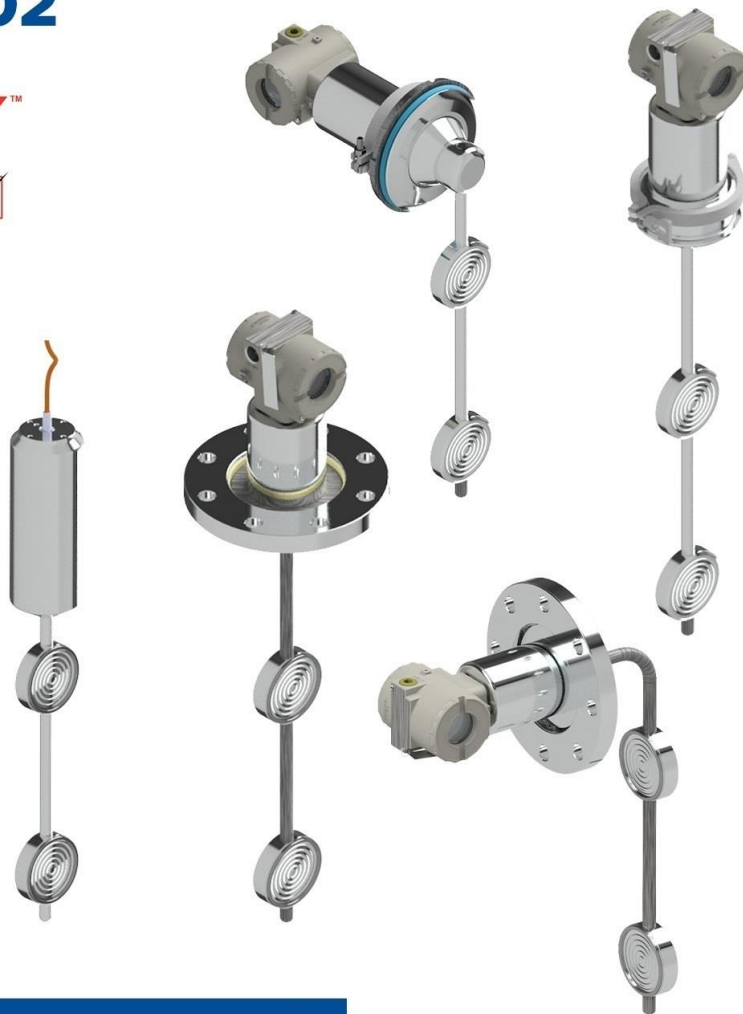


**MANUAL**

INSTRUCTIONS | OPERATION | MAINTENANCE

# DENSITY/CONCENTRATION TRANSMITTER DT302



AUG/25 - VERSION 3

**smar**  
Technology Company

# DT302

Density/Concentration Transmitter



Consult our  
subsidiary



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# INTRODUCTION

The **DT302** is from the first generation of Fieldbus Foundation devices. It is a transmitter for concentration and density measurements. It is based on a field-proven capacitive sensor that provides reliable operation and high performance. The digital technology used in the **DT302** enables the choice of several types of transfer functions, an easy interface between the field and the control room and several interesting features that considerably reduce the installation, operation and maintenance costs.

The Concentration/Density transmitter **DT302 (Touché)** is a device to measure in continuous mode the concentration and density of liquids, directly in industrial process.

The **DT302** is composed for a probe with two repeater diaphragms into the process fluid. The probe is connected to a capacitive sensor, extern to the process, through the capillaries. A fill fluid transmits the process pressure in the two repeater diaphragms to the differential pressure sensor.

A temperature sensor into the probe and between the two repeater diaphragms makes the automatic compensation of any temperature variation of the process. The factory procedure of the probe and temperature sensor allow that small process temperature variations be fast informed to the transmitter, that using a specific software calculates with precision the value of density in the process.

According to the industrial process, the measured concentration by means **DT302** can be expressed in Density, Relative Density, Brix Degree, Baumé Degree, INPM Degree, Plato Degree, Solid %, etc.

The **DT302** is part of Smar's complete 302 line of Fieldbus Foundation devices.

Some of the advantages of bi-directional digital communications are known from existing smart transmitter protocols: Higher accuracy, multi-variable access, remote configuration and diagnostics, and multi-dropping of several devices on a single pair of wires.

The system controls variable sampling, algorithm execution and communication so as to optimize the usage of the network, not losing time. Thus, high closed loop performance is achieved. Using Fieldbus technology, with its capability to interconnect several devices, very large control schemes can be constructed. In order too be user friendly the function block concept was introduced

The **DT302**, like the rest of the 302 family, has some Function Blocks built in, like Analog Input Block.

The need for implementation of Fieldbus in small as well as large systems was considered when developing the entire 302 line of Fieldbus Foundation devices.

They have common features and can be configured locally using a magnetic tool, eliminating the need for a configurator or console in many basic applications.

The **DT302** is available as a product on its own, but also replaces the circuit board for the DT301. They use the same sensor board. Refer to the maintenance section of this manual for instructions on upgrading. The **DT302** uses the same hardware and housing for the **DT302**.

The **DT302**, like its predecessor DT301, has some built-in blocks, eliminating the need for a separate control device. The communication requirement is considerably reduced, and that means less dead-time and tighter control is achieved, not to mention the reduction in cost. They allow flexibility in control strategy implementation.

## ATTENTION

Get the best results of the **DT302** by carefully reading these instructions.

This product is protected by US patent numbers: **6,234,019**; **D439,855** and **5,827,963**.

**NOTE**

This Manual is compatible with version 3.XX, where 3 denotes software version and XX software release. The indication 3.XX means that this manual is compatible with any release of software version 3.

**Waiver of responsibility**

The contents of this manual abides by the hardware and software used on the current equipment version. Eventually there may occur divergencies between this manual and the equipment. The information from this document are periodically reviewed and the necessary or identified corrections will be included in the following editions. Suggestions for their improvement are welcome.

**Warning**

For more objectivity and clarity, this manual does not contain all the detailed information on the product and, in addition, it does not cover every possible mounting, operation or maintenance cases.

Before installing and utilizing the equipment, check if the model of the acquired equipment complies with the technical requirements for the application. This checking is the user's responsibility.

If the user needs more information, or on the event of specific problems not specified or treated in this manual, the information should be sought from Smar. Furthermore, the user recognizes that the contents of this manual by no means modify past or present agreements, confirmation or judicial relationship, in whole or in part.

All of Smar's obligation result from the purchasing agreement signed between the parties, which includes the complete and sole valid warranty term. Contractual clauses related to the warranty are not limited nor extended by virtue of the technical information contained in this manual.

Only qualified personnel are allowed to participate in the activities of mounting, electrical connection, startup and maintenance of the equipment. Qualified personnel are understood to be the persons familiar with the mounting, electrical connection, startup and operation of the equipment or other similar apparatus that are technically fit for their work. Smar provides specific training to instruct and qualify such professionals. However, each country must comply with the local safety procedures, legal provisions and regulations for the mounting and operation of electrical installations, as well as with the laws and regulations on classified areas, such as intrinsic safety, explosion proof, increased safety and instrumented safety systems, among others.

The user is responsible for the incorrect or inadequate handling of equipments run with pneumatic or hydraulic pressure or, still, subject to corrosive, aggressive or combustible products, since their utilization may cause severe bodily harm and/or material damages.

The field equipment referred to in this manual, when acquired for classified or hazardous areas, has its certification void when having its parts replaced or interchanged without functional and approval tests by Smar or any of Smar authorized dealers, which are the competent companies for certifying that the equipment in its entirety meets the applicable standards and regulations. The same is true when converting the equipment of a communication protocol to another. In this case, it is necessary sending the equipment to Smar or any of its authorized dealer. Moreover, the certificates are different and the user is responsible for their correct use.

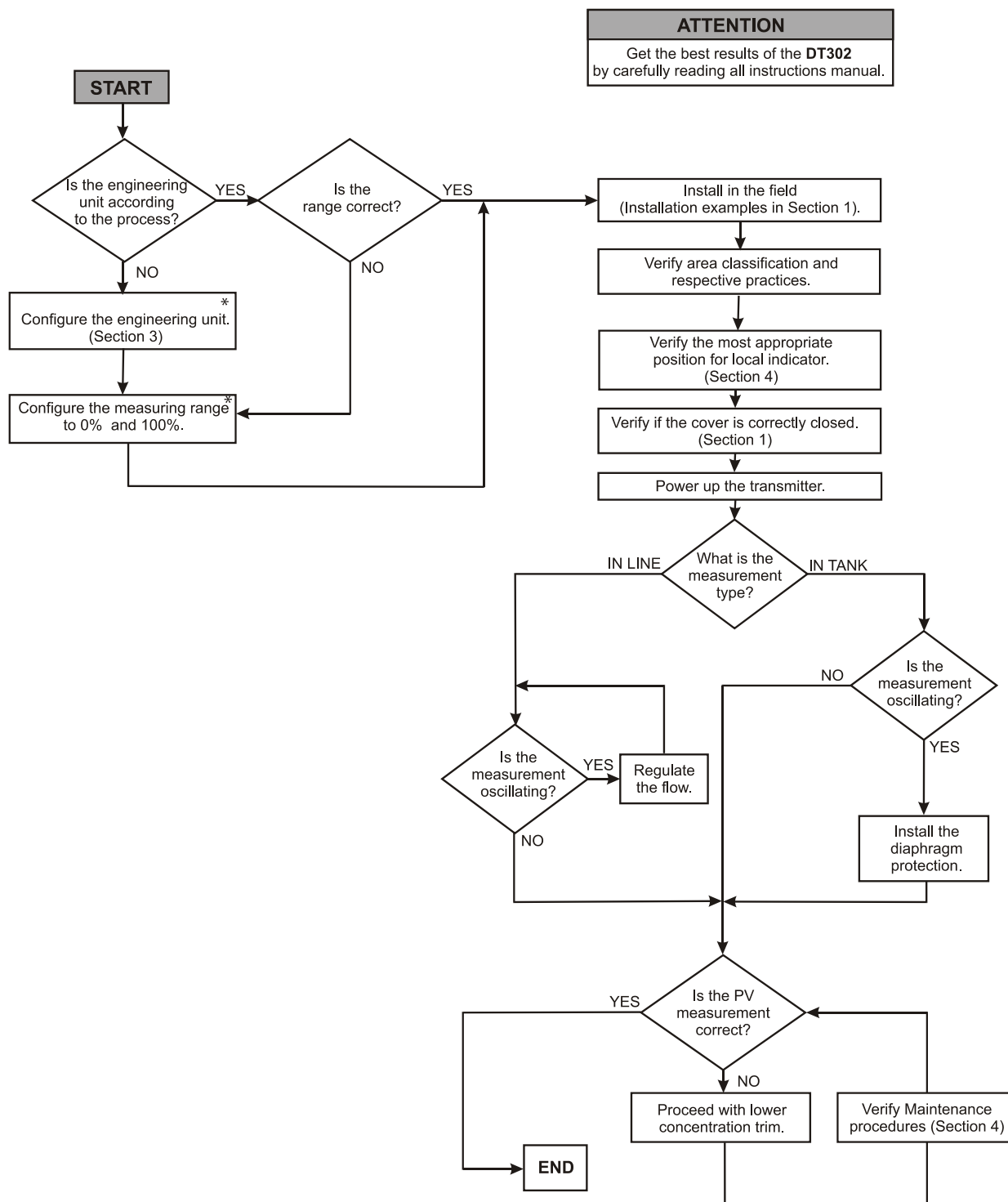
Always respect the instructions provided in the Manual. Smar is not responsible for any losses and/or damages resulting from the inadequate use of its equipments. It is the user's responsibility to know and apply the safety practices in his country.

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# Installation Flowchart







# Section 1

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## INSTALLATION

The overall accuracy of a density measurement depends on several variables. Although the transmitter has an outstanding performance, proper installation is essential to maximize its performance.

Among all factors, which may affect transmitter accuracy, environmental conditions are the most difficult to control. There are, however, ways of reducing the effects of temperature, humidity, and vibration.

### **General**

The **DT302** has a built-in temperature sensor to compensate for temperature variations. At the factory, each transmitter is submitted to a temperature cycle process, and the characteristics under different pressures and temperatures are recorded in the transmitter memory. At the field, this feature minimizes the temperature variation effect.

Locating the transmitter in areas protected from extreme environmental changes can minimize temperature fluctuation effects.

The transmitter should be installed in such a way as to avoid, as much as possible, direct exposure to the sun or any source of irradiated heat.

Humidity is fatal for electronic circuits. In areas subjected to high relative humidity, the O-rings for the electronic housing covers must be correctly placed and the covers must be completely closed by tightening them by hand until the O-rings are compressed. Do not use tools to close the covers. Removal of the electronics cover in the field should be reduced to the minimum necessary, as each time it is removed; the circuits are exposed to the humidity.

The electronic circuit is protected by a humidity proof coating, but frequent exposure to humidity may affect the protection provided. It is also important to keep the covers tightened in place. Every time they are removed, the threads are exposed to corrosion, since painting cannot protect these parts.

Although the transmitter is virtually insensitive to vibration, installation close to pumps, turbines or other vibrating equipment should be avoided.

### **Recommendation in using of DT302**

The process fluid must always cover the two repeater diaphragms.

The maximum process fluid velocity over the two repeater diaphragms must be 0.3 m/s, what means a flow of 26 m<sup>3</sup>/h in a piping of  $\phi$  6". This information is according to fluids which viscosity is close to that water. For fluids where the viscosity is very different to that water viscosity should be analyzed. This limitation is due to the losing of load between the diaphragms. The temperature range of process fluid must be between -20°C and 150°C.

For applications in corrosive fluids, compatible material with the process fluid must be chosen. Materials that are not in contact with the process, but can be in contact with the corrosive atmosphere or process residues, also must be considered.

Verify if a possible leak of fill fluid (unless than 5ml), due an orifice in the diaphragm can contaminate the process. If it is not possible, please, chose a compatible fill fluid.

Verify if the fill fluid does not evaporate in the conditions of limit temperatures and limit pressures of the process.

## **Models of DT302**

**DT302I** - Industrial Model, for general use.

**DT302S**- Sanitary Model, for food, pharmaceutical industries and other applications where is necessary sanitary conditions.

**DT30XM** – Immersion model, for applications where the above models are not possible or tanks with greater depths and allow the probe to be submerged.

The industrial model uses flanged connection according to the standard ANSI B16.5 or DIN 2526.

The sanitary model uses tri-clamp connection, allowing a fast connection to the process. The standard of finishing of the wet surface is 32Ra, highly polished, so that the probe is free of cracks, preventing the accommodation of food residues or bacteria, which could contaminate the process.

## **Mounting**

Both models (**DT302I** and **DT302S**) have two mounting types: top mounting (straight type) and side mounting (curved type).

For **DT302M** only straight type configuration is possible.

The dimensions of both types, industrial and sanitary models, can be seen in the figures 1.1 to 1.4 and **M** model figures 1.5 and 1.6.

The installation can be made in open or pressurized tanks or through an external sampler device from the process.

Some examples are shown in the following figures, 1.7 to 1.21.

Choose a place with free access and free mechanical chock to install the device.

Use a valve in the process connection before the DT302. This simplifies the calibration and maintenance of the equipment.

