug 1/4 NPT + Vent screw)						
400-0792	SST AISI 316L					
400-0793	Hastelloy C276					
400-0794	Monel 400					

RTJ SPARE PARTS (ASME B 16.20)						
ØN	CLASS	RING	METALLIC RING			
MIN	CLASS	KING	SST 316L			
	150	R15	400-0887			
	300	R16	400-0888			
1"	600	R16	400-0888			
	1500	R16	400-0888			
	2500	R18	400-0889			
	150	R19	400-0890			
	300	R20	400-0891			
1.1/2"	600	R20	400-0891			
	1500	R20	400-0891			
	2500	R23	400-0893			
	150	R22	400-0892			
	300	R23	400-0893			
2"	600	R23	400-0893			
	1500	R24	400-0894			
	2500	R26	400-0895			
	150	R29	400-0896			
3"	300	R31	400-0897			
	600	R31	400-0897			
	150	R36	400-0900			
4"	300	R37	400-0901			
	600	R37	400-0901			

Table 5.3 - LD301L - Spare parts codes for SST gasket (without extension)

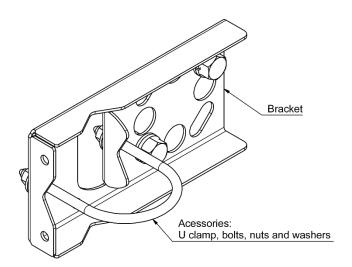
400-0258	HOUSI	NG OF	IG OF FLANGED REMOTE SEAL						
	CODE	Size							
	1	1" ASME B16.5			6	DN25 DIN EN 1092-1			
		1.1/2" ASME B16.5			7	DN40 DIN EN 1092-1			
	_	2" ASMI			8	DN50 DIN EN 1092-1			
		3" ASMI			9	DN80 DIN EN 1092-1			
	5	4" ASMI			Α	DN100 DIN EN 1092-1			
		CODE	Pressur						
		0		ary With F		Class		3	600 # ASME B-16.5
		1		SME B-16.				4	1500 # ASME B-16.5
		2 300 # ASME B-16						5	2500 # ASME B-16.5
	CODE Housing			Material					
				SST 316					
				Hastelloy					
				Super Du					
			4	Duplex (L					
CODE			CODE	Gasket N	sket Material				
					Without (Gasket _T	-	Teflor	on.
				_	Grafoil	'		CIIOI) ii
				l i	SST 316	L			

Special	Options									
CODE	Size									
ZZ	See note	s								
	CODE	Housing	Connection							
	G0	WITH 1 1	1/4" NPT FLUSH CONNECTION (IF SUPPLIED WITH HOUSING)							
	G1	WITH 2 1	//4" NPT TO 180 DEGREES FLUSH CONNECTIONS							
	G3	WITH 2 1	WITH 2 1/2"- 14 NPT TO 180 DEGREES CONNECTIONS (WITH PLASTIC PLUG)							
	G5	WITH 11	WITH 1 1/2" NPT FLUSH CONNECTION							
		CODE	CODE Face							
		H0	H0 Grooved Face RF FF (ASME, DIN) (1)							
		H2	Flat Face With Sealing Channel - RTJ (ASME B 16.20) (1)							

400-0258 1

Note

(1) Only housing RTJ face vary by pressure class. RF and FF do not vary with the flange pressure class.



PART NUMBER	DESCRIPTION
203-0801	CARBON STEEL BRACKET AND ACESSORIES
203-0802	STAINLESS STEEL BRACKET AND ACESSORIES
203-0803	CARBON STEEL BRACKET AND SS ACESSORIES

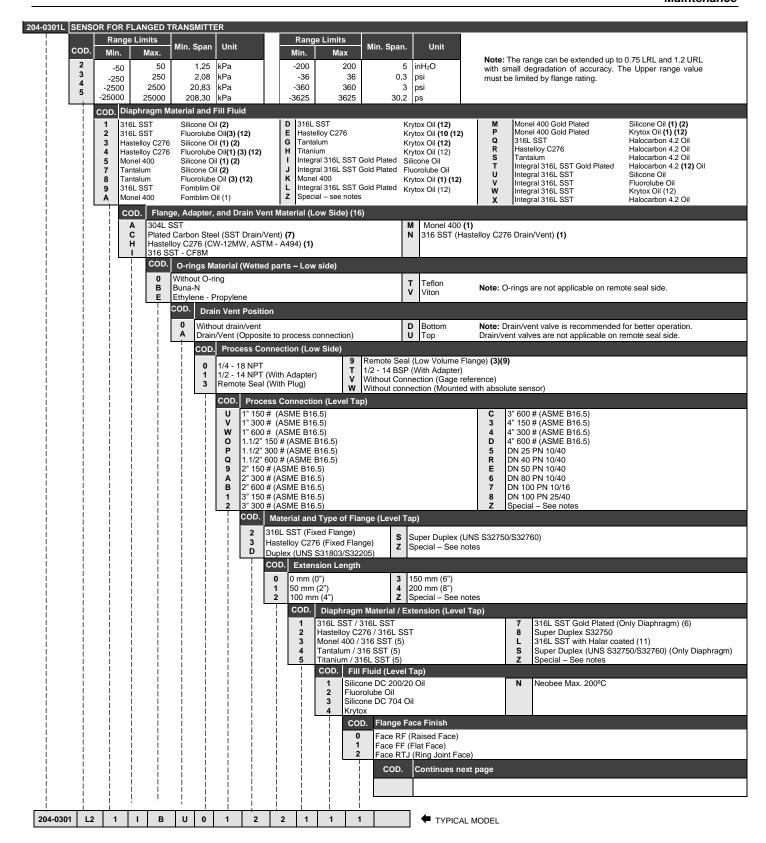
Figure 5.9 – Flat Bracket LD301

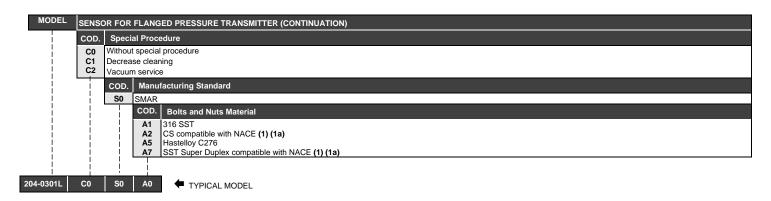
Ordering Code for the Sensor

	Turne	Range	Limits	Min.	Unit	Range	Limits	Min.	Unit	
COD	туре	Min.	Max.	Span	Unit	Min.	Max.	Span	Unit	
D0	Differential and Flow	-1	1	0.05	kPa	-4	4	0,05	inH ₂ O	
D1	Differential and Flow	-5	5	0.10	kPa	-20	20		inH ₂ O	NOTE: The range can be extended up to 0. LRL* and 1.2 URL* with small degradation
D2 D3	Differential and Flow Differential and Flow	-50 -250	50 250	0.42 2.08	kPa kPa	-200 -36	200 36	0,42 2,08	inH₂O psi	accuracy.
D3	Differential and Flow	-2500	2500	20.83	kPa	-360	360		psi	For range 6, the pressure range above URL m
MO	Gage	-1	1	0.05	kPa	-4	4		inH ₂ O	be assessed according to the maximum press
M1	Gage	- 5	5	0.10	kPa	-20	20		inH ₂ O	approved in the competent hazardous as
M2	Gage	- 50	50	0.42	kPa	-200	200	0,42	inH ₂ O	certification.
М3	Gage	-100	250	2.08	kPa	-14,5	36	2,08	psi	*LRL = Lower Range Limit.
M4	Gage	-100	2500	20.83	kPa	-14,5	360		psi	*URL = Upper Range Limit.
M5	Gage	- 0.1	25	0.21	Mpa	-14,5	3600	0,21	psi	
M6	Gage	- 0.1	40	0.33	Мра	-14,5	5800		psi	
A1	Absolute	0	5	2.00	kPa	0	20		inH ₂ O	
A2	Absolute	0	50	2.50	kPa	0	200	2,50	inH ₂ O	
A3 A4	Absolute	0	250	5.00	kPa	0	36	5,00	psi	
A4 A5	Absolute Absolute	0	2500 25	20.83 0.21	kPa Mpa	0	360 3600	20,83 0,21	psi psi	
A6	Absolute	0	40	0.21	Мра	0	5800		psi	
		-	-			-200	200		inH ₂ O	
H2 H3	Differential – High Static Pressure Differential – High Static Pressure	-50 -250	50 250	0.42 2.08	kPa kPa	-36	36	0,42 2,08	psi	
нз Н4	Differential – High Static Pressure	-2500	2500	20.83	kPa	-360	360	20,83	psi	
	Differential – High Static Pressure	-25	25	0.21	Мра	-3600	3600		psi	
	ÿ							,		
į	COD. Diaphragm Material and Fill Fluid									
-	1 316 SST Silicone Oil		Α	Monel 40		Fomblim C				Gold Plated Krytox Inert Oil (1) (3) (5)
į	2 316 SST Fluorolube			316L SS		Krytox Ine			16 SST	Halocarbon 4.2 Inert Oil (2) (3) (5)
ļ	3 Hastelloy C276 Silicone Oil		E	Hastello		Krytox Ine				
i	4 Hastelloy C276 Fluorolube		. , , ,	Hastello	•	Silicone Oi	. , . ,		antalum	Halocarbon 4.2 Inert Oil (2) (3) (5)
- !	5 Monel 400 Silicone Oil		G	Tantalun		Krytox Ine				ntegral Plate Silicone Oil
-	7 Tantalum Silicone Oil		1		T Gold Plated	Silicone Oi				ntegral Plate Fluorolube Inert Oil
!	8 Tantalum Fluorolube			Monel 40					16L SST II	ntegral Plate Krytox Inert Oil
ł						Silicone Oi	1 (1) (3) (4)		
į	COD Special Procedure									
- 1	C0 Standard									
i	C1 For use in oxygen / hydrog									
	C6 Test of Overpressure at 38	80 bar and s	tatic pres	sure at 48	0 bar (6)					
i										
- 1	i									

NOTES

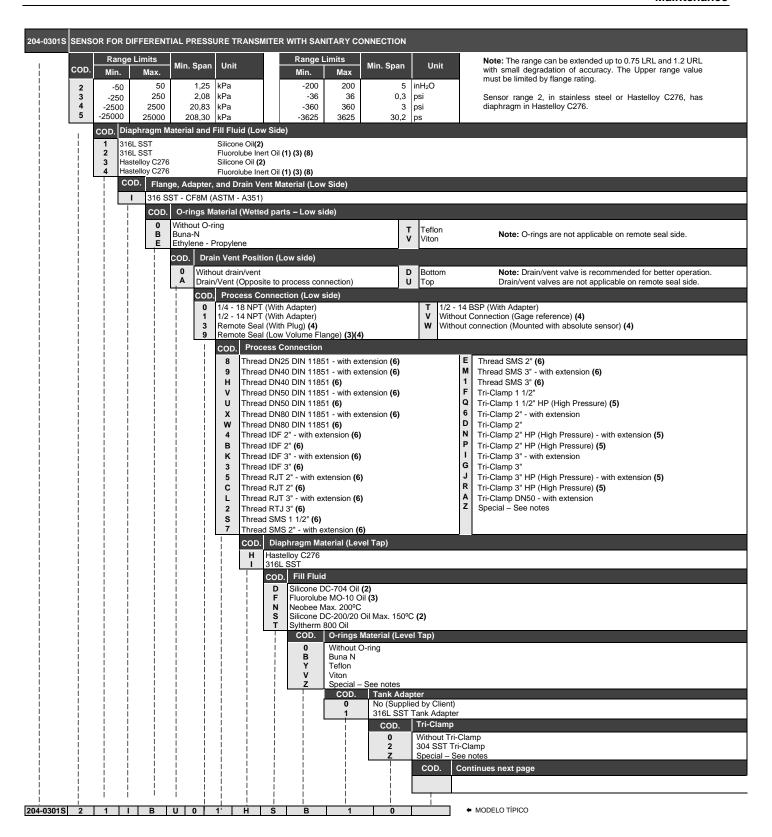
- (1) Meets NACE MR 01 75/ISO 15156 recommendations.
- (2) Not available for absolute models nor for vacuum applications.
- (3) Not available for range 0 and 1.
- (4) Silicone Oil is not recommended for oxygen (O2) or Chlorine service.
- (5) Inert Fluid: Oxygen Compatibility, safe for oxygen service.
- (6) Available only for H Class.

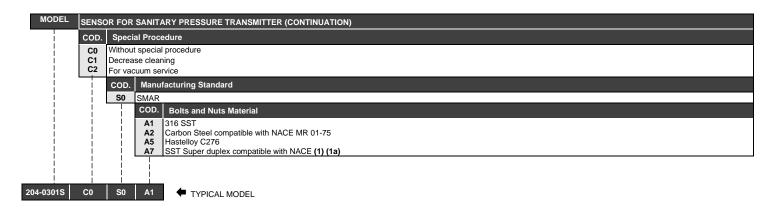




NOTES

- (1) Meets NACE MR-0175 / ISO15156 standard.
- (1a) Meets NACE MR-0103
- (2) Silicone Oil is not recommended for Oxygen (O2) or Chlorine service.
- (3) Not applicable for vacuum service.
- (4) Fluorolube fill fluid is not available for Monel diaphragm.
- (5) Attention, check the corrosion rate for the process, extension AISI 316L thickness 3-6mm. Titanium, Monel, and Tantalum diaphragm thickness 0.1 mm.
- (6) Item by inquiry.
- (7) Not applicable for saline atmosphere.
- (8) Degreaser's cleaning is not available for carbon steel flanges.
- (9) Drain/Vent not applicable.(10) Finishing of the flange faces according to specific standards.
- (11) Applicable only to:
 - Diameter/capillary length:
 - 2" ASME B 16.5 DN 50 DIN, JIS 50 A, for seals up to 3 meters of capillary and level models (by inquiry).
 - 3" ASME B 16.5 DN 80 DIN, JIS 80 A, for seals up to 5 meters of capillary and level models.
 - 4" ASME B 16.5, DN 100 DIN, JIS 100 A, for seals up to 8 meters and level models.
 - Faces: RF and FF;
 - Temperature Range: +10 °C to 100 °C
 - + 101 to 150 ° C (by inquiry)
 - Not applicable for use with gasket.
- (12) Inert Fluid is safe for oxygen service.





NOTES

- (1) Meets NACE MR-0175 / ISO15156 standard.
- (1a) Meets NACE MR-0103 (2) Silicone Oils not recommendations for Oxygen (O₂) or Chlorine service.
- (3) Not applicable for vacuum service.(4) Drain/Vent not applicable.

- (5) HP High Pressure.
 (6) Not available for tri-clamp connections.
- (7) Item by inquiry
- (8) Inert Fluid: safe for oxygen service.

HART® Special Units

VARIABLE	CODE	UNIT	DESCRIPTION				
	1	inH₂O (68°F)	inches of water at 68 degrees F				
	2	inHg (0°C)	inches of mercury at 0 degrees C				
	3	ftH ₂ O (68°F)	feet of water at 68 degrees F				
	4	mmH₂O	millimeters of water at 68 degrees F				
	5	(68°F) mmHg (0°C)	millimeters of mercury at 0 degrees C				
	6	lb/in²					
	7	bar	pounds per square inch bars				
	8	mbar	millibar				
	9	gf/cm ²	Gram force per square centimeter				
PRESSURE	10	kgf/cm ²	Kilogram force per square centimeter				
	11	Pa	pascal				
	12	kPa	kilopascal				
	13	torr	torr				
	14	atm	atmosphere				
	145	inH ² O (60°F)	inches of water at 60 degrees F				
	237	MPa	megapascal				
	238	inH ² O (4°C)	inches of water at 4 degrees C				
	239	mmH ² O (4°C)	millimeters of water at 4 degrees C				
	15	CFM	,				
	16	GPM	cubic feet per minute				
	17	l/min	gallons per minute				
		ImpGal/min	liters per minute				
	18 19	m³/h	imperial gallons per minute				
	22	gal/s	cubic meters per hour				
	23	Mgal/d	gallons per second million gallons per day				
	24	I/s	liters per second				
	25	MI/d	million liters per day				
	26	ft³/s	cubic feet per second				
	27	ft³/d	cubic feet per day				
	28	m³/s	cubic meters per second				
	29	m³/d	cubic meters per day				
	30	ImpGal/h	imperial gallons per hour				
VOLUMETRIC FLOW	31	ImpGal/d	imperial gallons per day				
	121	Nm³/h	normal cubic meters per hour				
	122	NI/h	normal liters per hour				
	123	ft³/min	standard cubic feet per minute				
	130	CFH	cubic feet per hour				
	131	m³/h	cubic meters per hour				
	132	bbl/s	barrels per second				
	133	bbl/min	barrels per minute				
	134	bbl/h	barrels per hour				
	135	bbl/d	barrels per day				
	136	gal/h	gallons per hour				
	137	ImpGal/s	imperial gallons per second				
	138	l/h	liters per hour				
	235	gal/d	gallons per day				
<u> </u>	200		ganons per day				

Velocity	VARIABLE	CODE	UNIT	DESCRIPTION		
VELOCITY		20	ft/s	feet per second		
VELOCITY	-	21	m/s	meters per second		
115		114	in/s	inches per second		
TEMPERATURE	VELOCITY	115	in/min	inches per minute		
Temperature	-	116	ft/min	feet per minute		
Temperature	-	120	m/h	meters per hour		
Temperature		32	°C	degrees Celsius		
Second		33	٥F	degrees Fahrenheit		
Segres Revinition Segr	TEMPERATURE	34	٥R	degrees Rankine		
Second	-	35	K	degrees Kelvin		
Name	_	36	mV	millivolts		
RESISTANCE 163		58	V	volts		
VOLUME	ELECTRIC	37	ohm	ohms		
VOLUME	RESISTANCE	163	kohm	kilo ohms		
VOLUME		39	mA	milliamperes		
Volume		40	gal	gallons		
Volume	-	41	I	liters		
VOLUME		42	ImpGal	imperial gallons		
Volume		43	m ³	cubic meters		
VOLUME		46	bbl	barrels		
112 ft3 cubic feet		110	bushel	bushels		
112 113 113 113 113 114 114 115		111	yd³	cubic yards		
124 bbl(liq) liquid barrels	VOLUME	112	ft³	cubic feet		
166		113	in³	cubic inches		
167		124	bbl(liq)	liquid barrels		
167		166	Nm³	normal cubic meter		
Length		167	NI	normal liter		
A4		168	SCF	standard cubic feet		
Length 45		236	hl	hectoliters		
LENGTH		44	ft	feet		
LENGTH		45	m	meters		
48		47	in	inches		
Time	LENGTH	48	cm	centimeters		
Time		49		millimeters		
TIME		151	ftin ¹⁶	feet in sixteenths		
TIME		50	min	minutes		
52	T	51	s	seconds		
60 9 grams	TIME	52	h	hours		
61 kg kilograms 62 t metric tons		53	d	days		
MASS 62 t metric tons 63 lb pounds 64 Shton short tons (2000 pounds) 65 Lton long tons (2240 pounds)		60	g	grams		
Mass 63 lb pounds 64 Shton short tons (2000 pounds) 65 Lton long tons (2240 pounds)		61	kg	kilograms		
64 Shton short tons (2000 pounds) 65 Lton long tons (2240 pounds)		62	t	metric tons		
65 Lton long tons (2240 pounds)	Mass	63	lb	pounds		
long tons (2240 pounds)		64	Shton	short tons (2000 pounds)		
125 OZ ounce		65	Lton	long tons (2240 pounds)		
1		125	OZ	ounce		