## A - Industrial Model – Straight Type

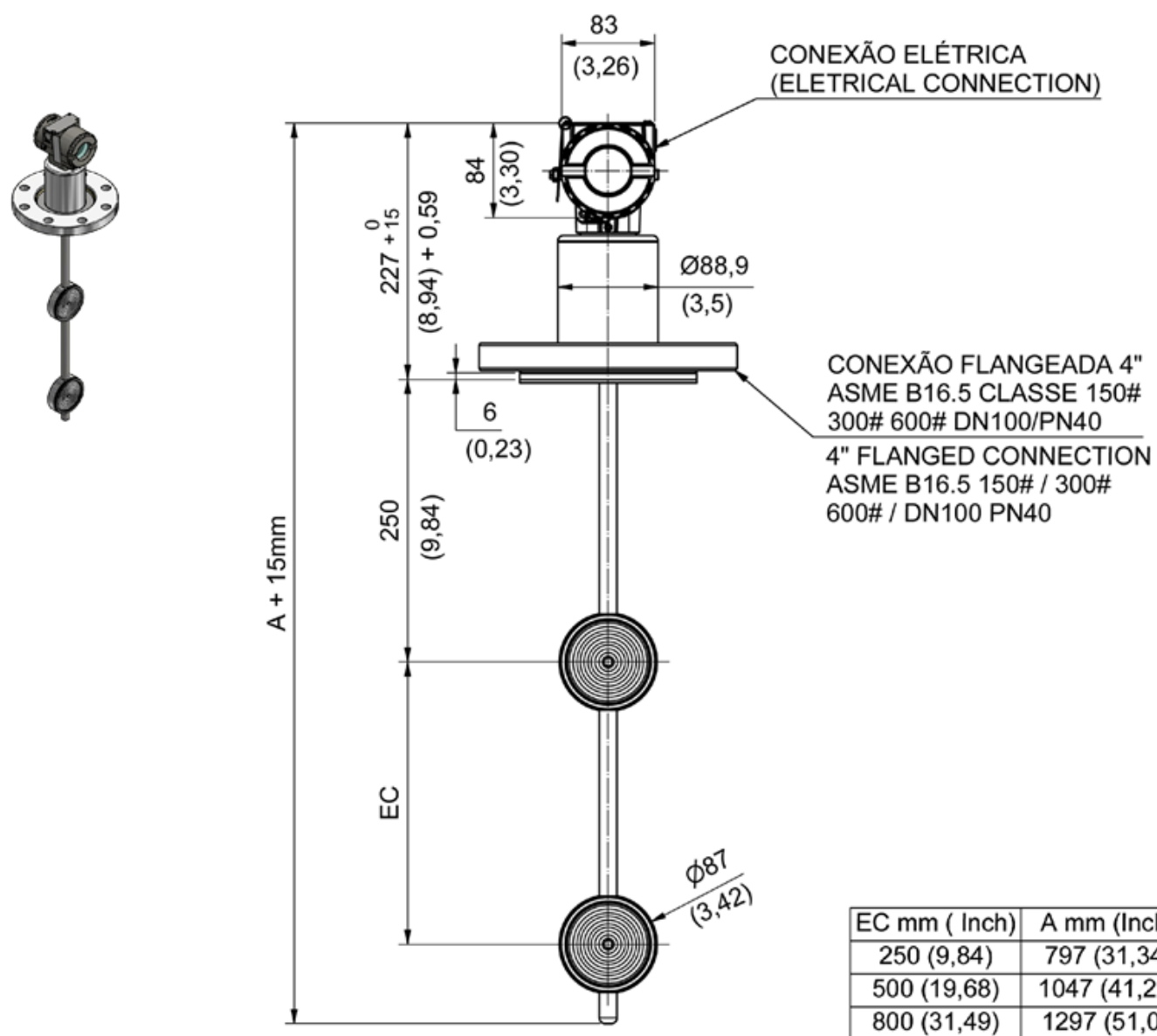


Figure 1.1 – DT302 Dimensional – Straight Industrial Model

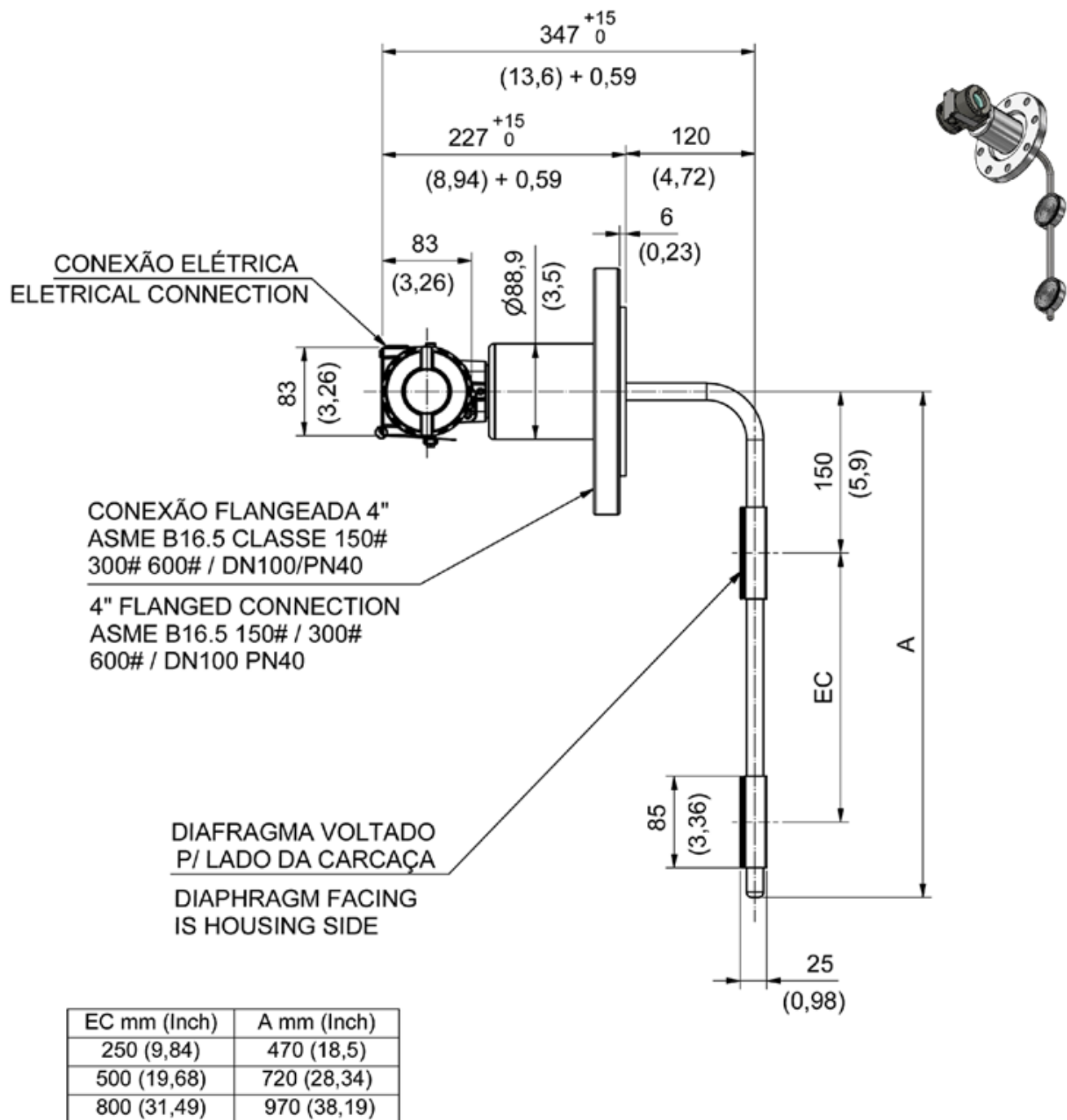
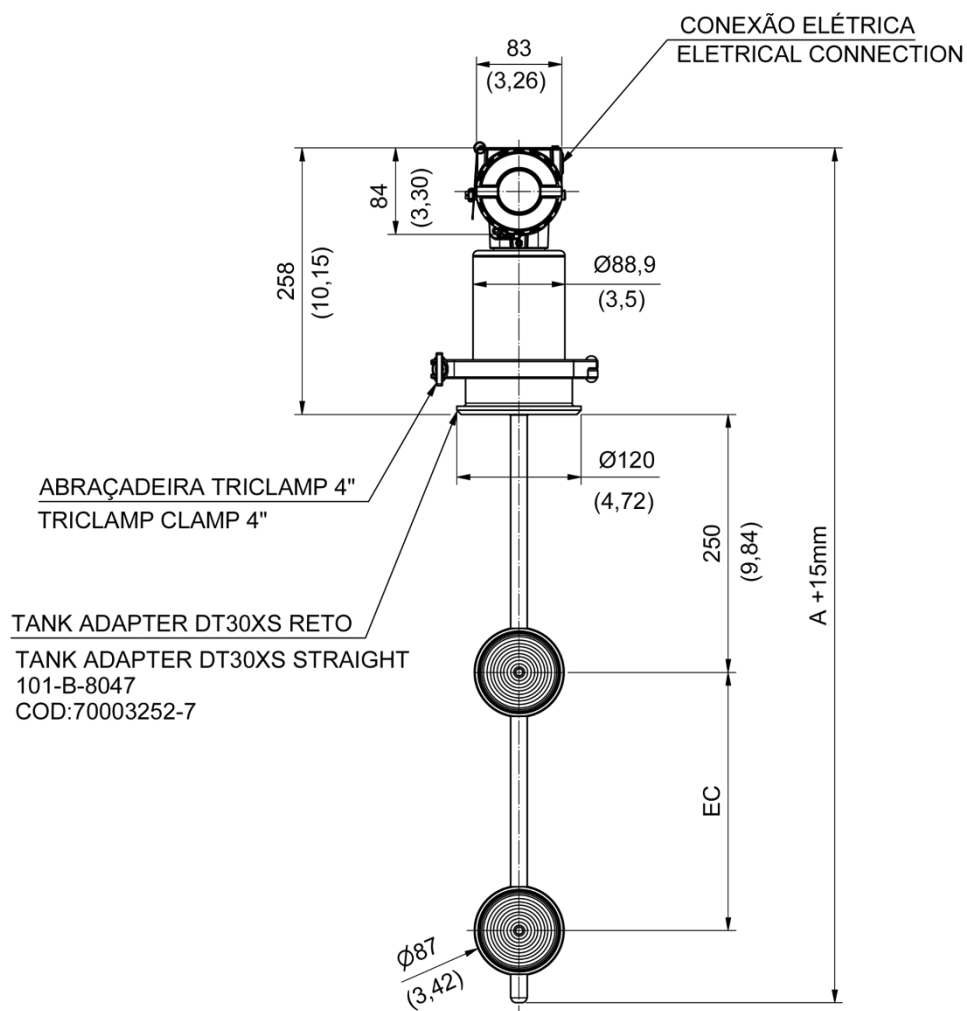
**B – Industrial Model – Curved Type**

Figure 1.2 – DT302 Dimensional - Curved Industrial Model

## C – Sanitary Model - Straight Type



EC mm (Inch)	A mm (Inch)
250 (9,84)	828 (32,59)
500 (19,68)	1078 (42,44)
800 (31,49)	1328 (52,28)

Figure 1.3 – DT302 Dimensional - Straight Sanitary Model

D – Sanitary Model – Curved Type

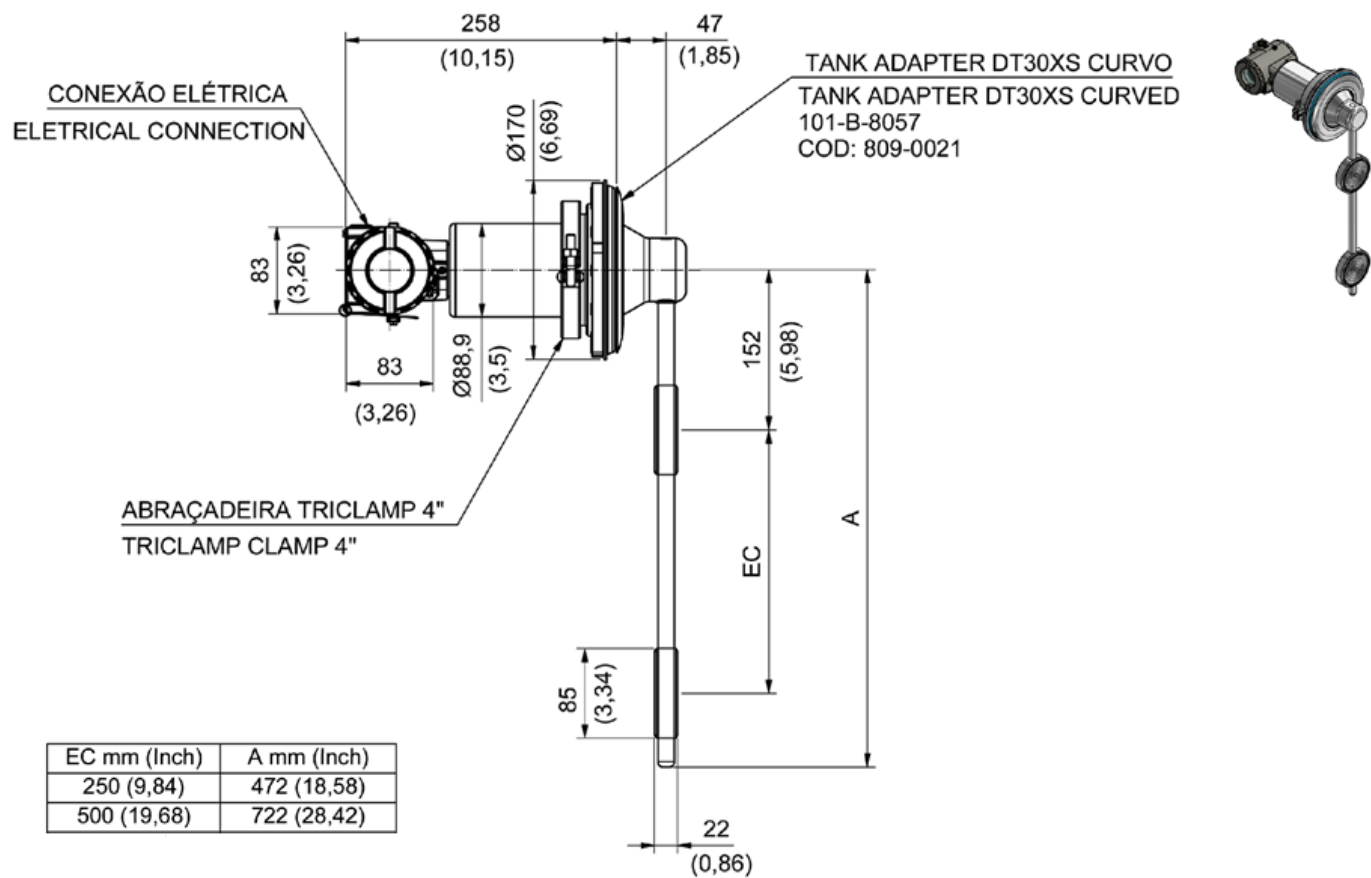


Figure 1.4 – DT302 Dimensional – Curved Sanitary Model

## E – DT30XM Model (Stainless Steel Tubular Rod)

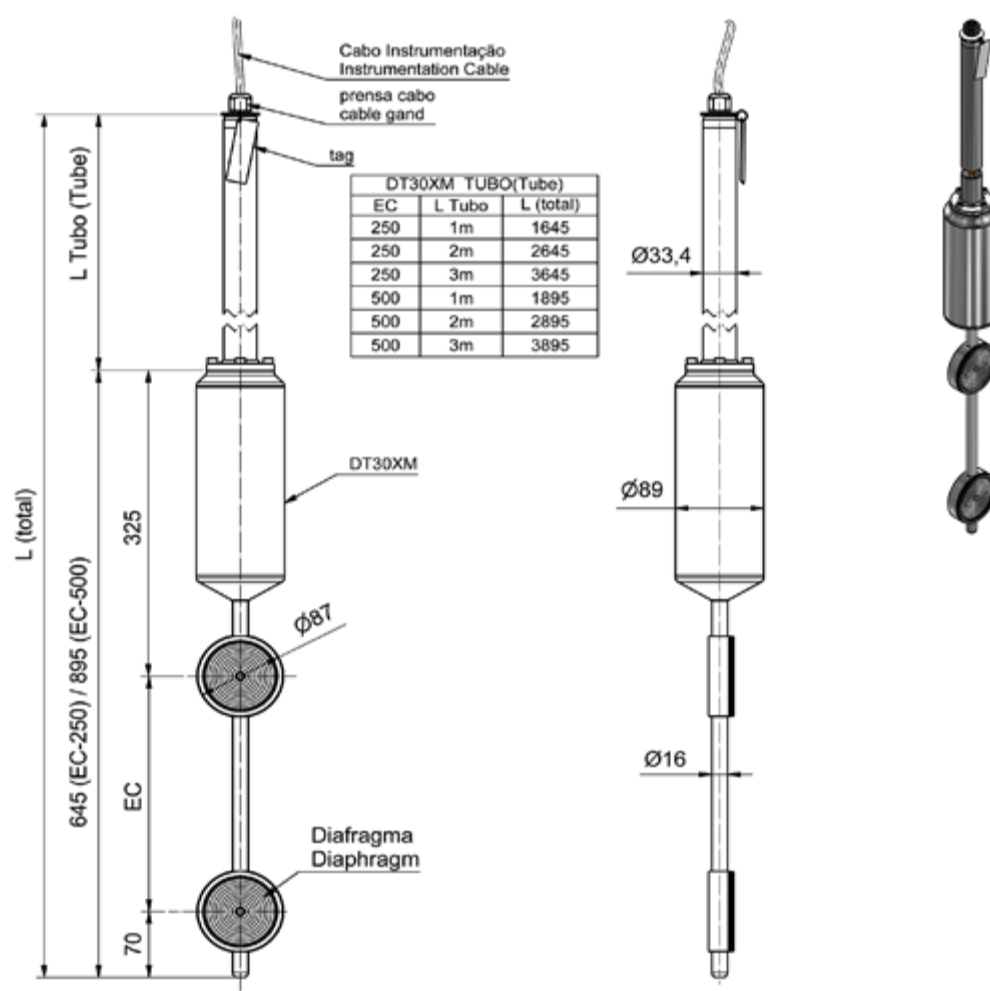


Figure 1.5 – DT302 Dimensional – SST Tubular Rod

F – DT30XM Model (Hose Rod)

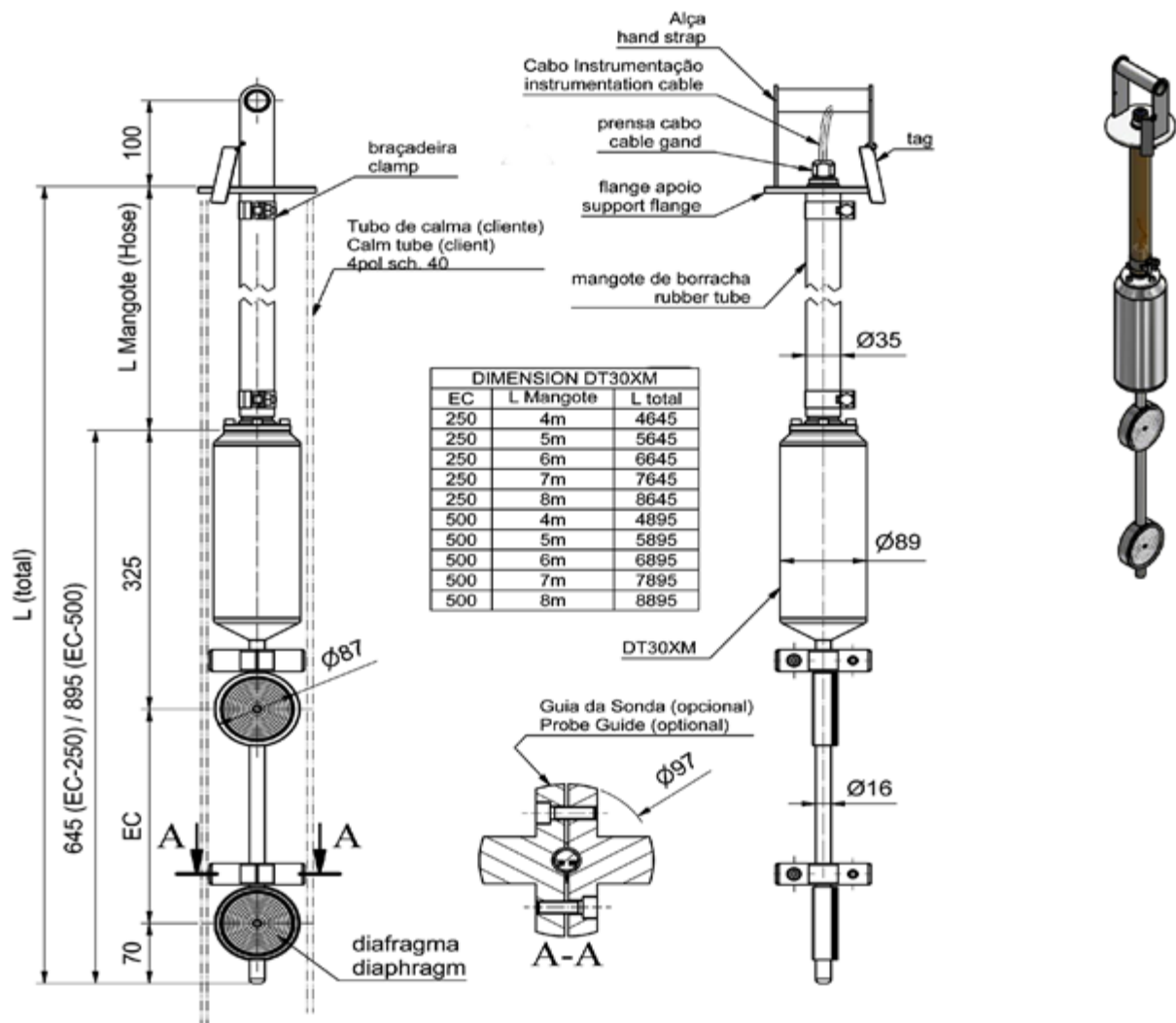


Figure 1.6 – DT302 Dimensional – Hose Rod



## A – Typical Installation for Standpipe Tank

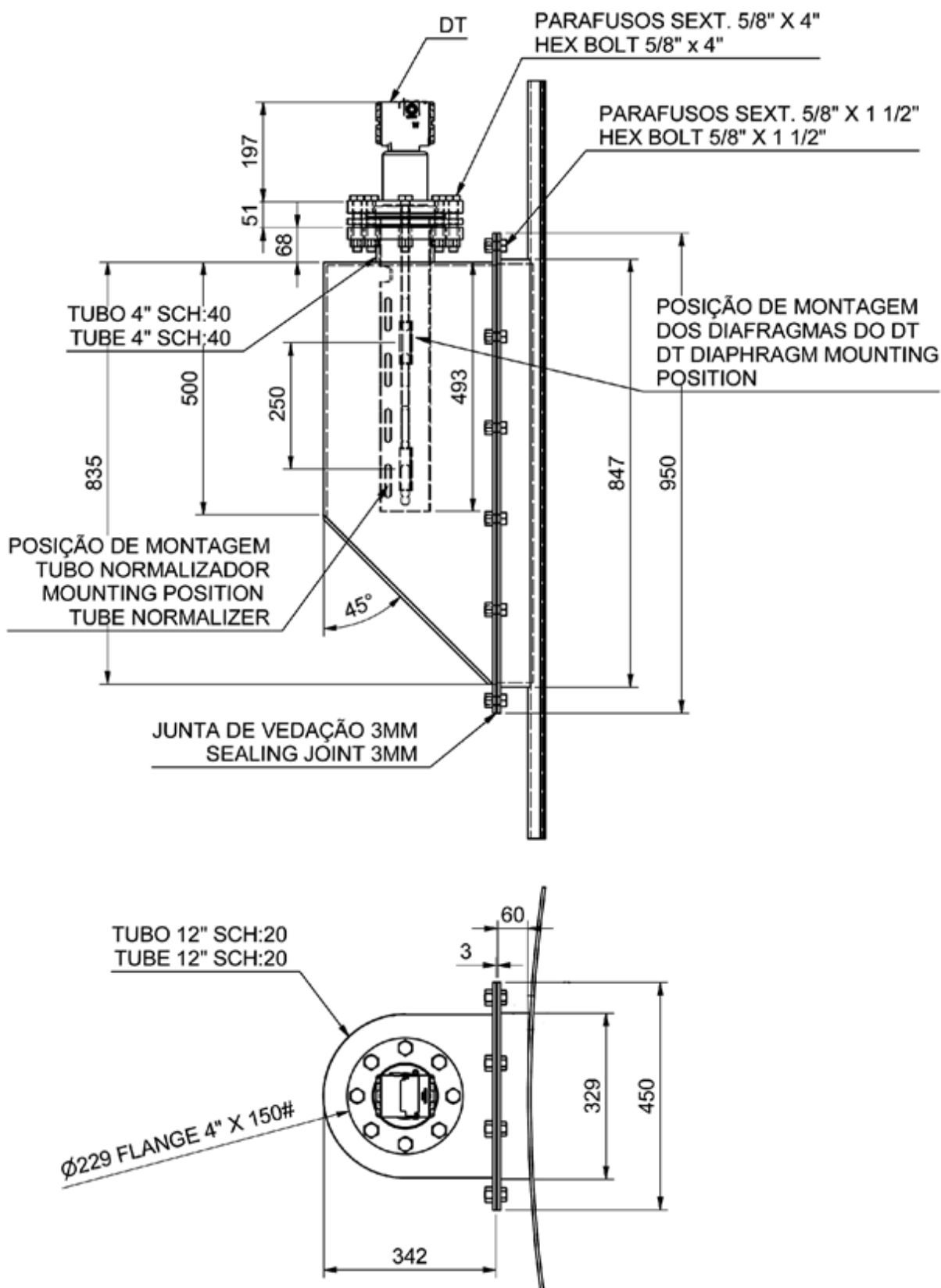


Figure 1.7 – Typical Installation for DT302 (A)