VARIABLE	CODE	UNIT	DESCRIPTION		
	54	cSt	centistokes		
VISCOSITY	55	cР	centipoises		
	69	N-m	newton meter		
	89	decatherm	deka therm		
F	126	ft-lb	foot pound force		
ENERGY (INCLUDES	128	KWH	kilo watt hour		
Work)	162	Mcal	mega calorie		
	164	MJ	mega joule		
	165	Btu	british thermal unit		
	70	g/s	grams per second		
	71	g/min	grams per minute		
	72	g/h	grams per hour		
	73	kg/s	kilograms per second		
	74	kg/min	kilograms per minute		
	75	kg/h	kilograms per hour		
	76	kg/d	kilograms per day		
	77	t/min	metric tons per minute		
	78	t/h	metric tons per hour		
Mass Flow	79	t/d	metric tons per day		
	80	lb/s	pounds per second		
	81	lb/min	pounds per minute		
	82	lb/h	pounds per hour		
	83	lb/d	pounds per day		
	84	Shton/min	short tons per minute		
	85	Shton/h	short tons per hour		
	86	Shton/d	short tons per day		
	87	Lton/h	long tons per hour		
	88	Lton/d	long tons per day		
	90	SGU	specific gravity units		
	91	g/cm³	grams per cubic centimeter		
	92	kg/m³	kilograms per cubic meter		
	93	lb/gal	pounds per gallon		
	94	lb/ft³	pounds per cubic foot		
	95	g/ml	grams per milliliter		
	96	kg/l	kilograms per liter		
	97	g/l	grams per liter		
Mass per Volume	98	lb/in³	pounds per cubic inch		
. Clonic	99	ton/yd³	short tons per cubic yard		
	100	degTwad	degrees twaddell		
	102	degBaum hv	degrees Baume heavy		
	103	degBaum It	degrees Baume light		
	104	deg API	degrees API		
	146	μg/l	micrograms per liter		
	147	μg/m³	micrograms per cubic meter		
	148	%Cs	percent consistency		
l	1		1 .		

VARIABLE	CODE	UNIT	DESCRIPTION			
	117	°/s	degrees per second			
ANGULAR VELOCITY	118	rev/s	revolutions per second			
	119	RPM	revolutions per minute			
	127	kW	kilo watt			
	129	hp	horsepower			
Power	140	Mcal/h	mega calorie per hour			
	141	MJ/h	mega joule per hour			
	142	Btu/h	British thermal unit per hour			
	38	Hz	hertz			
	56	μS	micro siemens			
	57	%	percent			
	59	pН	pН			
	66	mS/cm	milli siemens per centimeter			
	67	μS/cm	micro siemens per centimeter			
	68	N	newton			
	101	degbrix	degrees brix			
	105	%sol/wt	percent solids per weight			
	106	%sol/vol	percent solids per volume			
	107	degBall	degrees balling			
	108	proof/vol	proof per volume			
MISCELLANEOUS	109	proof/mass	proof per mass			
	139	ppm	parts per million			
	143	0	degrees			
	144	rad	radian			
	149	%vol	volume percent			
	150	%stm qual	percent steam quality			
	152	ft³/lb	cubic feet per pound			
	153	pF	picofarads			
	154	ml/l	milliliters per liter			
	155	μl/l	microliters per liter			
	160	% plato	percent plato			
	161	LEL	percent lower explosion level			
	169	ppb	parts per billion			
	240 to 249	=	May be used for manufacturer specific definitions			
	to 249 250	-	Not Used			
GENERIC	251	-	None			
	252	-	Unknown			
	253	-	Special			
	200		Sp Solai			

 $\begin{tabular}{lll} \textbf{Note:} & Information & extracted & from & HART^{\$} & Protocol \\ Specification. & \end{tabular}$

Isolation Test on Equipment Housings

- 1. Power off the equipment in the field, remove its back cover and disconnect all field cables from the transmitter terminal block, isolating them safely.
- 2. It is not necessary to remove the main board and display.
- 3. Jumper (connect) the power terminals (positive and negative) with the cable coming from the Megohmmeter (megger).
- 4. Configure the megohmmeter for 500 Vdc scale and check the isolation between the housing and the cable that short-circuits all the terminals.

ATTENTION



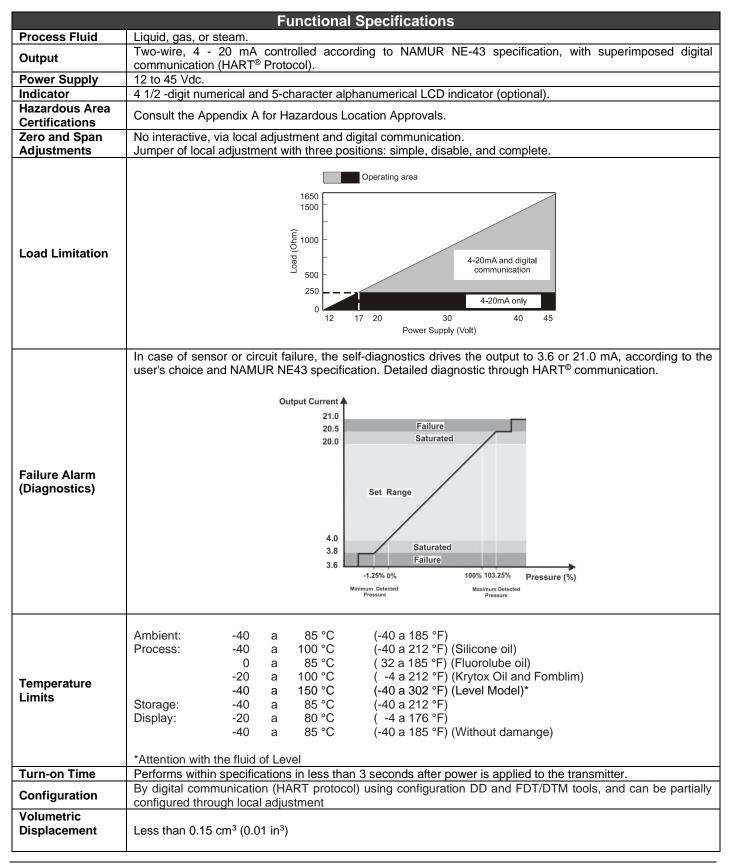
Never test with a voltage greater than 500 Vdc.

- 5. The value obtained must be greater than or equal to $2G\Omega$ and the voltage application time must be at least 1 second and at most 5 seconds.
- 6. If the value obtained by the megohmmeter is below $2G\Omega$, the possibility of moisture entering the electrical connection compartment must be analyzed.
- 7. It is possible to loosen the two screws that secure the terminal block to the housing and carry out a superficial cleaning and dry the surface well. Afterwards, the isolation can be tested again.
- 8. If the isolation test still shows that the isolation has been compromised, the housing must be replaced and sent to Nova Smar S.A. for analysis and retrieval.

IMPORTANT

- For equipment certified Exd and Exi (Explosion Proof and Intrinsically Safe) the standards advise not to carry out repairs in the field of the housing electronic components, only at Nova Smar S.A.
- In normal use, the housing components must not cause failures that affect its isolation. For this reason, it is important to verify whether there are traces of water entering the housing and, if so, an assessment of the electrical installations and the sealing rings of the covers must be carried out. Nova Smar S.A. has a team ready to support the assessment of facilities, if necessary.

TECHNICAL CHARACTERISTICS



	Functional Specifications										
Static Pressure Limits	70 psi (5 bar) for range 0 1200 psi (80 bar) for range 1 2300 psi (160 bar) for ranges 2, 3 and 4 4600 psi (320 bar) for models H2 to H5 Except for LD301A and LD301M models	Static pressure, in differential pressure measurement, is the pressure applied on both measuring chambers, simultaneously. For example, in flow measurement with restriction elements, the static pressure is the line pressure, present in both measuring chambers, simultaneously.									
Overpressure Limits	70 psi (5 bar) for range 0 1200 psi (80 bar) for range 1 2300 psi (160 bar) for ranges 2, 3 and 4 5800 psi (400 bar) for range 5 7500 psi (520 bar) for range 6 Flange Test Pressure (Burst Pressure): 68.95 MPa (1 Flange test is the maximum pressure applied to the transmitt Overpressures above will not damage the transmitter, Overpressure is the pressure applied to only one of the trans sensor's reading pressure limit (URL). The concept applies to	tter without damage to the measuring set. , but a new calibration may be necessary smitter chambers when this pressure is higher than the									

WARNING

It is described here only the maximum pressures of some materials referenced in each standard, other materials on request. Temperatures above 150 ° C are not available in standard models.