## B – Typical Installation for 6" Up Flow Tank with Normalizer Tube

MAXIMUM FLOW = 15m<sup>3</sup>/h

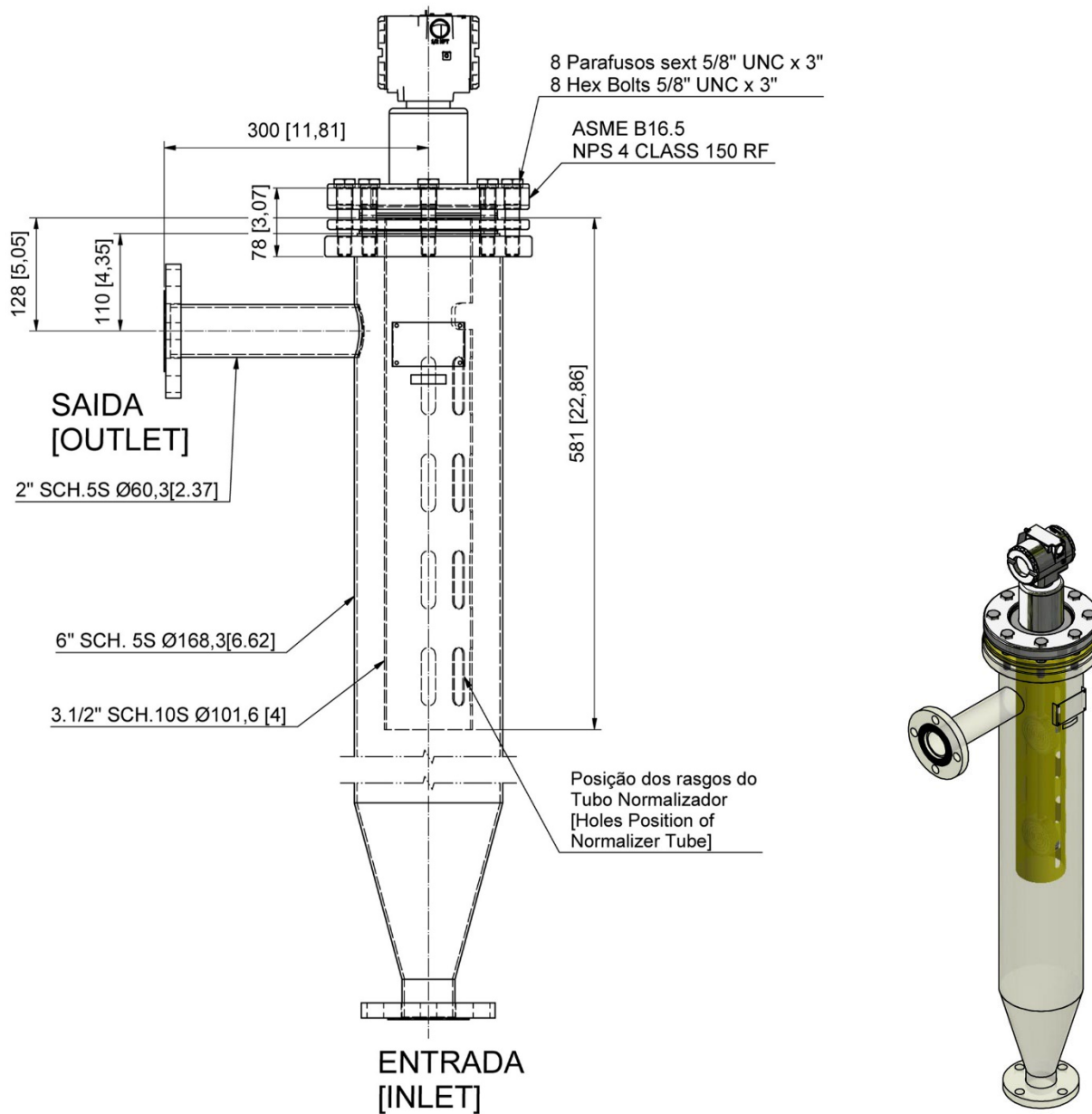


Figure 1.8 – Typical Installation for DT302 (B)

## C – Typical Installation for Up Flow Tank of Overflow with Normalizer Tube

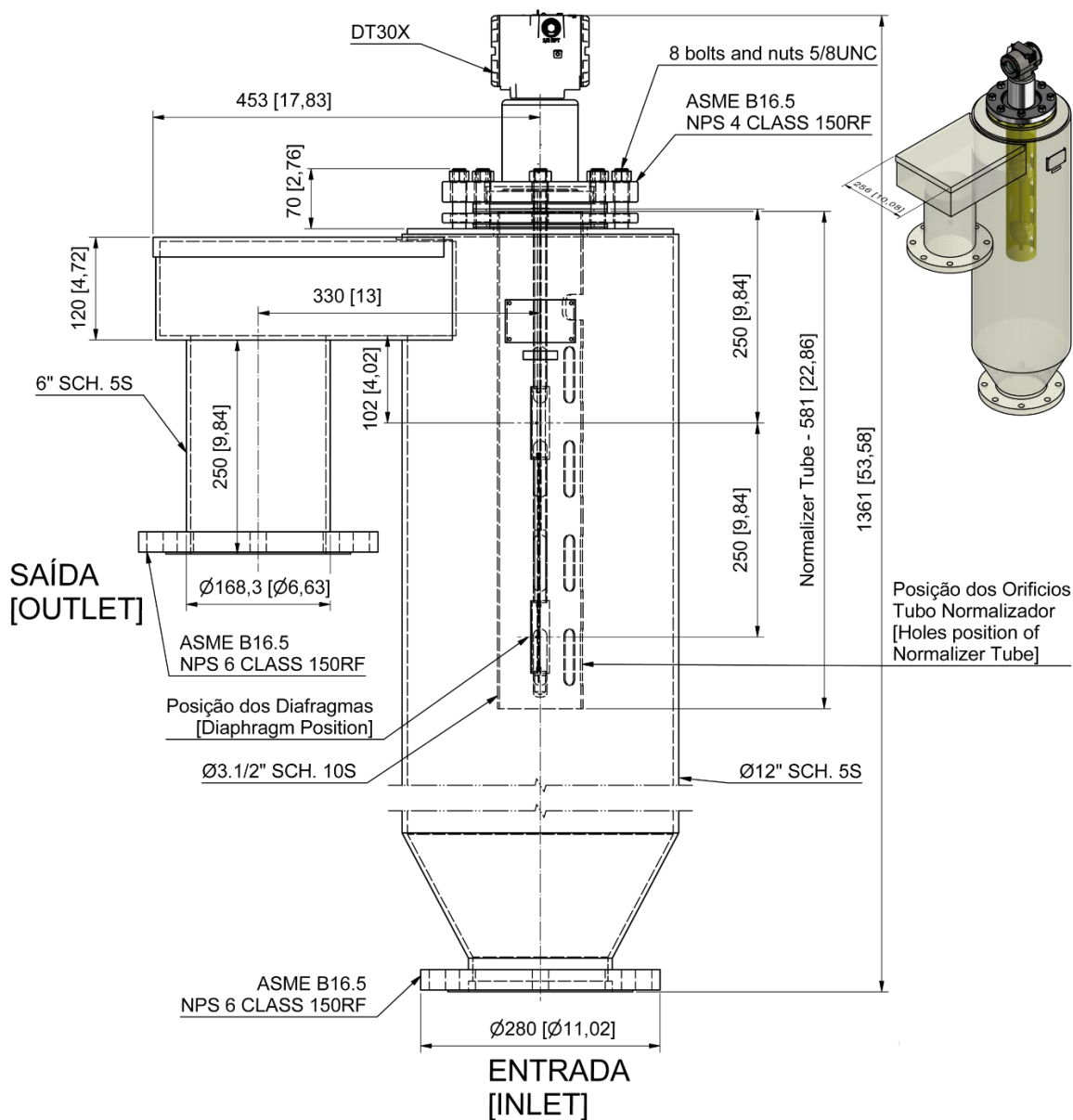


Figure 1.9 – Typical Installation for DT302 (C)

## D – Typical Installation for 6" Up flow Tank – Sanitary Model

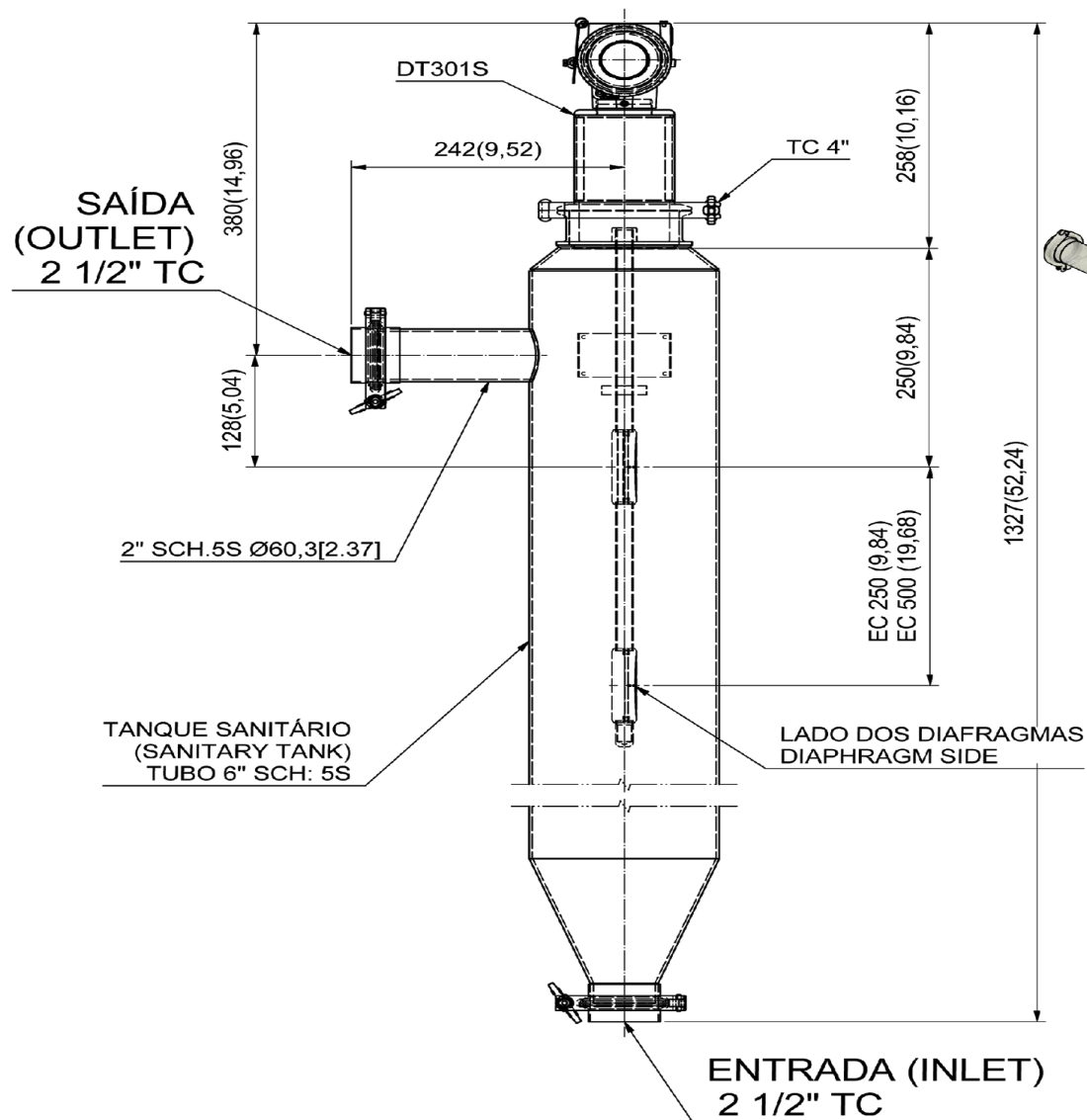
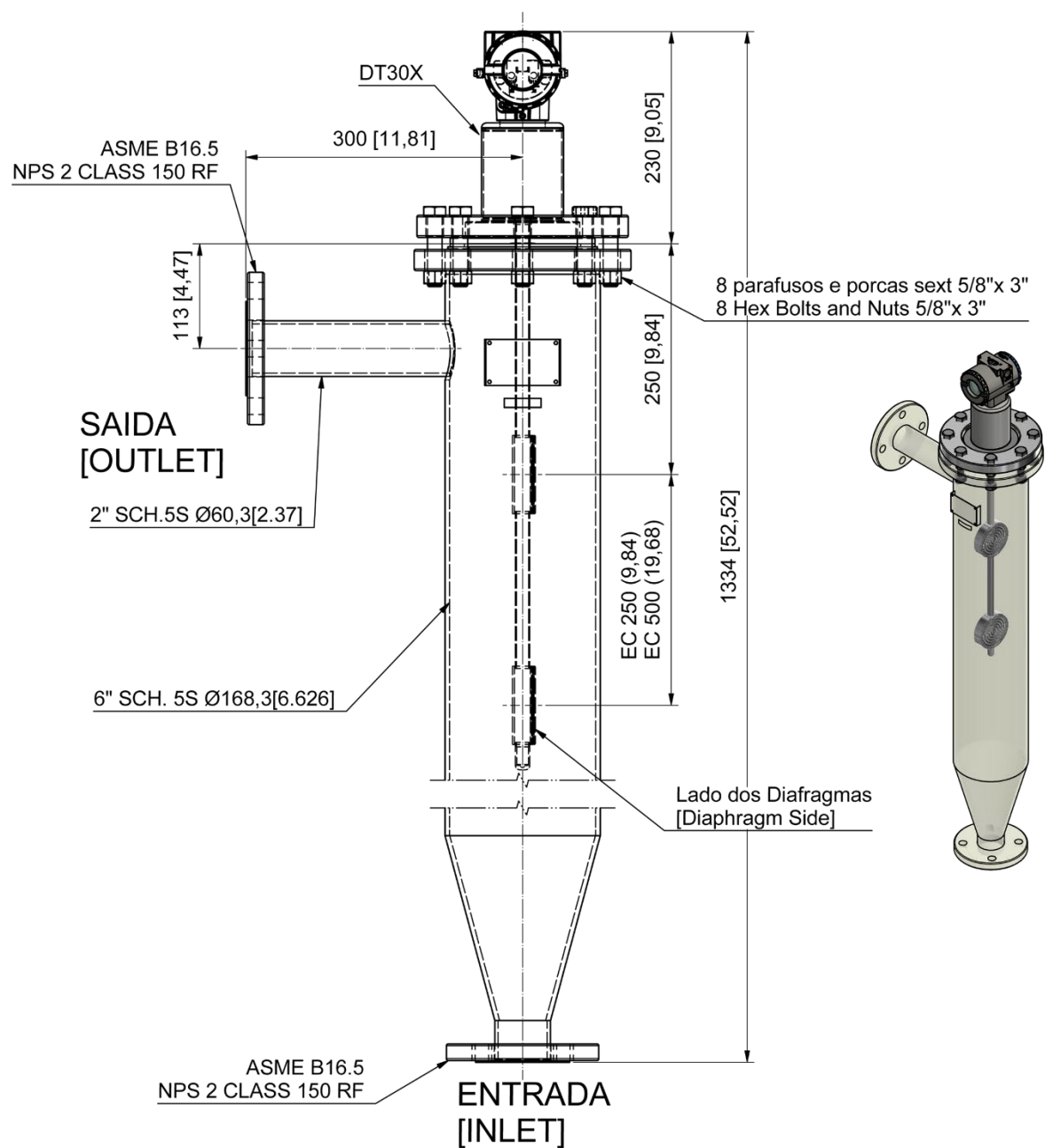


Figure 1.10 – Typical Installation for DT302 (D)

### ***E – Typical Installation for 6" Up Flow Tank***

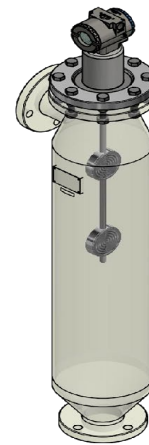
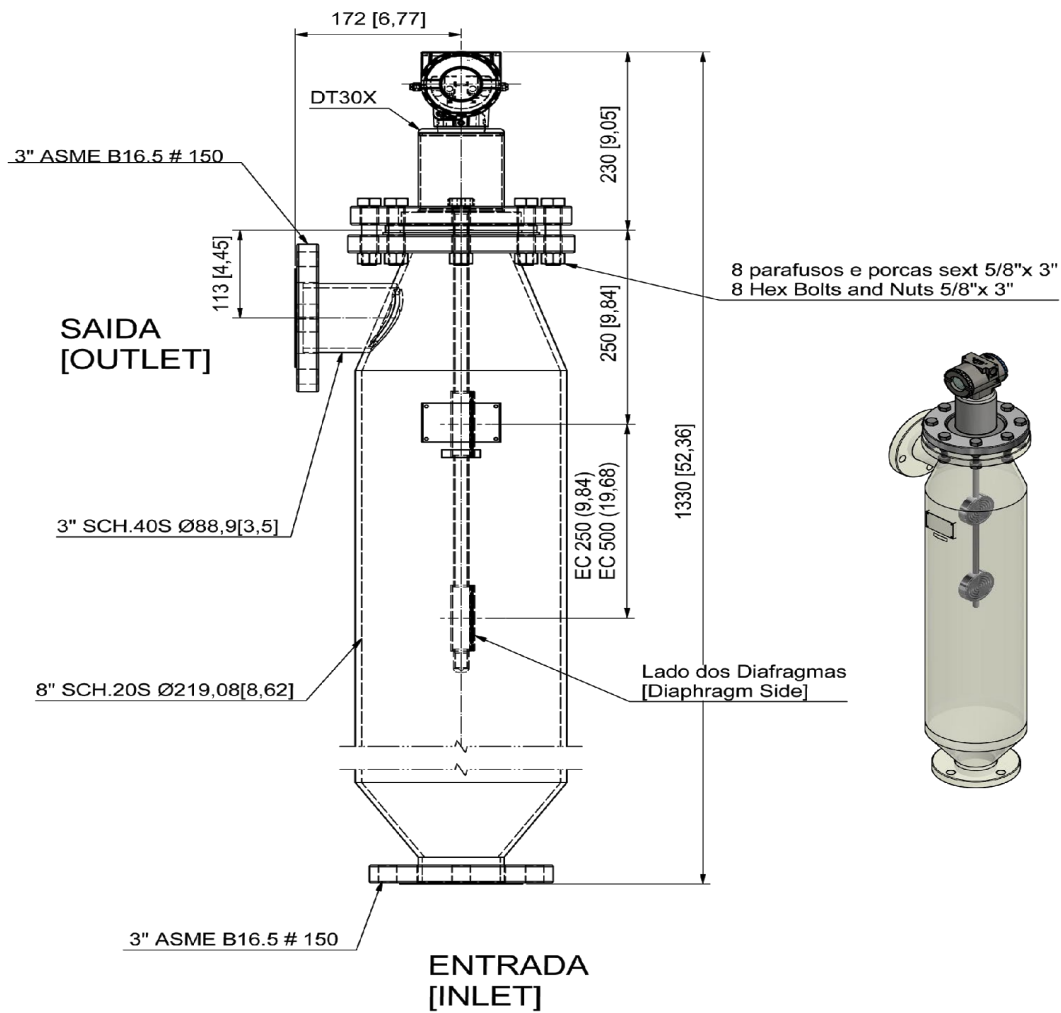
MAXIMUM FLOW =  $15\text{m}^3/\text{h}$



**Figure 1.11 – Typical Installation for DT302 (E)**

## F – Typical Installation for 8" Up Flow Tank

MAXIMUM FLOW = 27m<sup>3</sup>/h



## G - Typical Installation for 8" Up Flow Rubberized Tank

MAXIMUM FLOW = 27m<sup>3</sup>/h

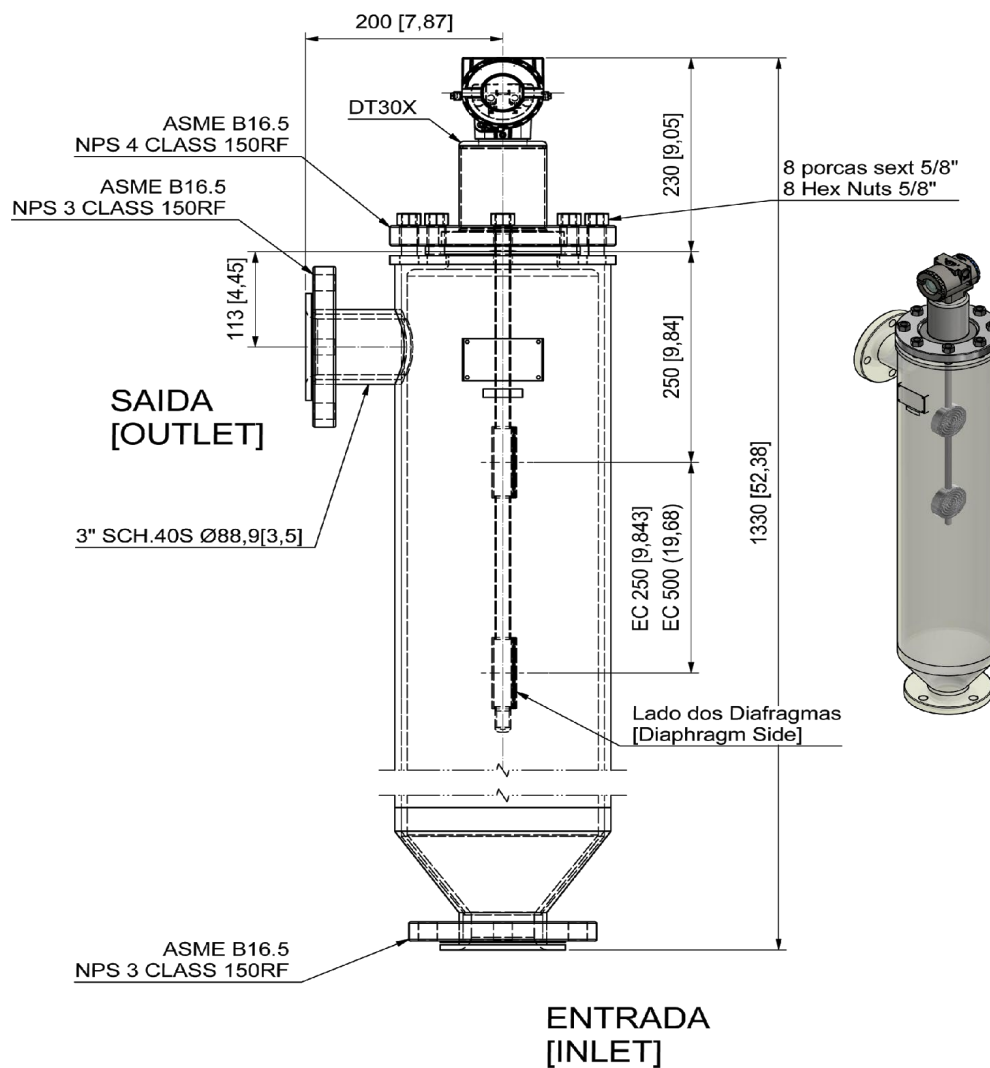


Figure 1.13 – Typical Installation for DT302 (G)

## H - Typical Installation for 12" Up Flow Tank of Overflow

MAXIMUM FLOW = 65m<sup>3</sup>/h

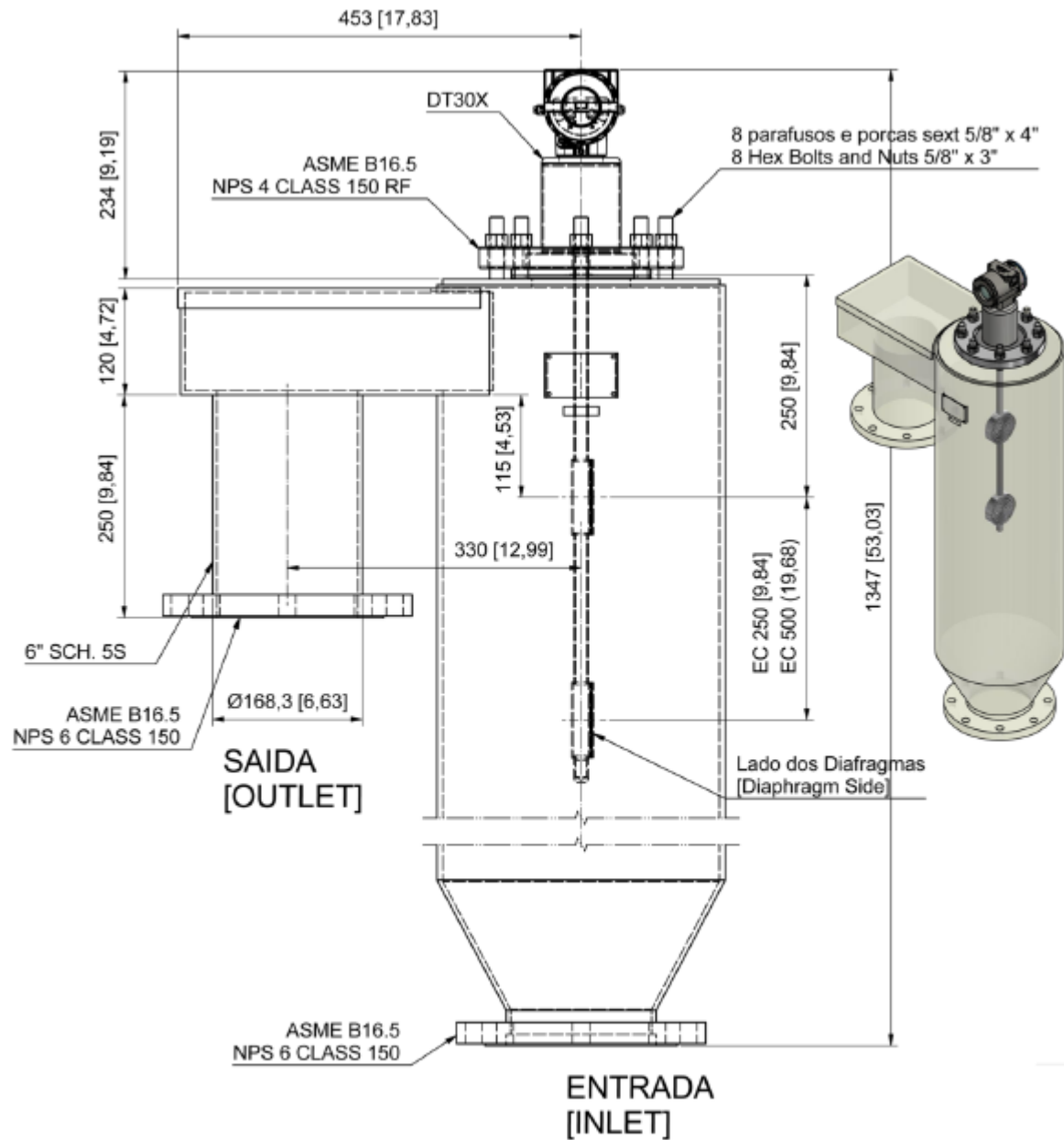


Figure 1.14 – Typical Installation for DT302 (H)



# I - Typical Installation for 12" Up Flow Rubberized Split Tank

MAXIMUM FLOW = 65m<sup>3</sup>/h

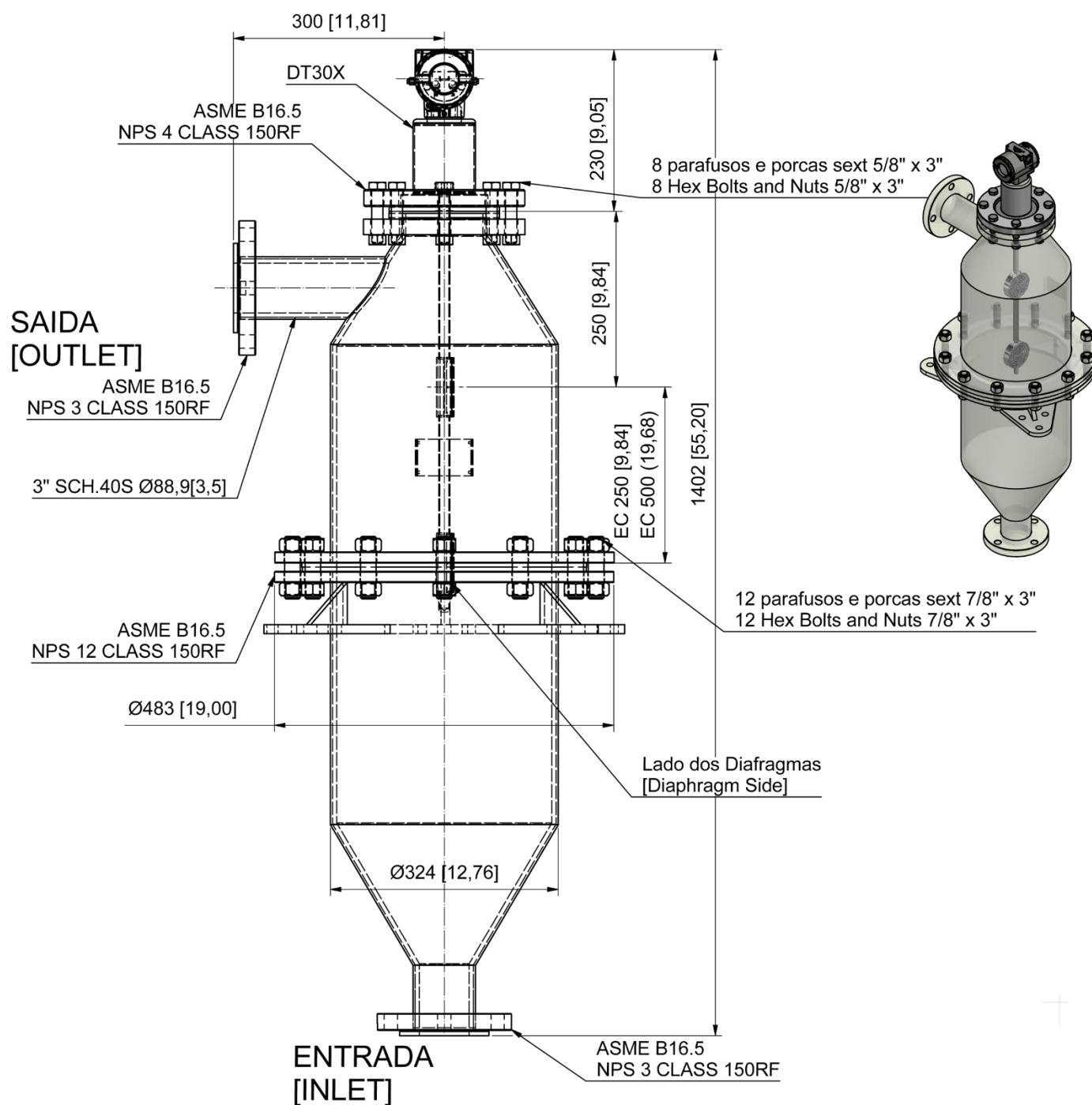
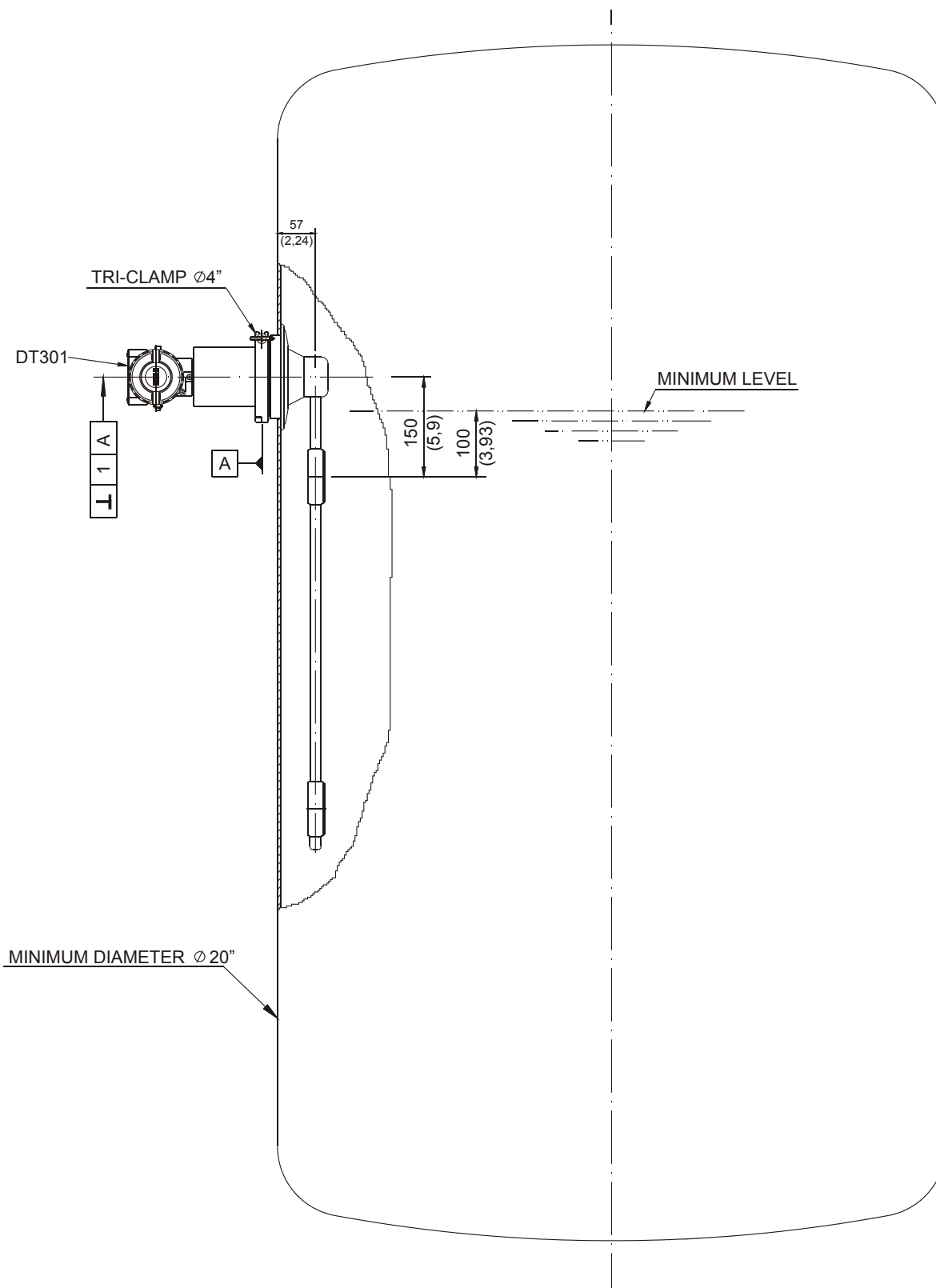


Figure 1.15 – Typical Installation for DT302 (I)



**K - Typical Installation in Tank (Sanitary Model)****Figure 1.17 – Typical Installation for DT302 (K)**

**L - Typical Installation in Tank with Diaphragm Protection (Industrial Model)**

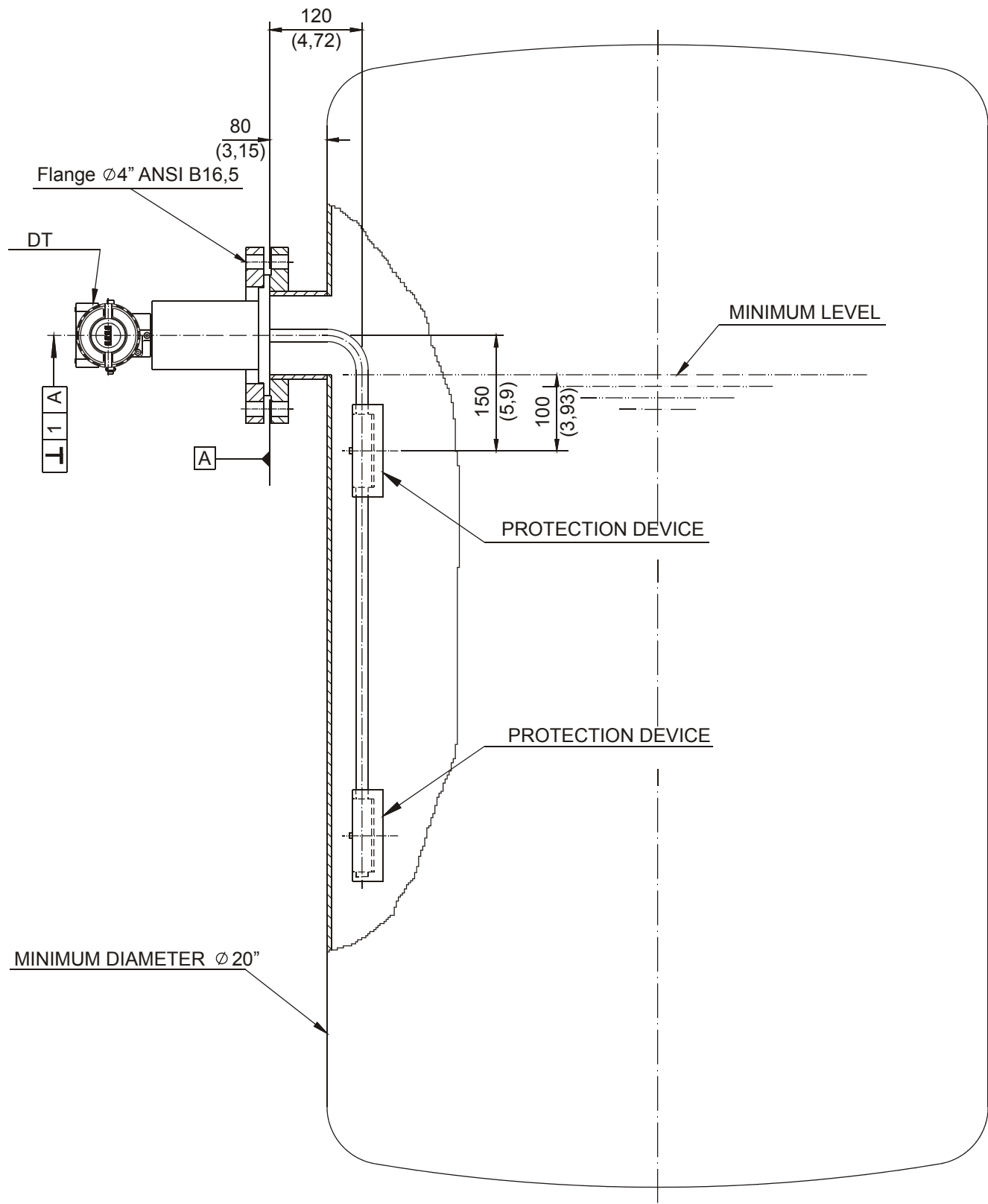
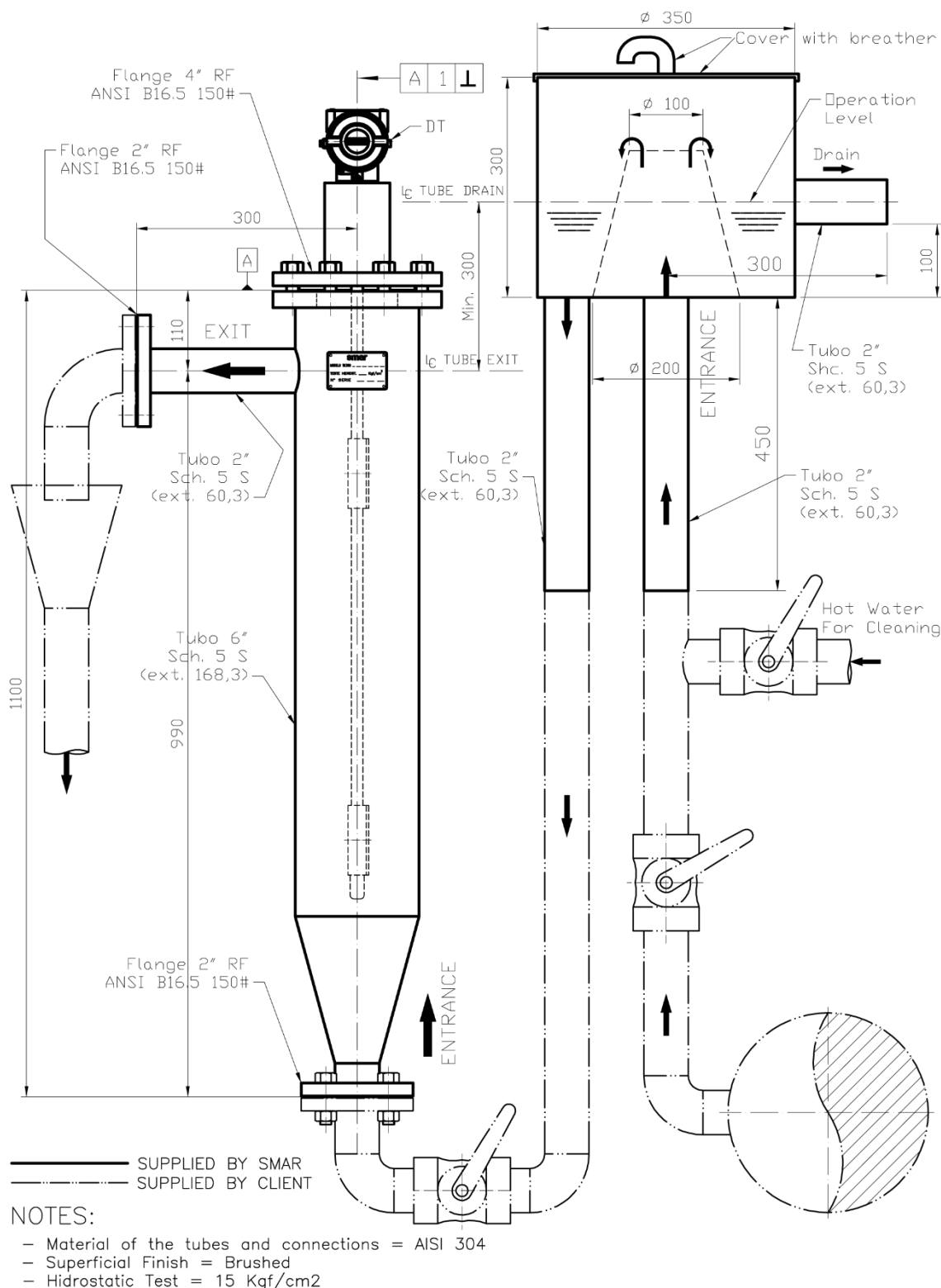