PRESSURES TABLE FOR SEAL AND LEVEL FLANGES DIN EN 1092-1 2008 STANDARD

		Maximum Temperature Allowed								
Material Group	Pressure Class	RT*	100	150	200	250	300	350		
Group	Olass		Maximum Pressure Allowed (bar)							
	PN 16	16	13.7	12.3	11.2	10.4	9,6	9.2		
	PN 25	25	21.5	19.2	17.5	16.3	15.1	14.4		
	PN 40	40	34.4	30.8	28	26	24.1	23		
10E0 AISI 304/304L	PN 63	63	54,3	48,6	44,1	41,1	38,1	36,3		
A101 304/304L	PN 100	100	86.1	77.1	70	65.2	60.4	57.6		
	PN 160	160	137.9	123.4	112	104.3	96.7	92.1		
	PN 250	250	215.4	192.8	175	163	151.1	144		

Pressure Limits for flanges

	Pressure Class	Maximum Temperature Allowed								
Material Group		RT*	100	150	200	250	300	350		
Cloup	Olass		Max	imum Pr	essure A	Allowed	(bar)			
	PN 16	16	16	14.5	13.4	12.7	11.8	11.4		
	PN 25	25	25	22.7	21	19.8	18.5	17.8		
	PN 40	40	40	36.3	33.7	31.8	29.7	28.5		
14E0 AISI 316/316L	PN 63	63	63	57.3	53.1	50.1	46.8	45		
AIGI 310/310E	PN 100	100	100	90.9	84.2	79.5	74.2	71.4		
	PN 160	160	160	145.5	134.8	127.2	118.8	114.2		
	PN 250	250	250	227.3	210.7	198.8	185.7	178.5		

	_	Maximum Temperature Allowed							
Material Group	Pressure Class	RT*	100	150	200	250	300	350	
Group	Class	Maximum Pressure Allowed (bar)							
	PN 16	16	16	16	16	16	-	-	
4050	PN 25	25	25	25	25	25	-	-	
16E0 1.4410 Super	PN 40	40	40	40	40	40	-	-	
Duplex	PN 63	63	63	63	63	63	-	-	
1.4462	PN 100	100	100	100	100	100	-	-	
Duplex	PN 160	160	160	160	160	160	-	-	
	PN 250	250	250	250	250	250	-	-	

^{**}RT = Reference Temperature (-10 to 50 °C)

Functional Specifications PRESSURES TABLE FOR SEAL AND LEVEL FLANGES ASME B16.5 2017 STANDARD

		Maximum Temperature Allowed											
Material Group	Pressure Class	-29 to 38	50	100	150	200	250	300	325	350			
		Maximum Pressure Allowed (bar)											
	150	20	19.5	17.7	15.8	13.8	12.1	10.2	9.3	8.4			
	300	51.7	51.7	51.5	50.3	48.3	46.3	42.9	41.4	40.3			
Hastelloy	600	103.4	103.4	103	100.3	96.7	92.7	85.7	82.6	80.4			
C276	1500	258.6	258.6	257.6	250.8	241.7	231.8	214.4	206.6	201.1			
	2500												
		430.9	430.9	429.4	418.2	402.8	386.2	357.1	344.3	335.3			

				Max	imum T	emperat	ure Allo	wed		
Material Group	Pressure Class	-29 to 38	50	100	150	200	250	300	325	350
				Maxi	mum Pr	essure A	Allowed	(bar)		
S31803	150	20	19.5	17.7	15.8	13.8	12.1	10.2	9.3	8.4
Duplex	300	51.7	51.7	50.7	45.9	42.7	40.5	38.9	38.2	37.6
S32750	600	103.4	103.4	101.3	91.9	85.3	80.9	77.7	76.3	75.3
Super	1500	258.6	258.6	253.3	229.6	213.3	202.3	194.3	190.8	188.2
Duplex	2500	430.9	430.9	422.2	382.7	355.4	337.2	323.8	318	313.7

Pressure Limits for flanges

				Max	imum T	emperat	ure Allo	wed		
Material Group	Pressure Class	-29 to 38	50	100	150	200	250	300	325	350
				Maxi	mum Pr	essure A	Allowed	(bar)		
AISI316L	150	15.9	15.3	13.3	12	11.2	10.5	10	9.3	8.4
AISISTOL	300	41.4	40	34.8	31.4	29.2	27.5	26.1	25.5	25.1
	600	82.7	80	69.6	62.8	58.3	54.9	52.1	51	50.1
	1500	206.8	200.1	173.9	157	145.8	137.3	130.3	127.4	125.4
	2500	344.7	333.5	289.9	261.6	243	228.9	217.2	212.3	208.9

				Max	imum T	emperat	ure Allo	wed		
Material Group	Pressure Class	-29 to 38	50	100	150	200	250	300	325	350
				Maxi	mum Pr	essure A	Allowed	(bar)		
AISI316	150	19	18.4	16.2	14.8	13.7	12.1	10.2	9.3	8.4
AISISTO	300	49.6	48.1	42.2	38.5	35.7	33.4	31.6	30.9	30.3
	600	99.3	96.2	84.4	77	71.3	66.8	63.2	61.8	60.7
	1500	248.2	240.6	211	192.5	178.3	166.9	158.1	154.4	151.6
	2500	413.7	400.9	351.6	320.8	297.2	278.1	263.5	257.4	252.7

				Max	imum T	emperat	ure Allo	wed		
Material Group	Pressure Class	-29 to 38	50	100	150	200	250	300	325	350
				Maxi	mum Pr	essure A	Allowed	(bar)		
	150	19	18.3	15.7	14.2	13.2	12.1	10.2	9.3	8.4
	300	49.6	47.8	40.9	37	34.5	32.5	30.9	30.2	29.6
AISI304	600	99.3	95.6	81.7	74	69	65	61.8	60.4	59.3
	1500	248.2	239.1	204.3	185	172.4	162.4	154.6	151.1	148.1
	2500	413.7	398.5	340.4	308.4	287.3	270.7	257.6	251.9	246.9

PRESSURES TABLE FOR SEAL AND LEVEL FLANGES JIS 2220 – 2012 STANDARD

Material	Draggura	Max	ximum Temp	erature Allowed	i
Group	Pressure Class	Tamb at 120°	220°	300°	350°
Group	Class	Max	imum Pressເ	ire Allowed (ba	r)
	10k	14	12	10	
AISI316L	20k	34	31	29	26
	40k	68	62	57	52

		Functiona	l Specification:	S	
		PRESSURES TABL			S4825 P3
		PN no	ormal	HP High	Pressure
	DN	20°C (68°F)	120°C (248°F)	20°C (68°F)	120°C (248°F)
			Maximum Pressu	ıre Allowed (bar)	
	1.1/2"	34	20	100	60
	2" - DN50	28	17	70	42
	3"	22	13	70	42
ressure Limits or sanitary onnections		PRESSURES	TABLE FOR THRE	ADED CONNECTION	ONS
		Sanitary Ti	hreads – Temperat	ure Limits	
		RJT	IDF	SMS	DIN
	DN	120°C (248°F)	120°C (248°F)	120°C (248°F)	120°C (248°F)
		BS4825 P5	BS4825 P4	SMS1145	DIN11851
			Maximum Pressu	ıre Allowed (bar)	
	DN25				40
	1.1/2"-DN40	10	16	40	40
	2-DN50	10	16	25	25
	3-DN80	10	16	25	25

	Performance Specifications
Reference	Span starting at zero, temperature of 25°C (77°F), atmospheric pressure, power supply of 24 Vcc, silicone
Conditions	oil fill fluid, isolating diaphragms in 316L SST and digital trim equal to lower and upper range values. For range 0, and differential or gage models and 316L SST or Hastelloy diaphragm with silicon or
	halocarbon filling fluid:
	0.2 URL ≤ span ≤ URL: ± 0.1% of span
	0.05 URL ≤ span < 0.2 URL: ± [0.025+0.015 URL/span]% of span
	For ranges 1, 2, 3, 4, 5 or 6, differential or gage models, and 316L SST or Hastelloy diaphragm with silicon or halocarbon filling fluid:
	0.1 URL ≤ span ≤ URL : ± 0.075% of span 0.025 URL ≤ span < 0.1 URL : ± [0.0375+0.00375.URL/span]% of span 0.0083 URL ≤ span < 0.025 URL : ± [0.0015+0.00465.URL/span]% of span
	For ranges 2 to 6 and absolute model. For tantalum or monel diaphragm. For fluorolube filling fluid:
Accuracy	0.1 URL ≤ span ≤ URL : ± 0.1% of span 0.025 URL ≤ span < 0.1 URL : ± [0,05+0,005 URL/span]% of span 0.0083 URL ≤ span < 0.025 URL : ± [0.01+0.006 URL/span]% of span
	For range 1 and absolute model: ± 0.2% of span
	For ranges 2, 3 or 4 and level model and 316L SST diaphragm with silicon or halocarbon filling fluid with maximum pressure matching the flange pressure class:
	0.1 URL ≤ span ≤ URL: ± 0.075% of span 0.025 URL ≤ span < 0.1 URL : ± [0.0375+0.00375.URL/span]% of span 0.0083 URL ≤ span < 0.025 URL : ± [0.0015+0.00465.URL/span]% of span
	Linearity effects, hysteresis and repeatability are included. For ranges 1, 2, 3, 4, 5 and 6: ± 0.15% of URL for 5 years at 20 °C temperature change and up to 7 MPa (1000 psi) of static pressure.
Stability	For ranges 0: ± 0.2% of URL for 12 months at 20 °C temperature change, and up to 100 kPa (1bar) of static pressure.
	For Level model: ± 0.2% of URL for 12 months at 20 °C temperature change.
	For ranges 2, 3, 4, 5 and 6: 0.2 URL ≤ span ≤ URL: ± [0.02% URL + 0.06% span] per 20 °C (68 °F) 0.0085 URL ≤ span < 0.2 URL: ± [0.023% URL + 0.045% span] per 20 °C (68°F)
	For range 1: 0.2 URL ≤ span ≤ URL: ± [0.08% URL + 0.05% span] per 20 °C (68 °F) 0.025 URL ≤ span < 0.2 URL: ± [0.06% URL + 0.15% span] per 20 °C (68 °F)
Temperature	For range 0:
Effect	0.2 URL ≤ span ≤ URL : ± [0.15% URL + 0.05% span] per 20 °C (68 °F) 0.05 URL ≤ span < 0.2 URL : ± [0.1% URL + 0.3% span] per 20 °C (68 °F)
	For level model:
	6 mmH ₂ O per 20 °C for 4" and DN100
	17 mmH₂O per 20 °C for 3" and DN80 Consult Smar for other flange dimensions and fill fluid.
	Zero error:
	For ranges 2, 3, 4 and 5: ± 0.033% of URL per 7MPa (1000 psi)
	For range 1: ± 0.05% of URL per 1.7 MPa (250 psi) For range 0: ± 0.1% of URL per 0.5 MPa (5 bar)
	For Level model: ± 0.1% of URL per 0.5 MPa (5 0a)
Static Pressure	
Effect	The zero error is a systematic error that can be eliminated by calibrating at the operating static pressure.
	Span error:
	For ranges 2, 3, 4, 5 and 6: correctable to ± 0.2% of reading per 7MPa (1000 psi) For range 1 and level transmitters: correctable to ± 0.2% of reading per 3.5 MPa (500 psi) For range 0: correctable to ± 0.2% of reading per 0.5 MPa (5 bar) (70 psi)

	Performance Specifications
Power Supply Effect	± 0.005% of calibrated span per volt
Mounting Position Effect	Zero shift of up to 250 Pa (1 inH2O) which can be calibrated out. No span effect.
Electromagnetic Interference Effect	Approved according to IEC61326-1:2006, IEC61326-2-3:2006, IEC61000-6-4:2006, IEC61000-6-2:2005.