Figure 1.18 – Typical Installation for DT302 (L)

ui

***M - Typical Installation for Low Flow Tank with Bubble Breaker (Industrial Model)***



**Figure 1.19 – Typical Installation for DT302 (M)**

## N - Typical Installation in Tank for Level Interface (Industrial Model)

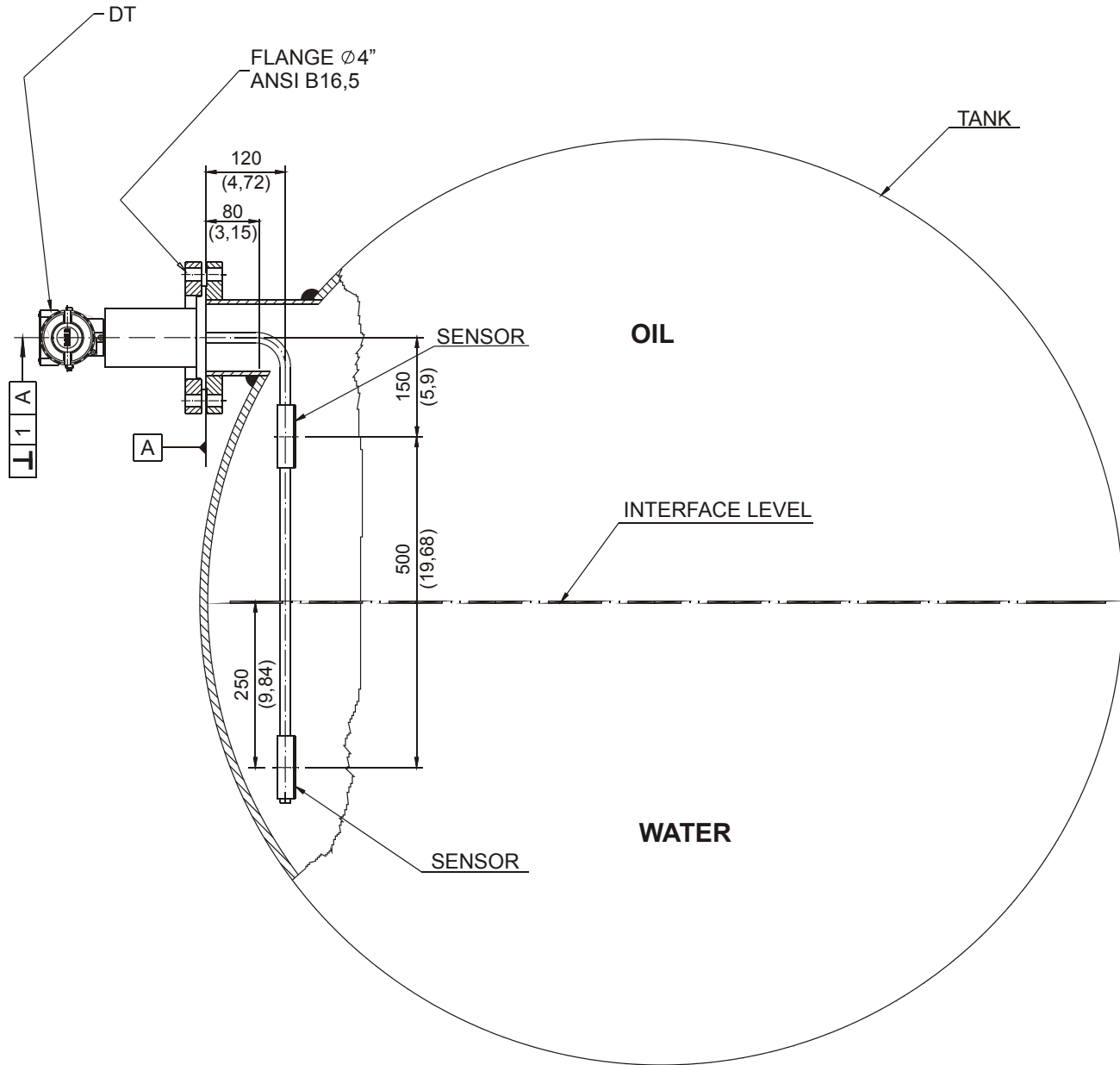


Figure 1.20 – Typical Installation for DT302 (N)

## O - Typical Installation in Tank for Level Interface Stand Pipe (Industrial Model)

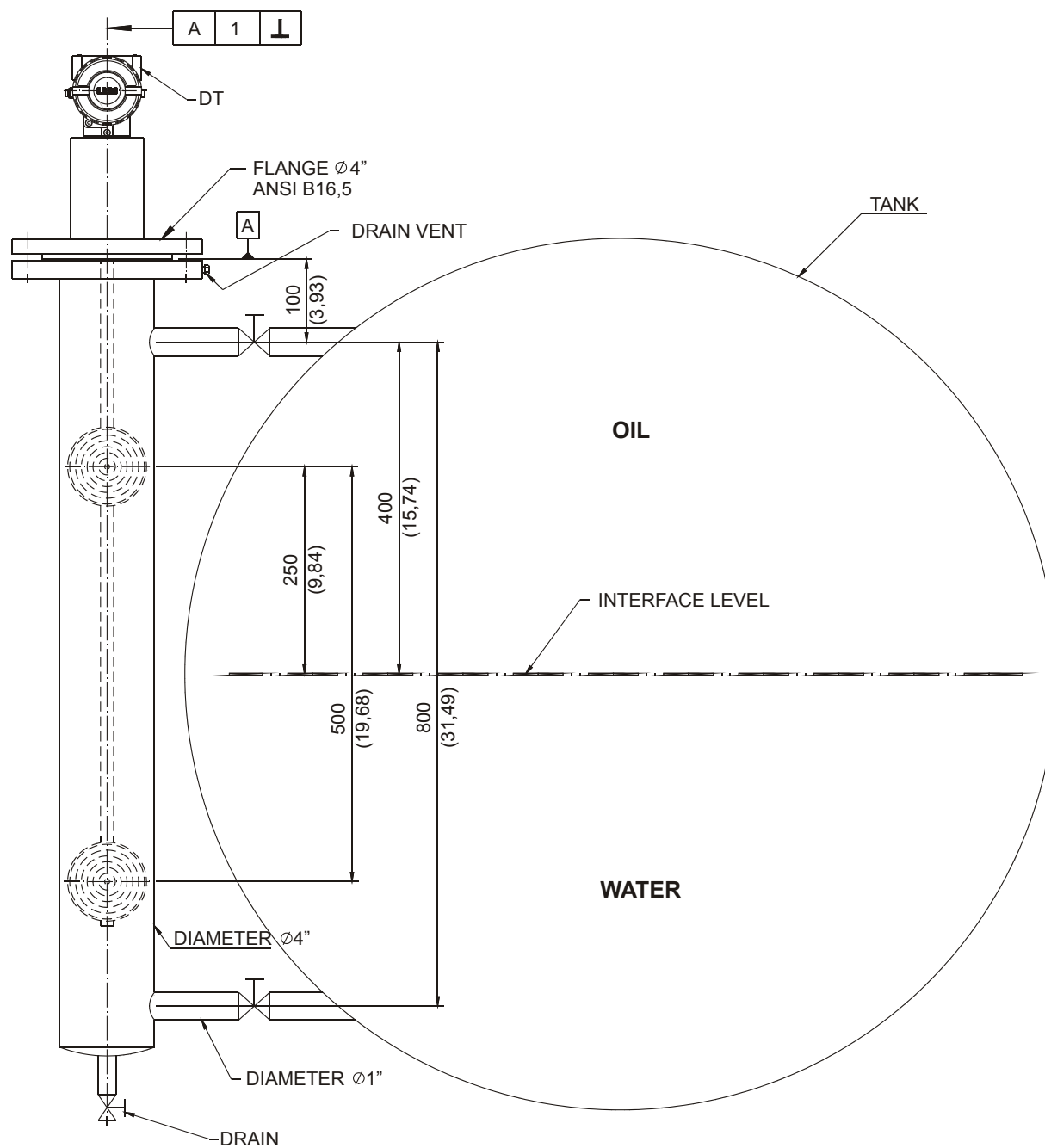
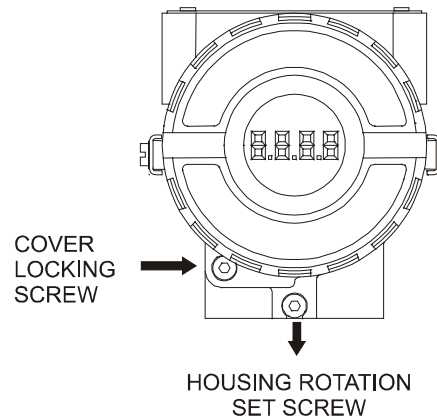


Figure 1.21 – Typical Installation for DT302 (O)

## Housing Rotation

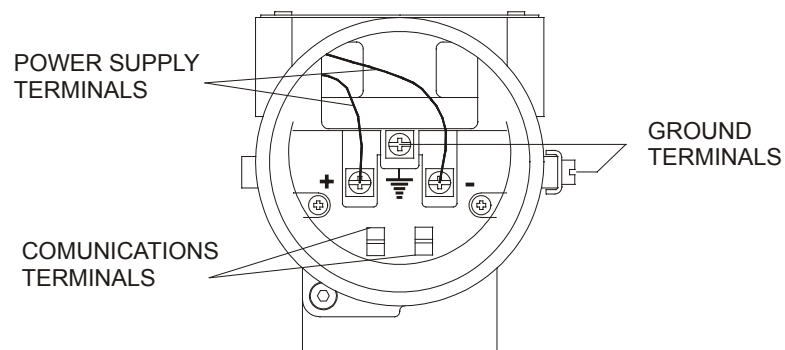
The housing can be rotated to get the digital display in better position. To rotate it, releases the Housing Rotation Set Screw. See next figure.

The digital display can also be rotated. **See Figure 4.2 – Four Possible Positions of the Display.**



**Figure 1.22 - Housing Rotation Set Screw**

For convenience there are three ground terminals: one inside the cover and two externals, located close to the conduit entries.



**Figure 1.23 - Terminal Block**

The **DT302** uses the 31.25 kbit /s voltage mode option for the physical signaling. All other devices on the same bus must use the same signaling. All devices are connected in parallel along the same pair of wires.

Various types of Fieldbus devices may be connected on the same bus.

The **DT302** receives power from the bus via the signal wiring. The power supply may come from a separate unit or from another device such as a controller or DCS.

In hazardous area, the number of devices may be limited by intrinsically safe restrictions.

The **DT302** is protected against reverse polarity, and can withstand  $\pm 35$  VDC without damage, but it will not operate when in reverse polarity.

It is recommended to use twisted pair cables. The shield must also be grounded at only one end. The ungrounded tip must be carefully insulated.



## Bus Topology and Network Configuration

### Wiring

Other types of cable may be used, other than for conformance testing. Cables with improved specifications may enable longer trunk length or superior interface immunity. Conversely, cables with inferior specifications may be used subject to length limitations for trunk and spurs plus possible nonconformance to the RF/EMI susceptibility requirements. For intrinsically safe applications, the inductance/ resistance ratio (L/R) should be less than the limit specified by the local regulatory agency for the particular implementation.

Bus topology and tree topology are supported. Both types have a trunk cable with two terminations. The devices are connected to the trunk via spurs. The spurs may be integrated in the device giving zero spur length. A spur may connect more than one device, depending on the length. Active couplers may be used to extend spur length.

Active repeaters may be used to extend the trunk length. The total cable length, including spurs, between any two devices in the Fieldbus should not exceed 1900m.

The connection of the couplers must be between 15 and 250m.

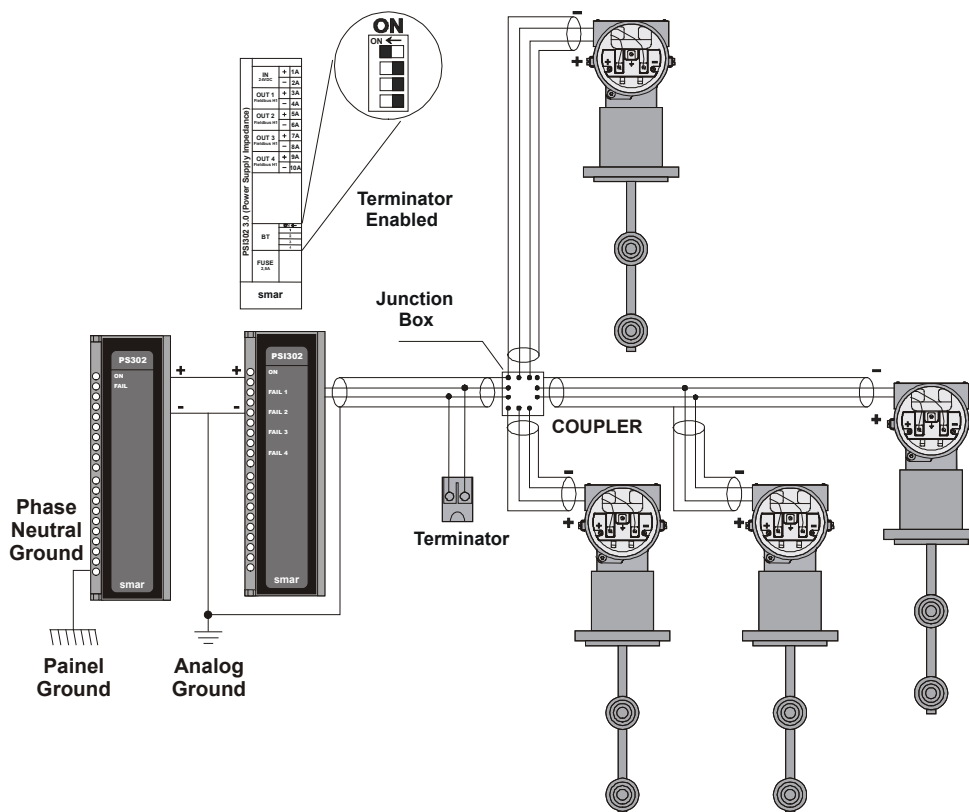


Figure 1.24 - Bus Topology

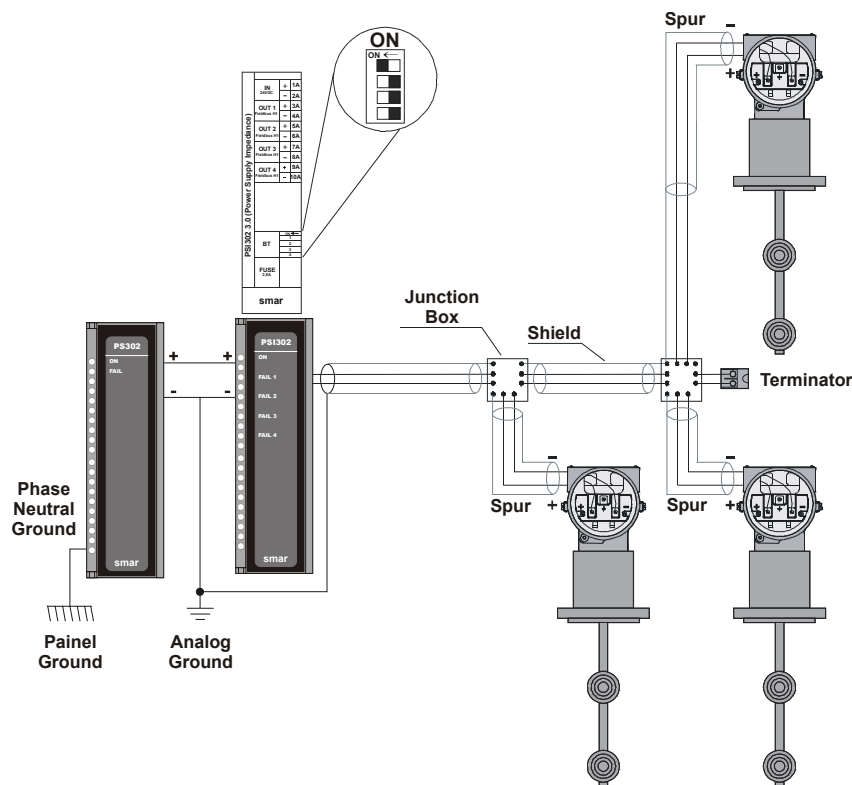


Figure 1.25 - Tree Topology

**Intrinsic Safety Barrier**

When the Fieldbus is in hazardous location with Explosive Atmosphere, the protection type “intrinsic safety (Ex-i)” can be used with a barrier inserted on the trunk between the power supply and the Fieldbus bus.