	Physical Specifications
	1/2 - 14 NPT
Electrical Connection	3/4 - 14 NPT with 316 SST adapter for 1/2 - 14 NPT) 3/4 - 14 BSP with 316 SST adapter for 1/2 - 14 NPT) 1/2 - 14 BSP with 316 SST adapter for 1/2 - 14 NPT) M20 X 1.5 PG 13.5 DIN
	1/4 - 18 NPT or 1/2 -14 NPT (with adapter)
	For level models or other options, see the Ordering Code.
Wetted Parts	Sensor Isolating Diaphragms: 316L SST, Hastelloy C276, Monel 400 or Tantalum Drain/Vent Valves and Plugs 1/4NPT: 316 SST, Hastelloy C276 or Monel 400 Drain / Vent Valves and 1/4 NPT Plug: 316L SST, Hastelloy C276, Monel 400 Transmitter's Flanges (1/4 NPT) and 1/2 NPT Adapter: Plated Carbon Steel, 316 SST (ASTM - A351-CF8M), Hastelloy C276 ASTM - A494 CW-12MW) or Monel 400 Wetted O-Rings (For Flanges and Adapters): Buna N, Viton™ PTFE, Ethylene-Propylene, or Kalrez. Level Flanges (LD301L - ASME / DIN / JIS) 316L SST; 304L SST; Hastelloy C276; Duplex UNS S31803 / S32205; Super Duplex UNS S32750 / S32760 Flanges Isolating Diaphragms 316L SST; 304L SST; Hastelloy C276; Super Duplex UNS S32750 / S32760; 316L SST with Halar coating; 316L SST gold plated; Monel gold plated Flange's Gaskets PTFE; Grafoil Sanitary connections (TC, SMS, RTJ, IDF, DIN 11851): 316L SST; Hastelloy C276 (extension end of connection) Sanitary Diaphragms 316L SST; Hastelloy C276 Sanitary Connections - Sealing rings Buna N; PTFE; Viton The LD301 is available in NACE MR-0175/ISO 15156 compliant materials. Electronic Housing: aluminum or 316 SST with polyester or epoxy painting or 316 SST without painting
Nonwetted Parts	housing. Complies with NEMA 4X/6P, IP66 or IP66W*, IP68 or IP68W*. *The IP68 sealing test (immersion) was performed at 10m for 24 hours. The W condition or 4X was tested for 200h and refer to saline atmosphere. Absolute/Gage Flange; reduced volume flange and Plug Flange
	316 SST - CF8M (ASTM - A351 CF8M) Fill Fluid: Silicone, Fluorolube, Krytox, Halocarbon 4.2 or Fomblim oils

	Physical Specifications
	O-Rings (cover/housing and sensor/housing) Buna-N
Nonwetted Parts (continuation)	Mounting Bracket: Plated carbon steel or 316 SST Accessories (bolts, nuts, washers, and U-clamps) in plated carbon steel or 316 SST
	Transmitter Flange Bolts and Nuts: 316 SST For NACE applications: carbon steel B7M; Hastelloy; Super duplex
	Identification Plate: 316 SST
	The LD301 is available in NACE MR-0175/ISO 15156 compliant materials.
Mounting	 a) Flange mounted for Level and sanitary models. b) Optional universal mounting bracket for surface or vertical/horizontal 2"- pipe (DN 50). c) Manifold Valve integrated to the transmitter. d) Directly on piping for closely coupled transmitter/orifice flange combinations.
Approximate	e) L mounting bracket 3.15 kg (7 lb): all models, except L models.
Approximate Weights	4.6 to 23.5 kg (10 lb to 52 lb): L models depending of diameter; class and material flanges and extension.
Control Functions Characteristics (Optional)	Control Block (PID) and Totalizer (TOT)

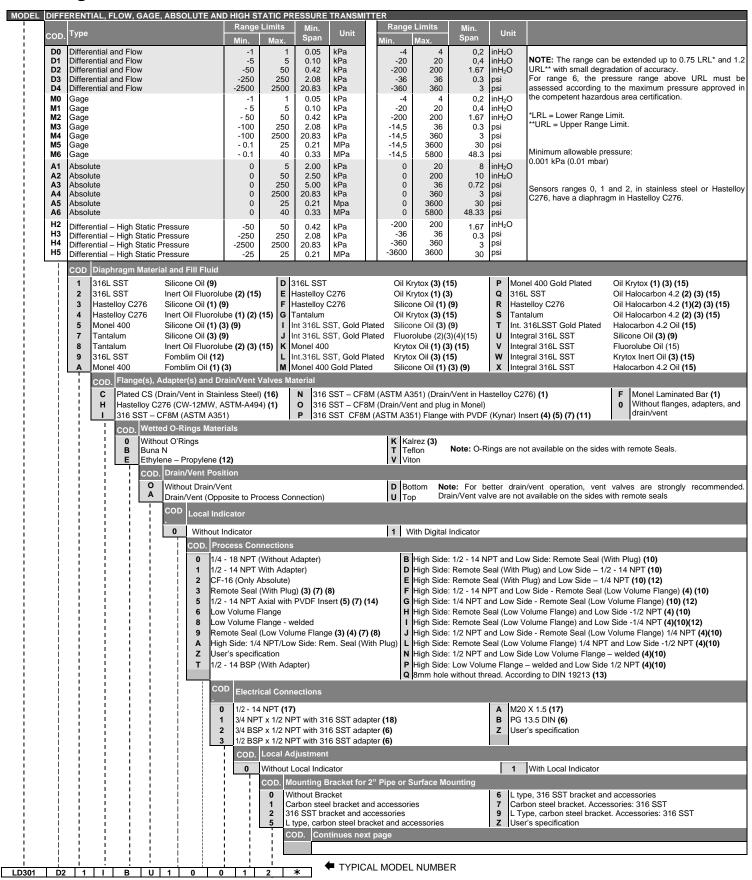
Technical Characteristics of High Performance - CODE L1								
High Performanc	e option (cod	e L1) is a	vailable u	nder the f	ollo	owing cond	litions on	ıly:
Application	Differen	itial and	Gage					
		Range	Limits	Unit		Range I	_imits	Unit
	COD	Min.	Max.	Oilit		Min.	Max.	Oilit
	D0	-1	1	kPa		-4	4	inH ₂ O
	D1	-5	5	kPa		-20	20	inH ₂ O
	D2	-50	50	kPa		-200	200	inH ₂ O
	D3	-250	250	kPa		-36	36	psi
	D4	-2500	2500	kPa		-360	360	psi
	MO	-1	1	kPa		-4	4	inH ₂ O
Dange	M1	-5 -5	5	kPa		-20	20	inH ₂ O
Range	M2 M3	-50	50	kPa		-200	200	inH ₂ O
	M4	-100 -100	250 2500	kPa kPa		-14,5	36 360	psi
	M5	-0,1	2500 25	MPa		-14,5 -14,5	3600	psi psi
	M6	-0,1	40	MPa		-14,5	5800	psi
		0,1	40			14,5	3000	ры
	H2	-50	50	kPa		-200	200	inH ₂ O
	H3	-250	250	kPa		-36	36	psi
	H4	-2500	2500	kPa		-360	360	psi
	H5	-25	25	MPa		-3600	3600	psi
Diaphragm Material	316L SS	ST or Has	telloy C27	6				
Fill Fluid	Silicone							

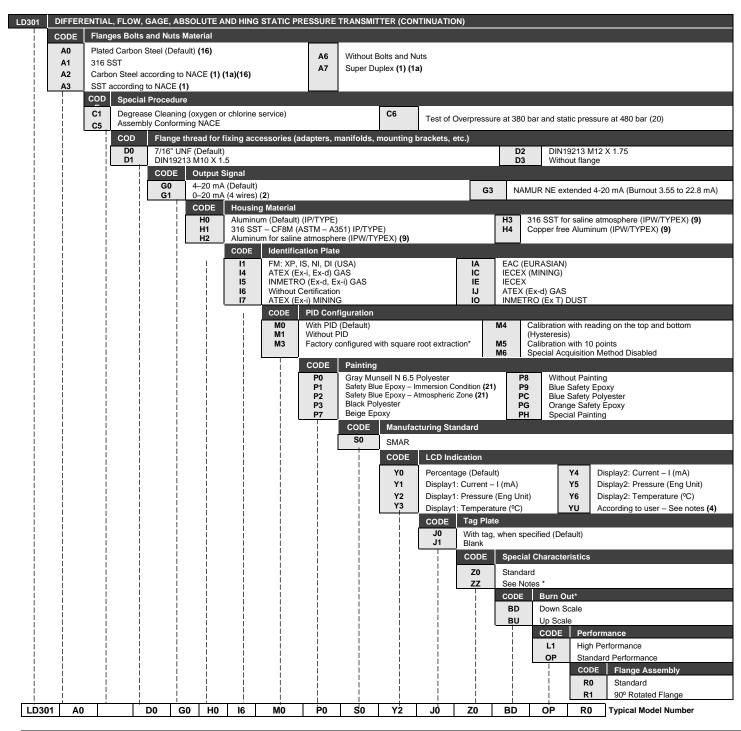
Performance Specifications - CODE L1						
Reference Conditions	Span starting at zero, temperature of 25 °C (77 °F), atmospheric pressure, power supply of 24 Vdc, silicone oil fill fluid, isolating diaphragms in 316L SST and digital trim equal to lower and upper range values.					
Accuracy	For all L1 ranges: 0.2 URL ≤ span ≤ URL: ± 0.04% of span 0.05 URL ≤ span < 0.2 URL: ± [0.021667+0.003667URL/span]% of span 0.0085 URL ≤ span < 0.05 URL: ± [0.0021+0.004645URL/span]% of span					