Use of DF47-12 or DF47-17 is recommended.

**Jumper Configuration**

In order to work properly, the jumpers J1 and W1 located in the **DT302** main board must be correctly configured (See *Table 1.1 - Description of the Jumpers*).

J1	This jumper enables the simulation mode parameter in the AI block.
W1	This jumper enables the local adjustment programming tree.

Table 1.1 - Description of the Jumpers

**Power Supply**

The **DT302** receives power from the bus via the signal wiring. The power supply may come from a separate unit or from another device such as a controller or DCS.

The voltage should be between 9 to 32 Vdc for non-intrinsic safe applications.

A special requirement applies to the power supply used in an intrinsically safe bus and depends on the type of barrier used.

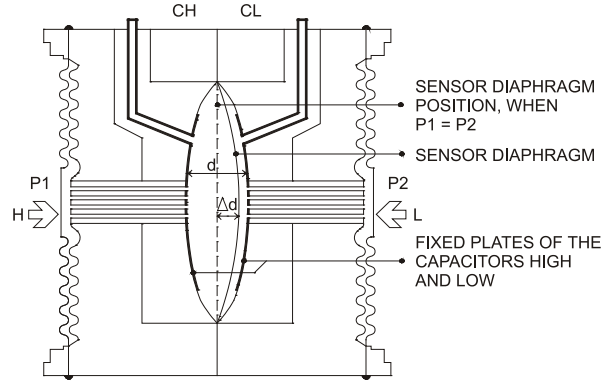
Use of **PS302** is recommended as power supply.

**Installation in Hazardous Areas**

Refer to Appendix A for certifications information.

### OPERATION

The **DT302** Concentration Density Transmitter use capacitive sensors (capacitive cells) as pressure sensing elements. This is exactly the same sensor as the DT301 series uses, the sensor modules are therefore interchangeable.



**Figure 2.1 - Capacitive Cell**

#### Functional Description - Sensor

Where,

P<sub>1</sub> and P<sub>2</sub> are the pressures and P<sub>1</sub> ≥ P<sub>2</sub>

CH = Capacitance between the fixed plate on P<sub>1</sub> side and the sensing diaphragm.

CL = Capacitance between the fixed plate on the P<sub>2</sub> side and the sensing diaphragm.

d = Distance between CH and CL fixed plates.

Δd = Sensing diaphragm's deflection due to the differential pressure ΔP = P<sub>1</sub> - P<sub>2</sub>.

Knowing that the capacitance of a capacitor with flat, parallel plates may be expressed as a function of plate area (A) and distance (d) between the plates:

$$C \approx \frac{\epsilon \times A}{d}$$

Where,

ε = Dielectric constant of the medium between the capacitor's plates.

$$CH \approx \frac{\epsilon \times A}{(d/2) + \Delta d} \quad \text{and} \quad \frac{\epsilon \times A}{(d/2) - \Delta d} \approx CL$$

However, should CH and CL be considered as capacitances of flat and parallel plates with identical areas, then:

However, should the differential pressure (ΔP) applied to the capacitive cell not deflect the sensing diaphragm beyond d/4, it is possible to assume ΔP as proportional to Δd, that is:

$$\Delta P \propto \Delta d$$

By developing the expression (CL - CH)/(CL + CH), it follows that:

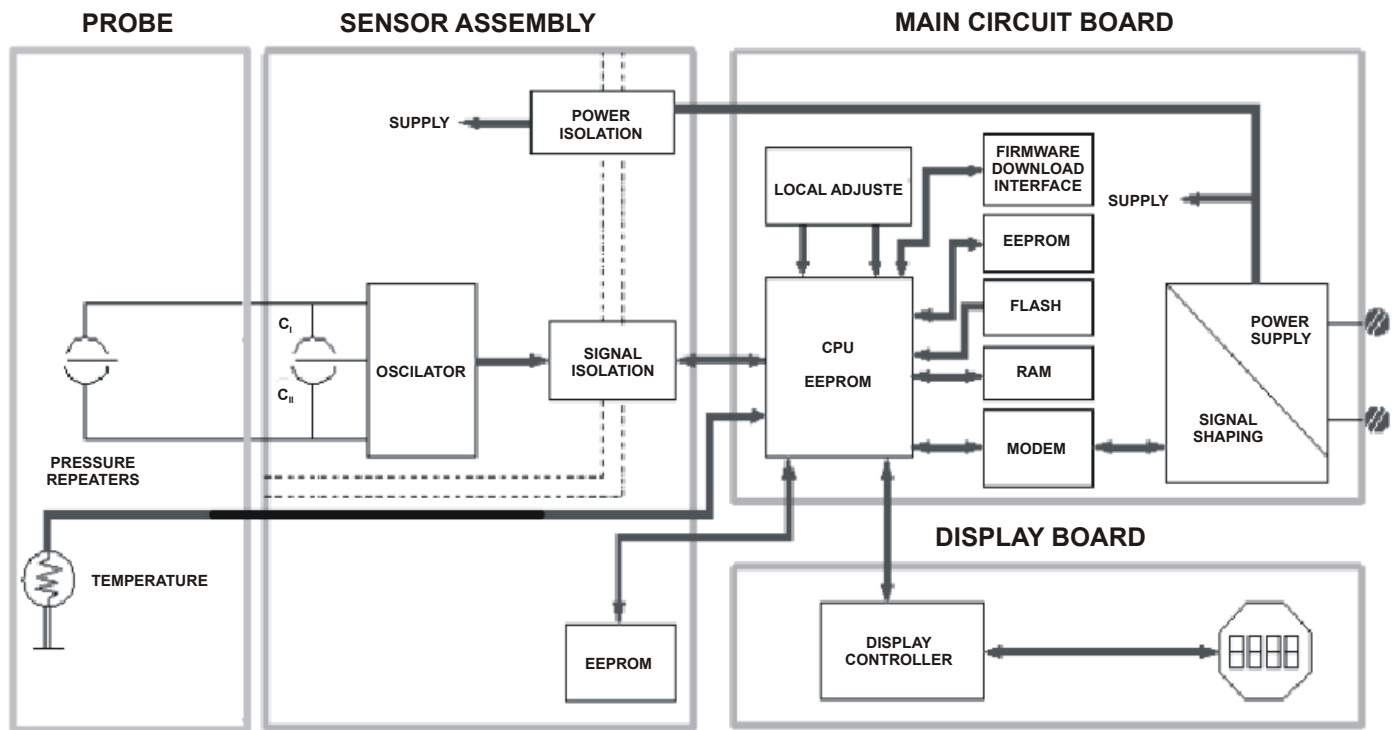
$$\frac{CL - CH}{CL + CH} = \frac{2\Delta d}{d}$$

As the distance (d) between the fixed plates CH and CL is constant. It is possible to conclude that the expression (CL - CH)/(CL + CH) is proportional to Δd and, therefore, to the differential pressure to be measured.

Thus it is possible to conclude that the capacitive cell is a pressure sensor formed by two capacitors whose capacitance varies according to the applied differential pressure.

## Functional Description – Electronics

Refer to the block diagram. The function of each block is described below.



**Figure 2.2 - DT302 Block Diagram Hardware**

### Probe

Part of the transmitter directly in contact with the process.

### Pressure Repeaters

It transfers to the capacitive sensor the differential pressure detected in the process.

### Temperature Sensor

It captures the process fluid temperature.

### Oscillator

This oscillator generates a frequency as a function of sensor capacitance.

### Signal Isolator

The control signals from the CPU and the signal from the oscillator are isolated to avoid ground loops.

### Central Processing Unit (CPU), RAM, FLASH and EEPROM

The CPU is the intelligent portion of the transmitter, being responsible for the management and operation of measurement, block execution, self-diagnostics, and communication. The program is stored in a FLASH memory for easy upgrade and saving data on power-down event occurrence. For temporary storage of data there is a RAM. The data in the RAM is lost if the power is switched off, however the main board has a nonvolatile EEPROM memory where the static data configured that must be retained is stored. Examples of such data are the following: calibration, links, and identification data.

### Sensor EEPROM

Another EEPROM is located within the sensor assembly. It contains data pertaining to the sensor's characteristics at different pressures and temperatures. This characterization is done for each sensor at the factory. It also contains the factory settings; they are useful in case of main board replacement, when it does an automatic upload of data from the sensor board to main board.

**Fieldbus Modem**

Monitors line activity, modulate and demodulate communication signals, inserts, and deletes start and end delimiters, and checks integrity of frame received.

**Power Supply**

Takes power of the loop-line to power the transmitter circuitry.

**Power Isolation**

Isolates the signals to and from the input section, the power to the input section must be isolated.

**Display Controller**

Receives data from the CPU identifying which segments on the liquid crystal display to turn on. The controller drives the backplane and the segment control signals.

**Local Adjustment**

There are two switches that are magnetically activated. They can be activated by the magnetic tool without mechanical or electrical contact.

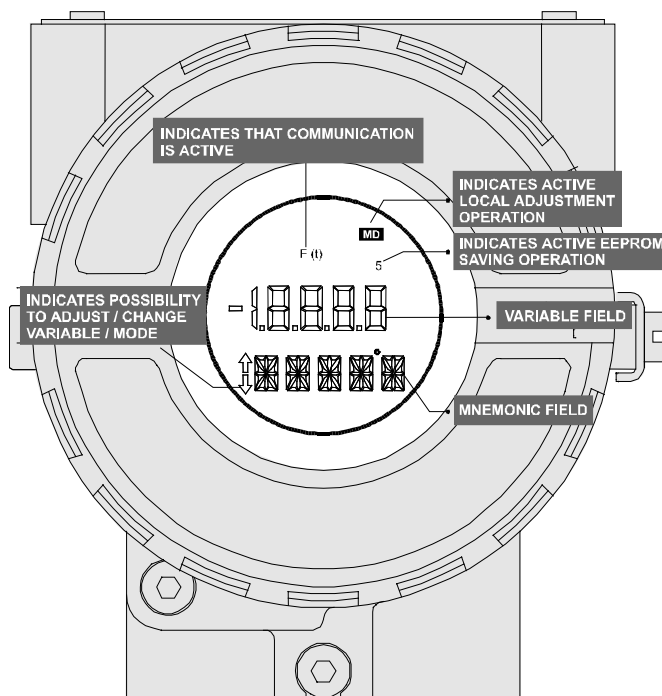
## Display

The indicator, constituted by the liquid crystal display, can show one or two variables in according to the user's selection. When it is shown two variables, the indicator will alternate between both with an interval of approximately 3 seconds.

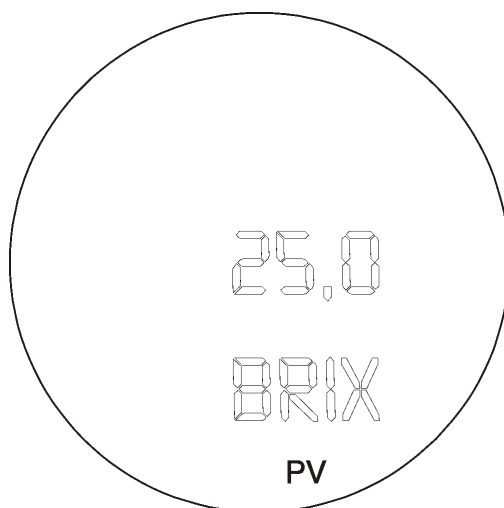
Beyond the numeric and alphanumeric fields, the display shows some alphanumeric icons to indicate the transmitter states. The figure 2.3 shows the segment configuration used by DT302 transmitter.

## Monitoring

The DT302 transmitter is continually in the monitoring mode. In this mode, the indication at the display alternates between the primary and secondary variable, according to the user's configuration. The indicator has the capacity to show the value, the engineering unit, and the variable type, simultaneously with most of the state indications. See in the figure 2.4 a sample of a DT302 standard indication.



**Figure 2.3 - LCD Indicator**



***Figure 2.4 – Typical Monitoring Mode Display Showing PV, in this case 25.0 BRIX***

## Section 3

# CONFIGURATION

One of the many advantages of Fieldbus is that device configuration is independent of the configurator. The **DT302** may be configured by a third-party terminal or operator console. Any configurator is therefore not addressed here.

The **DT302** contain one input transducer block, one resource, one display transducer block and functions blocks. Functions Blocks are not covered in this manual. For explanation and details see the "Functions Blocks Manual".

## Transducer Block

Transducer block insulates function block from the specific I/O hardware, such as sensors, actuators. Transducer block controls access to I/O through manufacturer specific implementation. This permits the transducer block to execute as frequently as necessary to obtain good data from sensors without burdening the function blocks that use the data. It also insulates the function block from the manufacturer specific characteristics of certain hardware.

By accessing the hardware, the transducer block can get data from I/O or passing control data to it. The connection between Transducer block and Function block is called channel. These blocks can exchange data from its interface. Normally, transducer blocks perform functions, such as linearization, characterization, temperature compensation, control, and exchange data to hardware.

## Transducer Block Diagram

See transducer block diagram below.

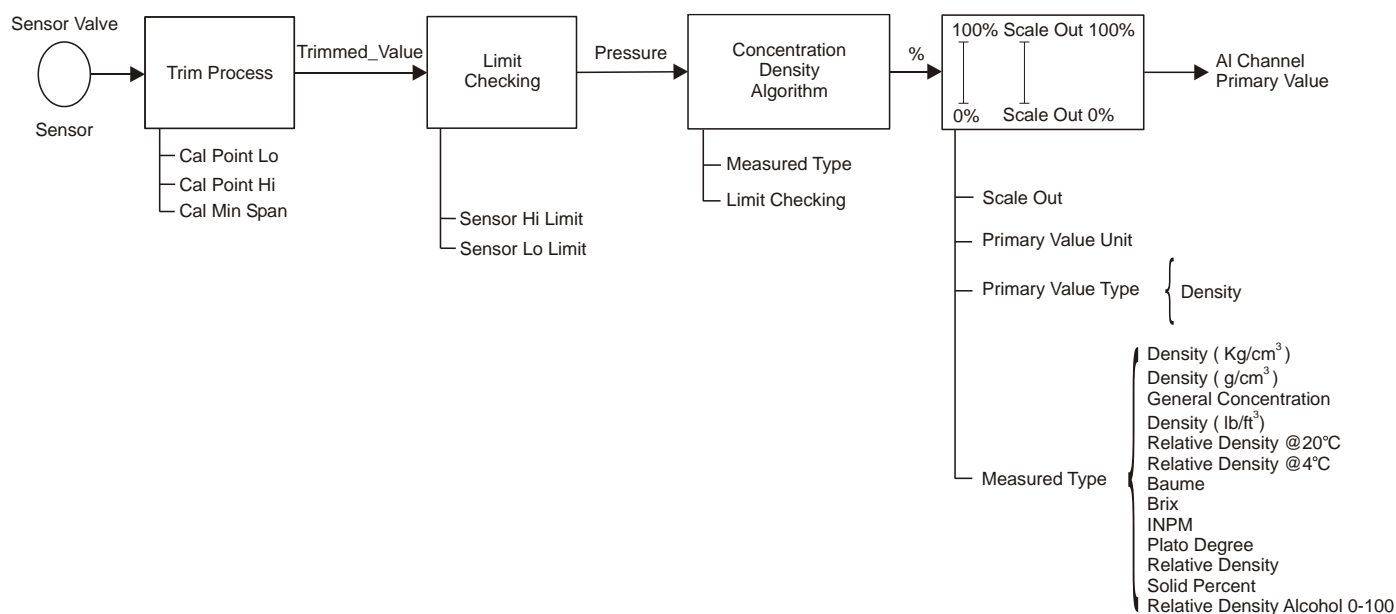


Figure 3.1 – Transducer Block Diagram

## Concentration/Density Transducer Block Parameter Description

Parameter	Description
ST_REV	Indicates the level of static data.
TAG_DESC	Transducer block description.
STRATEGY	This parameter is not checked and processed by transducer block.
ALERT_KEY	Number of identification in the plant.
MODE_BLK	Indicates the operation mode of transducer block.
BLOCK_ERR	Indicates the status associated with hardware or software in the transducer.
UPDATE_EVT	Alert for any static data.
BLOCK_ALM	Used for configuration, hardware, and other fail.
TRANSDUCER_DIRECTORY	Used to select several transducer blocks.
TRANSDUCER_TYPE	Indicates the type of transducer according to its class.
XD_ERROR	Used to indicate calibration status.
COLLECTION_DIRECTORY	Specifies the number of transducer index into transducer block.
PRIMARY_VALUE_TYPE	Defines the calculation type for transducer block.
PRIMARY_VALUE	Value and status used by channel.
PRIMARY_VALUE_RANGE	High and low range limit values, the engineering unit code and the number of digits to the right of the decimal point to be used for primary value.
CAL_POINT_HI	Highest calibrated value.
CAL_POINT_LO	Lowest calibrated value.
CAL_MIN_SPAN	Minimum calibration span value allowed. This minimum span information is necessary to ensure that when calibration is done, the two calibrated points (high and low) are not too close together.
CAL_UNIT	Device description engineering units code index for the calibration values.
SENSOR_TYPE	Type of sensor.
SENSOR_RANGE	Range of sensor.
SENSOR_SN	Serial number of sensor.
SENSOR_CAL_METHOD	Method of last sensor calibration. ISO defines several standard methods of calibration. This parameter is intended to record that method, or if some other method was used.
SENSOR_CAL_LOC	Location of last sensor calibration. This describes the physical location at which the calibration was performed.
SENSOR_CAL_DATE	Date of the last sensor calibration.
SENSOR_CAL_WHO	Name of person who is in charge of last calibration.
SENSOR_ISOLATION_MTL	Defines the construction material of the isolating diaphragms.
SENSOR_FLUID	Defines the type of fill fluid used in the sensor.
SECONDARY_VALUE	Secondary value (temperature value), related to the sensor.
SECONDARY_VALUE_UNIT	Engineering units to be used with SECONDARY_VALUE.
PRESS_LIN_NORMAL	Linear normalized pressure value.
PRESS_NORMAL	Normalized pressure value.
PRESS_CUTOFF	Cutoff pressure value.
CUTOFF_FLAG	Bypass flag for Pressure value.
DIGITAL_TEMPERATURE	Digital temperature value.
DIFF	Differential pressure value.
YDIFF	Differential pressure value.
CAPACITANCE_LOW	Low capacitance value.
CAPACITANCE_HIGH	High capacitance value.
BACKUP_RESTORE	This parameter is used to do backup or to restore configuration data.
SENSOR_RANGE_CODE	Indicates the sensor range code.
COEFF_POL0	Polynomial coefficient 0.
COEFF_POL1	Polynomial coefficient 1.
COEFF_POL2	Polynomial coefficient 2.
COEFF_POL3	Polynomial coefficient 3.
COEFF_POL4	Polynomial coefficient 4.
COEFF_POL5	Polynomial coefficient 5.
COEFF_POL6	Polynomial coefficient 6.
COEFF_POL7	Polynomial coefficient 7.
COEFF_POL8	Polynomial coefficient 8.
COEFF_POL9	Polynomial coefficient 9.
COEFF_POL10	Polynomial coefficient 10.
COEFF_POL11	Polynomial coefficient 11.
POLYNOMIAL_VERSION	Indicates the polynomial version.
CHARACTERIZATION_TYPE	Indicates the type of characterization curve.
CURVE_BYPASS_LD	Enable and disable the characterization curve.
CURVE_LENGTH	Indicates the length of characterization curve.
CURVE_X	Input points of characterization curve.
CURVE_Y	Output points of characterization curve.
CAL_POINT_HI_BACKUP	Indicates the backup for high calibration point.



Parameter	Description
CAL_POINT_LO_BACKUP	Indicates the backup for low calibration point.
CAL_POINT_HI_FACTORY	Indicates the factory high calibration point.
CAL_POINT_LO_FACTORY	Indicates the factory low calibration point.
CAL_TEMPERATURE	Defines the temperature calibration point.
DATASHEET	Indicates information about the sensor.
ORDERING_CODE	Indicates information about the sensor and control from factory production.
MAXIMUM_MEASURED_PRESSURE	Indicates the maximum pressure measured.
MAXIMUM_MEASURED_TEMPERATURE	Indicates the maximum temperature measured.
ACTUAL_OFFSET	Indicates the actual calibrated offset.
ACTUAL_SPAN	Indicates the actual span offset.
MAXIMUM_OFFSET_DEVIATION	Defines the maximum offset before an alarm is generated.
MAXIMUM_GAIN_DEVIATION	Defines the maximum gain before an alarm is generated.
OVERPRESSURE_LIMIT	Defines the maximum overpressure limit before an alarm is generated.
MAXIMUM_NUMBER_OF_OVERPRESSURE	Defines the maximum number of overpressure before an alarm is generated.
GRAVITY	Gravity acceleration used in concentration/density calculation. The unit is m/s <sup>2</sup> .
HEIGHT	Distance between the two pressure sensors. The unit is m.
MEASURED_TYPE	When the transducer type is density, it allows to measure: 0 - Density (g/cm <sup>3</sup> ), 1 - Density (Kg/m <sup>3</sup> ), 2 - Relative Density @ 20°C (g/cm <sup>3</sup> ), 3 - Relative Density @ 4°C (g/cm <sup>3</sup> ), 4 - Baume, 5 - Brix, 6 - Plato Degree, 7 - INPM, 8 - Relative Density Alcohol 0 - 100, 9 - Solid Percent, 10 - Density (lb/ft <sup>3</sup> ) 11 - API
LIN_DILATATION_COEF	Linear dilatation coefficient.
PRESSURE_COEFFICIENT	Coefficient of pressure.
TEMP_ZERO	Offset coefficient used to calculate the temperature.
TEMP_GAIN	Gain coefficient used to calculate the temperature.
ZERO_ADJUST_TEMP	Temperature of zero adjustment.
HEIGHT_MEAS_TEMP	Temperature of measurement of distance between the pressure sensors.
AUTO_CAL_POINT_LO	This parameter enables the lower self-calibration point. The sensor should be in air and the MEASURED_TYPE and XD_SCALE.UNIT should be Kg/cm <sup>3</sup> . The calibration point is 1.2 Kg/cm <sup>3</sup> .
AUTO_CAL_POINT_HI	This parameter enables the upper self-calibration point. The sensor should be on water and the MEASURED_TYPE and XD_SCALE.UNIT should be Brix. The calibration point is 0 Brix.
SOLID_POL_COEFF_0	Solid percent polynomial coefficient 0.
SOLID_POL_COEFF_1	Solid percent polynomial coefficient 1.
SOLID_POL_COEFF_2	Solid percent polynomial coefficient 2.
SOLID_POL_COEFF_3	Solid percent polynomial coefficient 3.
SOLID_POL_COEFF_4	Solid percent polynomial coefficient 4.
SOLID_POL_COEFF_5	Solid percent polynomial coefficient 5.
SOLID_LIMIT_LO	Solid percent limit low.
SOLID_LIMIT_HI	Solid percent limit high.
PRESS_COMP	Value used by the factory.
SIMULATE_PRESS_ENABLE	Enable the concentration simulation mode.
SIMULATE_PRESS_VALUE	Simulate pressure value in mmH <sub>2</sub> O at 68 °F. Used together with SIMULATE_PRESS_ENABLE.
SIMULATE_DENSITY_VALUE	Density value used to obtain the correspondent pressure.
CALCULATED_PRESS_VALUE	Pressure calculated according to the SIMULATE_DENSITY_VALUE.
CALC_PRESS_CAL_POINT_LO	Calculated pressure value by AUTO_CAL_POINT_LO procedure.
CALC_PRESS_CAL_POINT_HI	Calculated pressure value by AUTO_CAL_POINT_HI procedure.
DT_RANGE_CODE	<b>DT302</b> range code, depending on the probe size: 250 mm: Range 1 (0 to 3 g/cm <sup>3</sup> ) Range 2 (0 to 10 g/cm <sup>3</sup> ) 500 mm: Range 1 (0 to 2 g/cm <sup>3</sup> ) Range 2 (0 to 10 g/cm <sup>3</sup> ) 800 mm: Range 1 (0.35 to 1,6 g/cm <sup>3</sup> ) Range 2 (0.35 to 7 g/cm <sup>3</sup> )
DENSITY_KGM3	Density Value in Kg/m <sup>3</sup> .
DENSITY_STATUS	Density status information such as temperature between limits.
CONC	18 polynomial terms.
HI_LIM_DENS	Density upper limit for generic concentration.
LO_LIM_DENS	Density lower limit for generic concentration.
HI_LIM_TEMP	Temperature upper limit for generic concentration.
LO_LIM_TEMP	Temperature lower limit for generic concentration.
K_DENS	Density constant used to calculate generic concentration.
K_TEMP	Temperature constant used to calculate generic concentration.
MOUNTING_POSITION	Indicates de probe assembly position (direct or reverse).

Table 3.1 – Concentration/Density Transducer Block Parameter Description

## Concentration/Density Transducer Block Parameter Attributes

Relative Index	Parameter Mnemonic	Object Type	Data Type	Store	Size	Access	Default –value
1	ST_REV	Simple	Unsigned16	S	2	R/W	0
2	TAG_DESC	Simple	VisibleString	S	32	R/W	TRD BLOCK
3	STRATEGY	Simple	Unsigned16	S	2	R/W	0
4	ALERT_KEY	Simple	Unsigned8	S	1	R/W	0
5	MODE_BLK	Record	DS-69	S	4	R/W	O/S
6	BLOCK_ERR	Simple	Bit String	D	2	R	
7	UPDATE_EVT	Record	DS-73	D	5	R	
8	BLOCK_ALM	Record	DS-72	D	13	R	
9	TRANSDUCER_DIRECTORY	Simple	Array of Unsigned16	N	Variable	R	
10	TRANSDUCER_TYPE	Simple	Unsigned16	N	2	R	100
11	XD_ERROR	Simple	Unsigned8	D	1	R	0
12	COLLECTION_DIRECTORY	Simple	Array of Unsigned 32	S	Variable	R	
13	PRIMARY_VALUE_TYPE	Simple	Unsigned16	S	2	R/W	107
14	PRIMARY_VALUE	Record	DS-65	D	5	R	0
15	PRIMARY_VALUE_RANGE	Record	DS-68	S	11	R	
16	CAL_POINT_HI	Simple	Float	S	4	R/W	5080.0
17	CAL_POINT_LO	Simple	Float	S	4	R/W	0.0
18	CAL_MIN_SPAN	Simple	Float	S	4	R	0.0
19	CAL_UNIT	Simple	Unsigned16	S	2	R	1149
20	SENSOR_TYPE	Simple	Unsigned16	S	1	R/W	117
21	SENSOR_RANGE	Record	DS-68	S	11	R	0-100%
22	SENSOR_SN	Simple	Unsigned32	S	4	R/W	0
23	SENSOR_CAL_METHOD	Simple	Unsigned8	S	1	R/W	103
24	SENSOR_CAL_LOC	Simple	VisibleString	S	32	R/W	NULL
25	SENSOR_CAL_DATE	Simple	Time of Day	S	7	R/W	
26	SENSOR_CAL_WHO	Simple	VisibleString	S	32	R/W	NULL
27	SENSOR_ISOLATION_MTL	Simple	Unsigned16	S	2	R/W	2
28	SENSOR_FLUID	Simple	Unsigned16	S	2	R/W	1
29	SECONDARY_VALUE	Record	DS-65	D	5	R	0
30	SECONDARY_VALUE_UNIT	Simple	Unsigned16	S	2	R	1001 (°C)
31	PRESS_LIN_NORMAL	Record	DS-65	D	5	R	0
32	PRESS_NORMAL	Record	DS-65	D	5	R	0
33	PRESS_CUTOFF	Record	DS-65	D	5	R	0
34	CUTOFF_FLAG	Simple	Unsigned8	S	1	R/W	True
35	DIGITAL_TEMPERATURE	Record	DS-65	D	5	R	0
36	DIFF	Simple	Float	D	4	R	0
37	YDIFF	Simple	Float	D	4	R	0
38	CAPACITANCE_LOW	Simple	Float	D	4	R	0
39	CAPACITANCE_HIGH	Simple	Float	D	4	R	0
40	BACKUP_RESTORE	Simple	Unsigned8	S	1	R/W	0
41	SENSOR_RANGE_CODE	Simple	Unsigned16	S	2	R/W	1
42	COEFF_POL0	Simple	Float	S	4	R/W	-1
43	COEFF_POL1	Simple	Float	S	4	R/W	0
44	COEFF_POL2	Simple	Float	S	4	R/W	1
45	COEFF_POL3	Simple	Float	S	4	R/W	0
46	COEFF_POL4	Simple	Float	S	4	R/W	2
47	COEFF_POL5	Simple	Float	S	4	R/W	0
48	COEFF_POL6	Simple	Float	S	4	R/W	0
49	COEFF_POL7	Simple	Float	S	4	R/W	0
50	COEFF_POL8	Simple	Float	S	4	R/W	0
51	COEFF_POL9	Simple	Float	S	4	R/W	0
52	COEFF_POL10	Simple	Float	S	4	R/W	0
53	COEFF_POL11	Simple	Float	S	4	R/W	25
54	POLYNOMIAL_VERSION	Simple	Unsigned8	S	1	R/W	32
55	CHARACTERIZATION_TYPE	Simple	Unsigned8	S	1	R/W	255
56	CURVE_BYPASS_LD	Simple	Unsigned16	S	2	R/W	Enable&Backup Cal
57	CURVE_LENGTH	Simple	Unsigned8	S	1	R/W	5

Relative Index	Parameter Mnemonic	Object Type	Data Type	Store	Size	Access	Default –value
58	CURVE_X	Record	Array of Float	S	20	R/W	
59	CURVE_Y	Record	Array of Float	S	20	R/W	
60	CAL_POINT_HI_BACKUP	Simple	Float	S	4	R	5080
61	CAL_POINT_LO_BACKUP	Simple	Float	S	4	R	0
62	CAL_POINT_HI_FACTORY	Simple	Float	S	4	R	5080
63	CAL_POINT_LO_FACTORY	Simple	Float	S	4	R	0
64	CAL_TEMPERATURE	Simple	Float	S	4	R/W	17.496
65	DATASHEET	Record	Array of Unsigned8	S	10	R/W	
66	ORDERING_CODE	Simple	VisibleString	S	50	R/W	NULL
67	MAXIMUM_MEASURED_PRESSURE	Simple	Float	S	4	R/w	- INF
68	MAXIMUM_MEASURED_TEMPERATURE	Simple	Float	S	4	R/W	- INF
69	ACTUAL_OFFSET	Simple	Float	S	4	R	
70	ACTUAL_SPAN	Simple	Float	S	4	R	
71	MAXIMUM_OFFSET_DEVIATION	Simple	Float	S	4	R/W	0.5
72	MAXIMUM_GAIN_DEVIATION	Simple	Float	S	4	R/W	2.0
73	OVERPRESSURE_LIMIT	Simple	Float	S	4	R/W	+ INF
74	MAXIMUM_NUMBER_OF_OVERPRESSURE	Simple	Float	S	4	R/W	0
75	GRAVITY	Simple	Float	S	4	R/W	9.80665
76	HEIGHT	Simple	Float	S	4	R/W	0.500
77	MEASURED_TYPE	Simple	Float	S	4	R/W	0
78	LIN_DILATATION_COEF	Simple	Float	S	4	R/W	0.000016
79	PRESSURE_COEFFICIENT	Simple	Float	S	4	R/W	
80	TEMP_ZERO	Simple	Float	S	4	R/W	-30
81	TEMP_GAIN	Simple	Float	S	4	R/W	0.5
82	ZERO_ADJUST_TEMP	Simple	Float	S	4	R/W	20
83	HEIGHT_MEAS_TEMP	Simple	Float	S	4	R/W	0.5
84	AUTO_CAL_POINT_LO	Simple	Float	S	4	R/W	0
85	AUTO_CAL_POINT_HI	Simple	Float	S	4	R/W	0
86	SOLID_POL_COEFF_0	Simple	Float	S	4	R/W	0
87	SOLID_POL_COEFF_1	Simple	Float	S	1	R/W	1
88	SOLID_POL_COEFF_2	Simple	Float	S	4	R/W	0
89	SOLID_POL_COEFF_3	Simple	Float	S	4	R/W	0
90	SOLID_POL_COEFF_4	Simple	Float	S	4	R/W	0
91	SOLID_POL_COEFF_5	Simple	Float	S	4	R/W	0
92	SOLID_LIMIT_LO	Simple	Float	S	4	R/W	0
93	SOLID_LIMIT_HI	Simple	Float	S	4	R/W	100
94	PRESS_COMP	Simple	Float	D	4	R	0
95	SIMULATE_PRESS_ENABLE	Simple	Unsigned 8	D	1	R/W	Disable
96	SIMULATE_PRESS_VALUE	Simple	Float	D	4	R/W	0
97	SIMULATE_DENSITY_VALUE	Simple	Float	D	4	R/W	0
98	CALCULATED_PRESS_VALUE	Simple	Float	D	4	R	0
99	CALC_PRESS_CAL_POINT_LO	Simple	Float	D	4	R	0
100	CALC_PRESS_CAL_POINT_HI	Simple	Float	D	4	R	0
101	DT_RANGE_CODE	Simple	Unsigned 8	S	1	R/W	0
102	DENSITY_KGM3	Simple	Float	S	4	R	-
103	DENSITY_STATUS	Simple	Unsigned	S	1	R	-
104	CONC	Record	Array of Float	D	72	R/W	0
105	HI_LIM_DENS	Simple	Float	D	4	R/W	0
106	LO_LIM_DENS	Simple	Float	D	4	R/W	0
107	HI_LIM_TEMP	Simple	Float	D	4	R/W	0
108	LO_LIM_TEMP	Simple	Float	D	4	R/W	0
109	K_DENS	Simple	Float	D	4	R/W	1
110	K_TEMP	Simple	Float	D	4	R/W	1
111	MOUNTING_POSITION	Simple	Unsigned	D	1	R/W	-

Table 3.2 – Concentration/Density Transducer Blocks Parameter Attributes

## Concentration/Density Transducer Block View Object

Relative Index	Parameter Mnemonic	View_1	View_2	View_3	View_4
1	ST_REV	2	2		2
2	TAG_DESC				
3	STRATEGY				2
4	ALERT_KEY				1
5	MODE_BLK	4			
6	BLOCK_ERR	2			
7	UPDATE_EVT				
8	BLOCK_ALM				
9	TRANSDUCER_DIRECTORY				
10	TRANSDUCER_TYPE	2	2	5	2
11	XD_ERROR	1			
12	COLLECTION_DIRECTORY			5	
13	PRIMARY_VALUE_TYPE		2	5	
14	PRIMARY_VALUE	5			
15	PRIMARY_VALUE_RANGE				11
16	CAL_POINT_HI		4	5	
17	CAL_POINT_LO		4	4	
18	CAL_MIN_SPAN			4	4
19	CAL_UNIT			4	2
20	SENSOR_TYPE			4	2
21	SENSOR_RANGE				11
22	SENSOR_SN				4
23	SENSOR_CAL_METHOD				1
24	SENSOR_CAL_LOC				
25	SENSOR_CAL_DATE				
26	SENSOR_CAL_WHO				
27	SENSOR_ISOLATION_MTL				2
28	SENSOR_FLUID				2
29	SECONDARY_VALUE	5			
30	SECONDARY_VALUE_UNIT		2		
31	PRESS_LIN_NORMAL				
32	PRESS_NORMAL				
33	PRESS_CUTOFF				
34	CUTOFF_FLAG				
35	DIGITAL_TEMPERATURE				
36	DIFF				
37	YDIFF				
38	CAPACITANCE_LOW				
39	CAPACITANCE_HIGH				
40	BACKUP_RESTORE				1
41	SENSOR_RANGE_CODE				2
42	COEFF_POL0				4
43	COEFF_POL1				4
44	COEFF_POL2				4
45	COEFF_POL3				4
46	COEFF_POL4				4
47	COEFF_POL5				4
48	COEFF_POL6				4
49	COEFF_POL7				4
50	COEFF_POL8				4
51	COEFF_POL9				4
52	COEFF_POL10				4
53	COEFF_POL11				4
54	POLYNOMIAL_VERSION				1
55	CHARACTERIZATION_TYPE		1		
56	CURVE_BYPASS_LD		2	52	
57	CURVE_LENGTH		1		
58	CURVE_X		20		
59	CURVE_Y		20		
60	CAL_POINT_HI_BACKUP		4		
61	CAL_POINT_LO_BACKUP		4		
62	CAL_POINT_HI_FACTORY				
63	CAL_POINT_LO_FACTORY				
64	CAL_TEMPERATURE				

Relative Index	Parameter Mnemonic	View_1	View_2	View_3	View_4
65	DATASHEET				
66	ORDERING_CODE				
67	MAXIMUM_MEASURED_PRESSURE				
68	MAXIMUM_MEASURED_TEMPERATURE				
69	ACTUAL_OFFSET				
70	ACTUAL_SPAN				
71	MAXIMUM_OFFSET_DEVIATION				
72	MAXIMUM_GAIN_DEVIATION				
73	OVERPRESSURE_LIMIT				
74	MAXIMUM_NUMBER_OF_OVERPRESSURE				
75	GRAVITY				
76	HEIGHT				
77	MEASURED_TYPE				
78	LIN_DILATATION_COEF				
79	PRESSURE_COEFFICIENT				
80	ZERO_ADJUST_TEMP				
81	HEIGHT_MEAS_TEMP				
82	TEMP_ZERO				
83	TEMP_GAIN				
84	AUTO_CAL_POINT_LO				
85	AUTO_CAL_POINT_HI				
86	SOLID_POL_COEFF_0				
87	SOLID_POL_COEFF_1				
88	SOLID_POL_COEFF_2				
89	SOLID_POL_COEFF_3				
90	SOLID_POL_COEFF_4				
91	SOLID_POL_COEFF_5				
92	SOLID_LIMIT_LO				
93	SOLID_LIMIT_HI				
94	PRESS_COMP				
95	SIMULATE_PRESS_ENABLE				
96	SIMULATE_PRESS_VALUE				
97	SIMULATE_DENSITY_VALUE				
98	CALCULATED_PRESS_VALUE				
99	CALC_PRESS_CAL_POINT_LO				
100	CALC_PRESS_CAL_POINT_HI				
101	DT_RANGE_CODE				
102	DENSITY_KGM3				
103	DENSITY_STATUS				
104	CONC				
105	HI_LIM_DENS				
106	LO_LIM_DENS				
107	HI_LIM_TEMP				
108	LO_LIM_TEMP				
109	K_DENS				
110	K_TEMP				
111	MOUNTING_POSITION				
	TOTAL	21 bytes	68 bytes	52 bytes	99 bytes

Table 3.3 Concentration/Density Transducer Block View Object

## How to Configure the Transducer Block

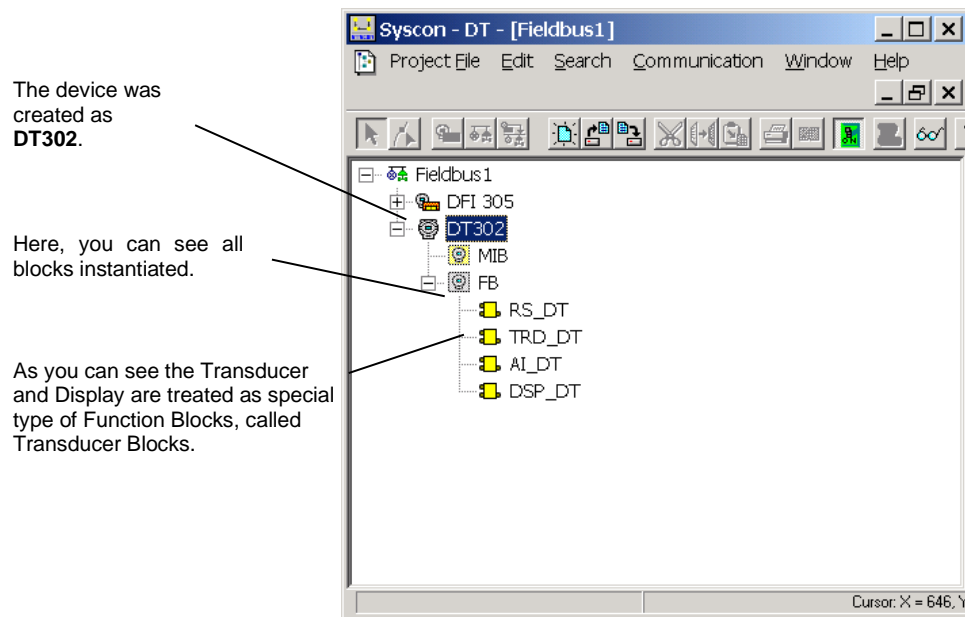
The transducer block has an algorithm, a set of contained parameters and a channel connecting it to a function block.