	Performance Specifications - CODE L1
Stability	For range 2: ± 0.05% of URL for 6 months For range 3: ± 0.075% of URL for 12 months For range 4: ± 0.1% of URL for 24 months For all M, D, and H transmitters: ± 0.15% of URL for 12 years, at 20 °C temperature change and up to 7 MPa (1000 psi) {70 bar} of static pressure, environment free of hydrogen migration.
Temperature Effect	From -10 °C to 50 °C, protected from direct sun radiation: 0.2 URL ≤ span ≤ URL: ±[0.018% URL + 0.012% span] per 20 °C (68 °F) 0.0085 URL ≤ span < 0.2 URL: ±[0.02% URL + 0.002% span] per 20 °C (68 °F)
Zero Error and Span Error	Zero error: ± 0.025% URL per 7 MPa (1000 psi) The zero error is a systematic error that can be eliminated by calibrating at the operating static pressure. Span error: Correctable to ± 0.2% of reading per 7 MPa (1000 psi).

NOTES				
Hastelloy is a trademark of the Cabot Corp.	Fluorolube is a trademark of Gabriel Chemical Corp.	Smar Pressure Transmitters are protected by		
Monel is a trademark of International Nickel Co.	Halocarbon is a trademark of Halocarbon.	US patent number 6,433,791		
Viton and Teflon are trademarks of E. I. DuPont de Nemours & Co.	HART® is a trademark of HART® communication Foundation.			

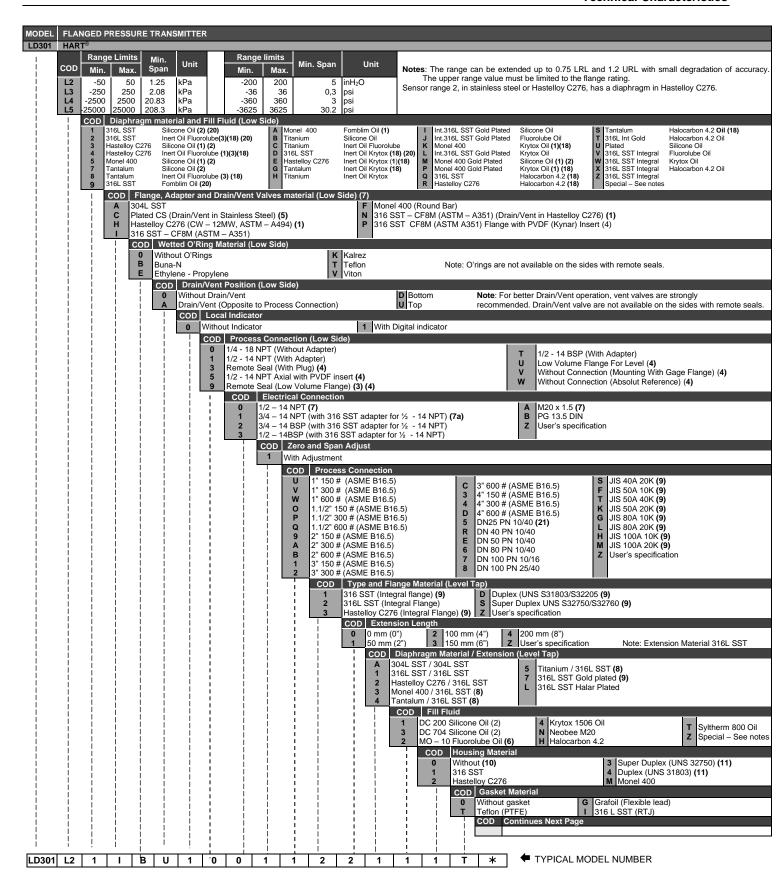
Ordering Code

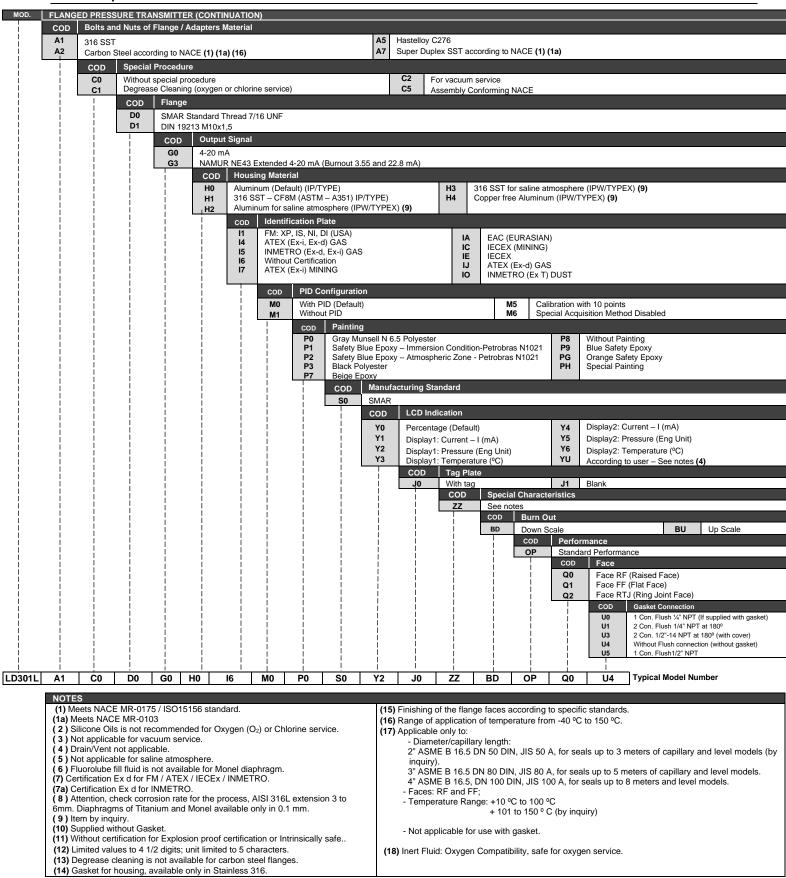


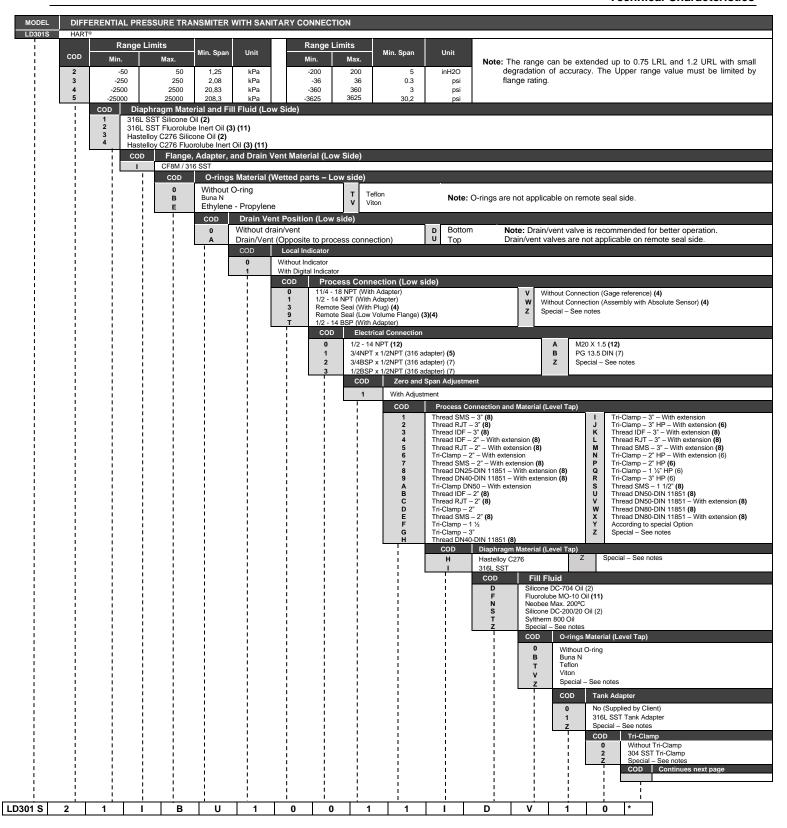


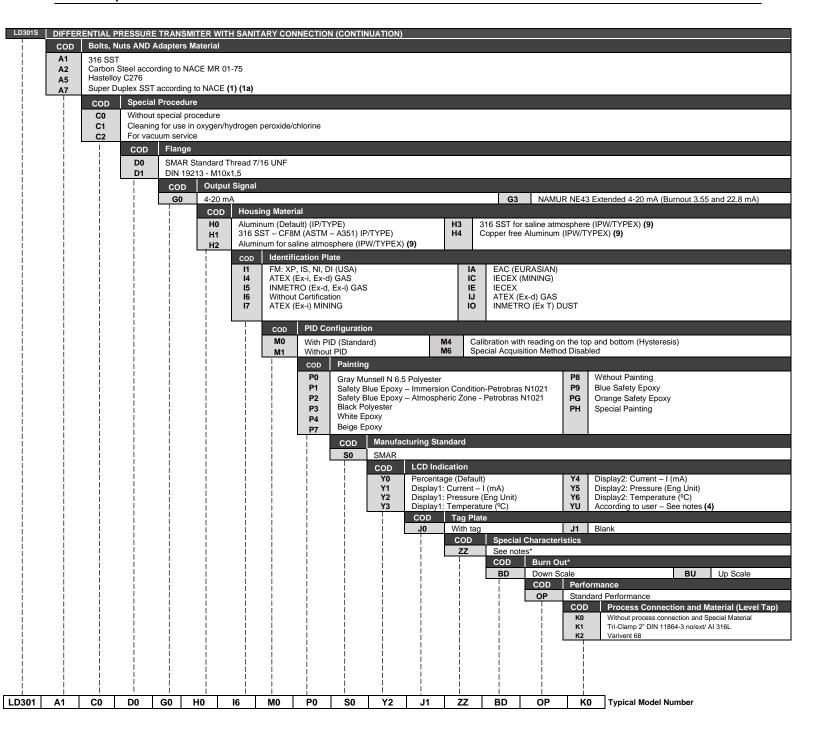
- (1) Meets NACE MR-0175 / ISO15156 standard.
- (1a) Meets NACE MR-0103.
- (2) Not available for absolute models nor vacuum applications.
- (3) Not available for range 0 and 1.
- (4) Not recommended for vacuum service.
- Maximum pressure 24 bar (350 psi).
- (6) Options not certified for hazardous locations.
- (7) Drain/Vent not applicable.
- (8) For remote seal only 316 SST CF8M flange (thread 7/16 20UNF).
- (9) Silicone Oil is not recommended for oxygen (O2) or Chlorine service.
- (10) Only available for differential pressure transmitters. (11) O'Ring should be Viton or Kalrez

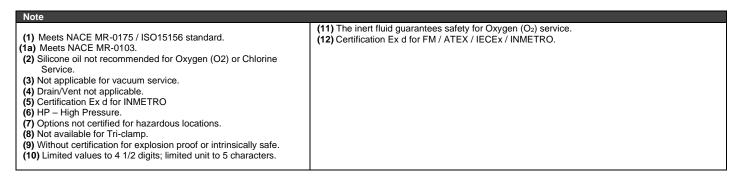
- (12) Not available for range 0.
- (13) Only available for pressure transmitters D4 or H4, only 316/CF-8M. (14) Only available for flange with PVDF (Kynar) insert.
- (15) Inert Fluid: Safe for oxygen service.
- (16) Not applicable for saline atmosphere
- (17) Certification Ex d for FM / ATEX / IECEx / INMETRO. (18) Certification Ex d for INMETRO.
- (19) 316L SST sensors range 0,1,2 has Hastelloy C276 diaphragm.
- (20) Only applicable in class H.
- (21) Petrobras N1021 Standard











CERTIFICATIONS INFORMATION

Hazardous locations general information

Ex Standards:

IEC 60079-0 General Requirements

IEC 60079-1 Flameproof Enclosures "d"

IEC 60079-11 Intrinsic Safety "i"

IEC 60079-26 Equipment with Separation Elements or combined Levels of Protection

IEC 60079-31 Equipment dust ignition protection by enclosure "t"

IEC 60529 Classification of degrees of protection provided by enclosures (IP Code)

IEC 60079-10 Classification of Hazardous Areas

IEC 60079-14 Electrical installation design, selection and erection

IEC 60079-17 Electrical Installations, Inspections and Maintenance

IEC 60079-19 Equipment repair, overhaul and reclamation

ISO/IEC 80079-34 Application of quality systems for equipment manufacture

Warning:

Explosions could result in death or serious injury, besides financial damage.

Installation of this instrument in hazardous areas must be in accordance with the local standards and type of protection. Before proceedings with installation make sure that the certificate parameters are in accordance with the classified hazardous area.

Maintenance and Repair

The instrument modification or replaced parts supplied by any other supplier than authorized representative of Smar is prohibited and will void the Certification.

Marking Label

The instrument is marked with type of protection options. The certification is valid only when the type of protection is indicated by the user. Once a particular type of protection is installed, do not reinstall it using any other type of protection.

Intrinsic Safety / Non Incendive application

In hazardous areas with intrinsic safety or non-incendive requirements, the circuit entity parameters and applicable installation procedures must be observed.

The instrument must be connected to a proper intrinsic safety barrier. Check the intrinsically safe parameters involving the barrier and equipment including the cable and connections. Associated apparatus ground bus shall be insulated from panels and mounting enclosures. Shield is optional, when using shielded cable, be sure to insulate the end not grounded.

Cable capacitance and inductance plus Ci and Li must be smaller than Co and Lo of the Associated Apparatus. It is recommended do not remove the housing covers when powered on.

Explosionproof / Flameproof application

Only use Explosionproof/Flameproof certified Plugs, Adapters and Cable glands.

The electrical connections entries must be connected using a conduit with sealed unit or closed using metal cable gland or metal blanking plug with at least IP66.

Do not remove the housing covers when powered on.

Enclosure

The electronic housing and sensor threads installed in hazardous areas must have a minimum of 6 fully engaged threads.

The covers must be tightening with at least 8 turns, to avoid the penetration of humidity or corrosive gases, and until it touches the housing. Then, tighten more 1/3 turn (120°) to guarantee the sealing.

Lock the housing and covers using the locking screw.

The enclosure contains aluminum and is considered to present a potential risk of ignition by impact or friction. Care must be taken during installation and use to prevent impact or friction.

Degree of Protection of enclosure (IP)

IPx8: Second numeral meaning continuous immersion in water under special condition defined as 10m for a period of 24 hours (Ref: IEC60529).

IPW/ TypeX: Supplementary letter W or X meaning special condition defined as saline environment tested in saturated solution of NaCl 5% w/w at 35°C for a period of 200 hours (Ref: NEMA 250/ IEC60529).

For enclosure with IP/IPW/TypeX applications, all NPT threads must apply a proper water-proof sealant (a non-hardening silicone group sealant is recommended).

Hazardous Locations Approvals

FM Approvals

FM19US0176X XP Class I Division 1, Groups A, B, C, D DIP Class II, Class III Division 1, Groups E, F, G IS Class I, II, III Division 1, Groups A, B, C, D, E, F G NI Class I, Division 2, Groups A, B, C, D; NIFW T4A; Ta = -25°C < Ta < 60°C; Type 4, 4X, 6

Electrical parameters: 30Vdc

Entity Parameters/Nonincendive Field Wiring Parameters: Supply terminals: Vmax = 30 V dc, Imax = 110 mA, Ci = 5nf, Li = 0

Special conditions for safe use:

The enclosure contains aluminum and is considered to present a potential risk of ignition by impact or friction. Care must be taken during installation and use to prevent impact or friction.

Overpressure Limits: 5800 psi (report 3024465)

The range H2 to H5 are similar to D2 to D5, the H ranges are differential type with high static pressure feature.

The ranges H, A5, A6, M5 and M6 need parback for correct and safe operation.

Drawing 38A-2075, 102A-1216, 102A-1339, 102A-1638, 102A-1639

ATEX DNV

Explosion Proof (DNV 25 ATEX 80594X) II 2 G Ex db IIC T6 Gb Ta -20 °C to +60 °C Options: IP66/68W or IP66/68

Special Conditions for Safe Use

Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 1 and 2 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with:

EN IEC 60079-0:2018 General Requirements EN 60079-1:2014 Flameproof Enclosures "d" Drawing 102A-1313, 102A-1491, 102A-2149, 102A-2150

IECEX DNV

Explosion Proof (IECEx DNV 25.0054X) Ex db IIC T6 Gb Ta -20 °C to +60 °C Options: IP66/68W or IP66/68

Special Conditions for Safe Use

Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 1 and 2 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with:

IEC 60079-0:2017 General Requirements

IEC 60079-1:2014-06 Equipment protection by flameproof enclosures "d"

Drawing 102A-2107, 102A-2108, 102A-2184, 102A-2185

ATEX DEKRA

Intrinsic Safety (DMT 01 ATEX E 059) Ex I M1 Ex ia I Ma Ex II 1/2 G Ex ia IIC T4/T5/T6 Ga/Gb

Supply and signal circuit intended for the connection to an intrinsically safe 4-20 mA current loop Ui = 28 Vdc, Ii = 93 mA, Ci ≤ 5 nF, Li = Neg

Ambient Temperature: -40°C ≤ Ta ≤ + 85°C

Maximum Permissible power:

Max. Ambient temperature Ta	Temperature Class	Power Pi
85°C	T4	700mW
75°C	T4	760mW
44°C	T5	760mW
50°C	T5	700mW
55°C	T5	650mW
60°C	T5	575mW
65°C	T5	500mW
70°C	T5	425mW
40°C	T6	575mW

The Essential Health and Safety Requirements are assured by compliance with:

EN 60079-0:2018 General Requirements

EN 60079-11:2012 Intrinsic Safety "i"

EN 60079-26:2015 Equipment with equipment protection level (EPL) Ga

Drawing 102A-1313, 102A-1491, 102A-1465, 102A-1521, 102A-2149, 102A-2150

IECEX DEKRA

Intrinsic Safety (IECEx BVS 19.0015) Ex ia I Ma

Ex ia IIC T4/T5/T6 Ga/Gb

Supply and signal circuit intended for the connection to an intrinsically safe 4-20 mA current loop Ui = 28 Vdc, Ii = 93 mA, Ci \leq 5 nF, Li = Neg Ambient Temperature: -40°C \leq Ta \leq + 85°C

Maximum Permissible power:

Max. Ambient temperature Ta	Temperature Class	Power Pi
85°C	T4	700 mW
50°C	T5	700 mW
55°C	T5	650 mW
60°C	T5	575 mW
65°C	T5	500 mW
70°C	T5	425 mW
40°C	T6	575 mW

The Essential Health and Safety Requirements are assured by compliance with:

IEC 60079-0:2017 General Requirements

IEC 60079-11:2011 Intrinsic Safety "i"

IEC 60079-26:2014 Equipment with equipment protection level (EPL) Ga

Drawing 102A-2107, 102A-2108, 102A-2138, 102A-2139, 102A-2184, 102A-2185

INMETRO NCC

IP66/68 ou IP66W/68W

Segurança Intrínseca (NCC 24.0161X) Ex ia IIC T5 Ga Ex ia IIIC T200 100 $^{\circ}$ C Da Ui = 30 V Ii = 100 mA Pi = 0,7 W Ci = 6,40 nF Li = desp Tamb: -20 $^{\circ}$ C a +50 $^{\circ}$ C

Prova de Explosão (NCC 24.0164) Ex db IIC T6 Ga/Gb Ex tb IIIC T85 °C Da/Db Tamb: -20 °C a +40 °C IP66/68 ou IP66W/68W

Observações:

O número do certificado é finalizado pela letra "X": Para indicar que para a versão do Transmissor de pressão, intrinsecamente seguro, modelos: LD290, LD291 e LD301 equipado com invólucro fabricado em liga de alumínio, somente pode ser instalado em localização que exigem o "EPL Ga", se durante a instalação for excluído o risco de ocorrer impacto ou fricção entre o invólucro e pecas de ferro/aco.

O produto adicionalmente marcado com a letra suplementar "W" indica que o equipamento foi ensaiado em uma solução saturada a 5% de NaCl p/p, à 35 °C, pelo tempo de 200 h e foi aprovado para uso em atmosferas salinas, condicionado à utilização de acessórios de instalação no mesmo material do equipamento e de bujões

de aço inoxidável ASTM-A240, para fechamento das entradas roscadas não utilizadas.

Os planos de pintura P1 são permitidos apenas para equipamento fornecido com plaqueta de identificação com marcação para grupo de gás IIB.

O grau de proteção IP68 só é garantido se nas entradas roscadas de ½" NPT for utilizado vedante não endurecível à base de silicone.

O segundo numeral oito indica que o equipamento foi ensaiado para uma condição de submersão de dez metros por vinte e quatro horas. O acessório deve ser instalado em equipamentos com grau de proteção equivalente.

É responsabilidade do fabricante assegurar que todos os transformadores da placa analógica tenham sido submetidos com sucesso aos ensaios de rotina de 1500 V durante um minuto.

Este certificado é válido apenas para os produtos dos modelos avaliados. Qualquer modificação nos projetos, bem como a utilização de componentes ou materiais diferentes daqueles definidos pela documentação descritiva dos produtos, sem a prévia autorização, invalidará este certificado.

As atividades de instalação, inspeção, manutenção, reparo, revisão e recuperação dos equipamentos são de responsabilidade dos usuários e devem ser executadas de acordo com os requisitos das normas técnicas vigentes e com as recomendações do fabricante.

Normas Aplicáveis:

ABNT NBR IEC 60079-0:2020 Atmosferas explosivas - Parte 0: Equipamentos - Requisitos gerais

ABNT NBR IEC 60079-1:2016 Atmosferas explosivas - Parte 1: Proteção de equipamento por invólucro à prova de explosão "d"

ABNT NBR IEC 60079-11:2013 Atmosferas explosivas - Parte 11: Proteção de equipamento por segurança intrínseca "i"

ABNT NBR IEC 60079-26:2022 Atmosferas explosivas - Parte 26: Equipamentos com elementos de separação ou níveis de proteção combinados

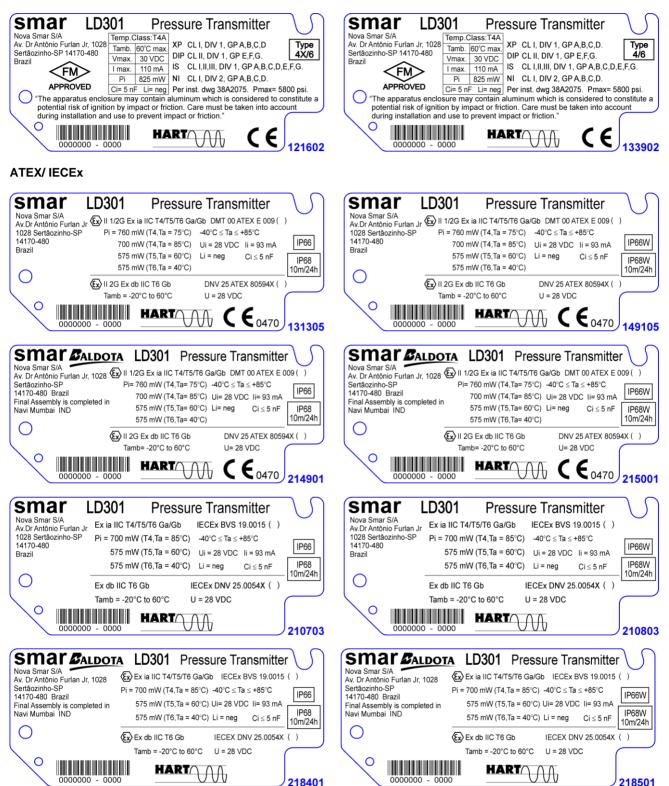
ABNT NBR IEC 60079-31:2022 Atmosferas explosivas - Parte 31: Proteção de equipamentos contra ignição de poeira por invólucros "t"

ABNT NBR IEC 60529:2017 Graus de proteção providos por invólucros (Código IP)

Desenhos 102A1374, 102A1254, 102A2032, 102A2031, 102A2088

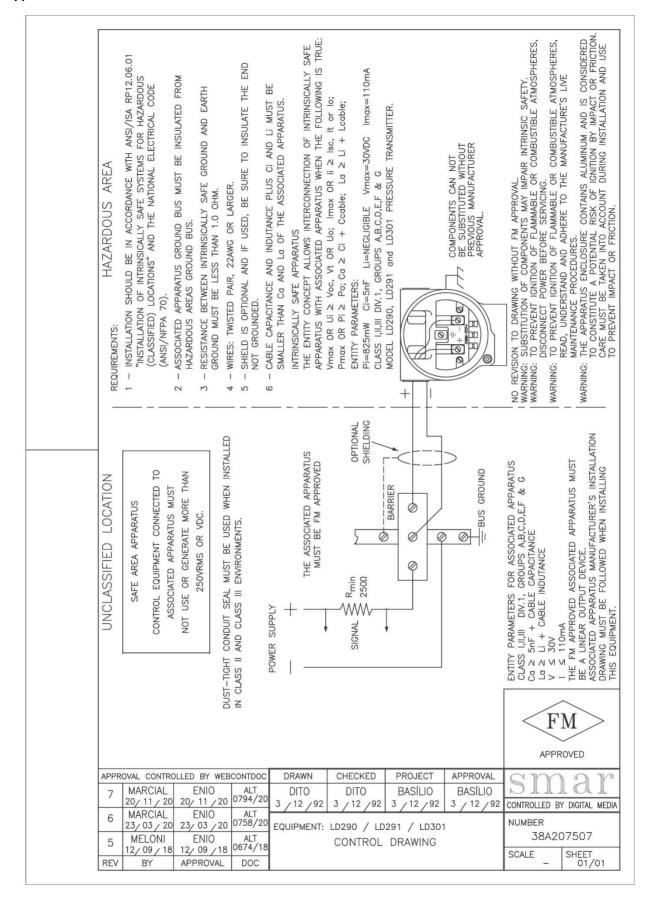
Identification Plate

FM Approvals





FM Approvals



Appendix B

sm	SMAT SRF – Service Request Form Pressure Transmitters						Proposal No.: (1)			
Company:			Unit:			Invoice:				
Full Name:	COMMER	RCIAL CON	TACT		Full Name:		CUSTUM	ER CO	NTACT	
Function:					Function:					
Phone:			Extension:		Phone:				Exte	ension:
Fax:					Fax:					
Email:					Email:					
EQUIPMENT DATA										
Model:					l Number:	Sensor Number:				
Technology:		(A)		•					Firmware	Version:
() 4-20 mA ()	HART [®] () HAR	r [®] sis ()	WIRELESSHART [®]	. , ,	FOUNDATION fi	eldbus () PROFIBU	S PA		
Process Fluid:				PROCESS	S DATA					
T TOOCSS T Tala.										
Calib	ration Range (4)		Ambie	oient Temperature (°F)		Process Temperature (°F)			ture (°F)	
Min.:	Max.:		Min.:	Max.:			Min.:		Ма	x.:
Process P	ressure (4)	St	tatic Pressure (4)		Vacu	um (4)			Applic	ation (3)
Min.:	Max.:	Min.:	Max.:	Min	.:	Max.:		()Tra	ansmitter	() Repeater
Normal Operation	on Time:		I		Failure D	ate:				
			FA	AILURE DES	SCRIPTION					
		(Pleas	e, describe the failur	re. Can the e	error be reprodu					
Did device dete	• •	Wha	t is the final value o _ mA	of the current? (2) What is the message in the display? (2)			(2)			
			MAIN	TENANCE	NEODMATION					
Did you allow th	MAINTENANCE INFORMATION Did you allow the firmware upgrade? () Yes () No () Yes () No									
Main board con () Original fact	ory configuration	()[Default configuration	on		_				
() Special conf	iguration (should	be inform	ed by the client. Ple	ease, use th	e space below	<u>')</u>				
OBSERVATIONS										
SUBMITTER INFORMATION										
Company:										
Submitted by:	Title: Section:									
Phone:	Phone: Extension: E-mail:									
Date:	Date: Signature:									
For warranty or non-warranty repair, please contact your representative. Further information about address and contacts can be found on https://www.smar.com/en/support.										
NOTE										
 (1) This field should be filled out by the Smar. (2) Required for SIS devices. (3) Required for WirelessHART[®] devices. (4) Required to specify the pressure unit. 										