The algorithm describes the behavior of the transducer as a data transfer function between the I/O hardware and other function block. Transducer parameters cannot be linked to inputs and outputs of other blocks. They can be divided into Standard and Manufacturer Specific.

The standard parameters will be present for such class of device, as density, pressure, temperature, actuator, etc., whatever is the manufacturer. Oppositely, the manufacturers' specific ones are defined only for its manufacturer. As common manufacturer specific parameters, we have calibration settings, material information, linearization curve, etc.

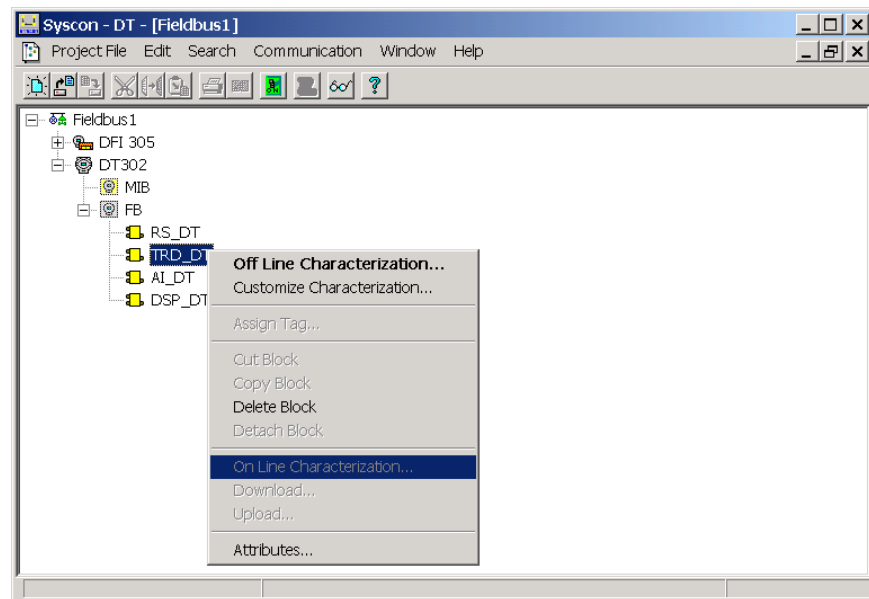
When a standard routine is performed, such as a calibration, the user is conducted step by step by a method. The method is generally defined as guideline to help the user to make common tasks. The

configuration tool identifies each method associated to the parameters and enables the interface to it. The Syscon (System Configurator) configuration software from Smar, for example, can configure many parameters of the blocks.

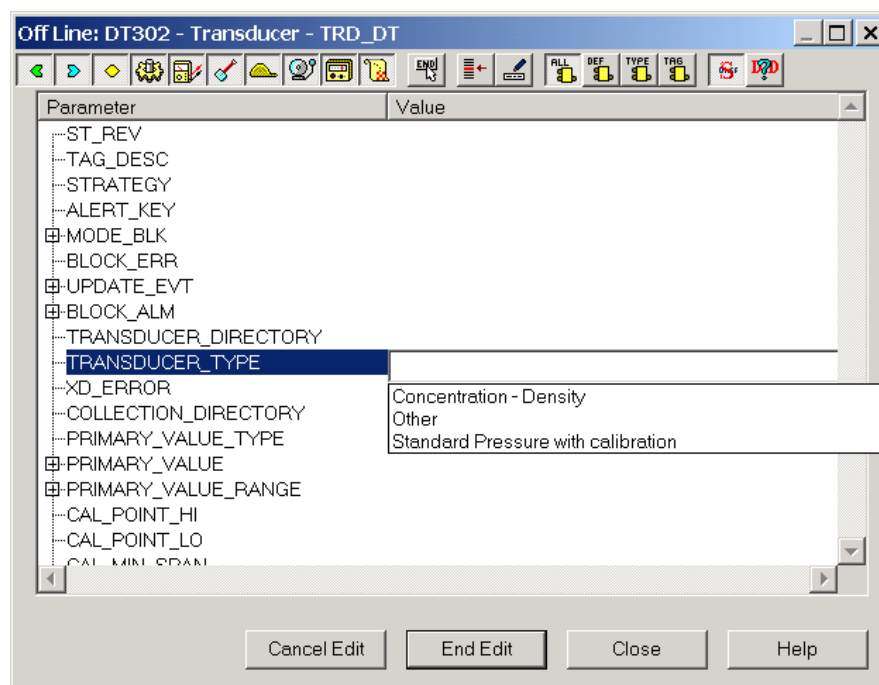


**Figure 3.2 - Function and Transducers Blocks**

To configure the Transducer Block, is necessary to select it and right click with the mouse to choose 'On Line Configuration'.

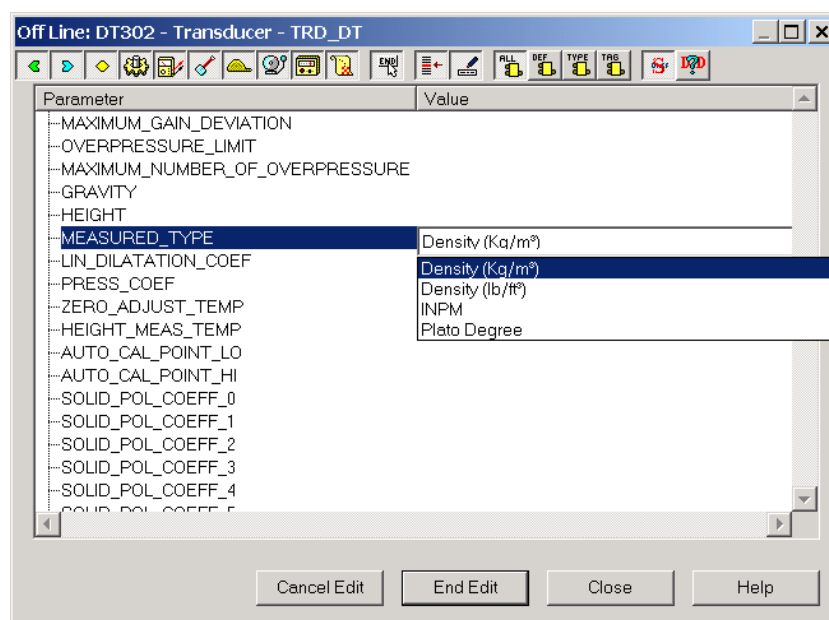


**Figure 3.3 - Online Configuration – Transducer**



**Figure 3.4 - Transducer Type Configuration**

Using this window, the user can set the transducer type according to the application, selecting "Density".



**Figure 3.5 - Measured Type Configuration**

Also, the user can select the Measured Type, choosing Density ( $\text{g/cm}^3$ ), Density ( $\text{Kg/m}^3$ ), Relative Density @  $20^\circ\text{C}$  ( $\text{g/cm}^3$ ), Relative Density @  $4^\circ\text{C}$  ( $\text{g/cm}^3$ ), Baumé, Brix, Plato Degree, INPM, Relative Density Alcohol 0 - 100, Solid Percent, Density ( $\text{lb/ft}^3$ ) and API.

## Engineering Unit Selection

The user can also choose the Measured\_Type:

- Density (g/cm<sup>3</sup>)
- Density (Kg/m<sup>3</sup>)
- Relative Density @ 20°C
- Relative Density @ 4°C
- Generic Concentration
- Baume
- Brix
- Plato Degree
- INPM
- GL
- Solid Percent
- Density (lb/ft<sup>3</sup>)
- API.

### Solid Percent (% sol)

The concentration/ density transmitter **DT302** offers resources with the objective of relating Baume degree to solid percent.

The general equation to determine the solid percent is:

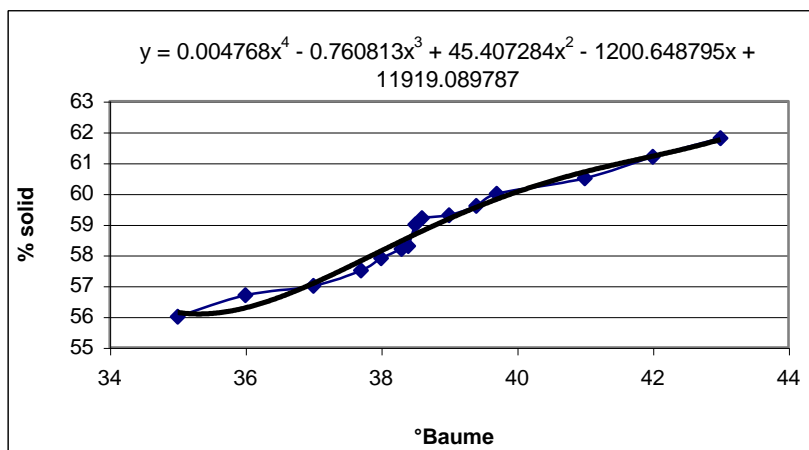
$$\%sol = a0 + a1 \text{ bme}^1 + a2 \text{ bme}^2 + a3 \text{ bme}^3 + a4 \text{ bme}^4 + a5 \text{ bme}^5$$

The table and the graph below indicate the application of the **DT302** polynomial that relates Baume degree to solid percent, generating the polynomial:

$$y = 0.004768x^4 - 0.760813x^3 + 45.407284x^2 - 1200.648795x + 11919.089787.$$

	X	Y
1	Bme	%SOL.
2	35	56
3	36	56,7
4	37	57
5	37,7	57,5
6	38	57,9
7	38,3	58,2
8	38,4	58,3
9	38,5	59
10	38,6	59,2
11	39	59,3
12	39,4	59,6
13	39,7	60
14	41	60,5
15	42	61,2
16	43	61,8

POLYNOMIAL REGRESSION



### Generic Concentration Percentage (% conc)

For applications that demand other relation among measures, the polynomial used is:

$$f(a,d,t) = a_0 + a_1 d + a_2 d^2 + a_3 d^3 + a_4 d^4 + a_5 d^5 + a_6 d t + a_7 d^2 t + a_8 d^3 t + a_9 d t^2 + a_{10} d^2 t^2 + a_{11} d^3 t^2 + a_{12} d^3 t^3 + a_{13} t + a_{14} t^2 + a_{15} t^3 + a_{16} t^4 + a_{17} t^5$$

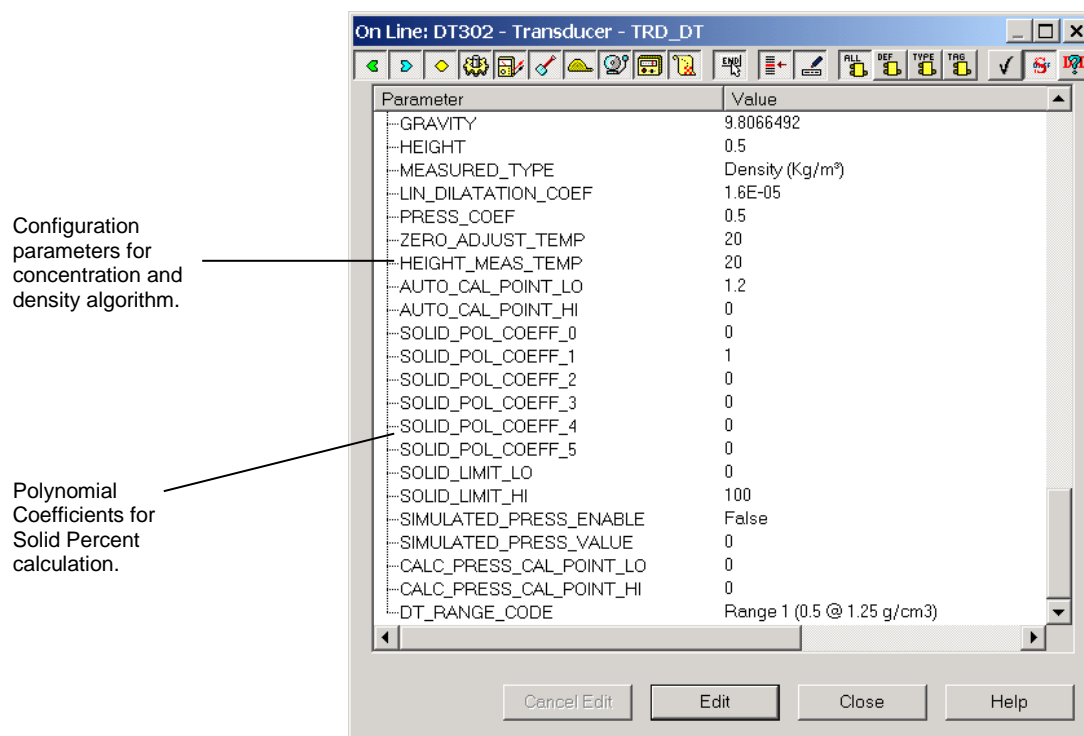
This function is applied to a higher number of applications. It relates three measurements: density, temperature and concentration.

As the digital display used in DT302 is of 4 ½ digits, the maximum indicated value would be 19999. When selecting the unit, be certified that in your application the value won't surpass 19999.



**WARNING**

The XD\_SCALE from transducer block should follow the measured type unit and its range; otherwise an error is going to appear in the XD\_ERROR.



**Figure 3.6 – Density Parameters**

Concentration/Density Values for scale of AI XD_SCALE					
Measured Type	Range 1		Range 2		AI Unit
	Lower	Upper	Lower	Upper	
Density (g/cm³)	0	3	0	10	g/cm³
Density (Kg/m³)	0	3000	0	10000	Kg/m³
Density (lb/ft³)	0	187,28	0	624,28	lb/ft³
Relative Density @ 20°C	0	3	0	10	-
Relative Density @ 4°C	0	3	0	10	-
Baume	-5	55	-5	55	degBaum
Brix	-10	110	-10	110	degBrix
Plato Degree	-10	110	-10	110	%Plato
INPM	-10	110	-10	110	INPM
GL	-10	110	-10	110	GL
Solid Percent	-10	110	-10	110	%Soli/wt
API	-10	110	-10	110	API

## How to Configure the Analog Input Block

The Analog Input block takes the input data from the Transducer block, selected by channel number, and makes it available to other function blocks at its output. When the Measured Type is changed in the transducer block, the unit and the range of XD\_SCALE must be changed too. Optionally, a filter may be applied in the process value signal, whose time constant is PV\_FTIME.

Considering a step change to the input, this is the time in seconds to the PV reaches 63.2 % of the final value. If the PV\_FTIME value is zero, the filter is disabled. For more details, please, see the Function Blocks Specifications.

To configure the Analog Input Block in offline mode, please, go to the main menu and select "Device Offline Configuration - Analog Input Block. Using this window, the user can configure the block mode operation, selects the channel, scales and unit for input and output value and the damping.

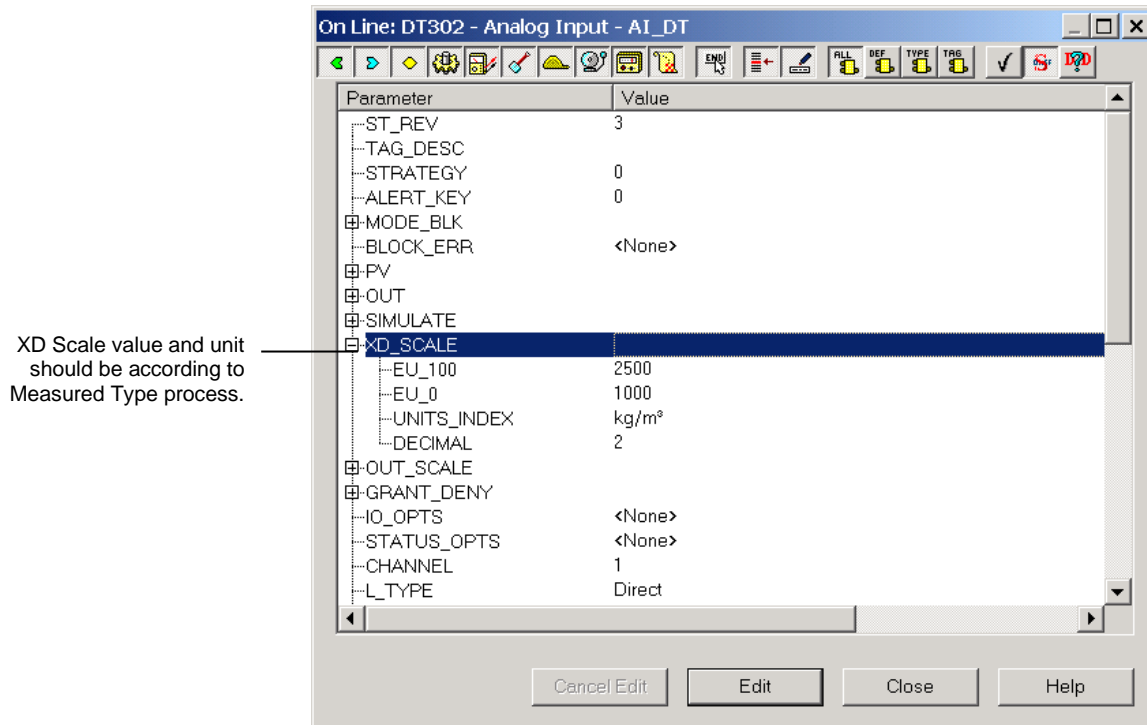


Figure 3.7 – AI Block – XD\_SCALE Configuration

## Lower and Upper Concentration/ Density Calibration

Each sensor has a characteristic curve that establishes a relation between the applied pressure, the sensor signal, and the measured concentration/density. This curve is determined for each sensor and it is stored in a memory together with the sensor. When the sensor is connected to the transmitter circuit, the content of its memory is made available to the microprocessor.

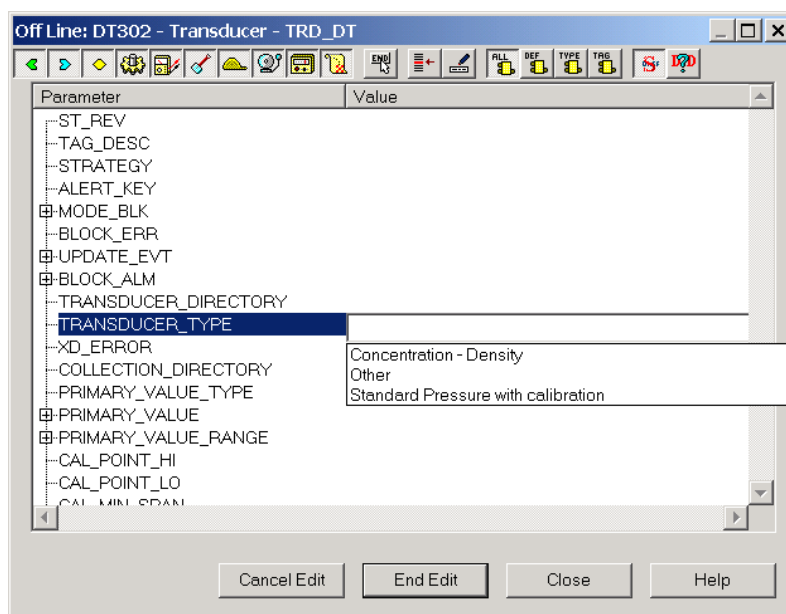
Sometimes the value on the transmitter display and transducer block reading may not match the applied pressure.

The reasons may be:

- The transmitter mounting position.
- The user's pressure standard differs from the factory standard.
- The transmitter had its original characterization shifted by over pressurization, over heating or by long term drift.

The calibration is used to match the reading with the correct concentration/density.

Please, sure that the **DT302** is measuring concentration/density. Open the Transducer Block and see the Transducer Type parameter. Please, see the following figure:



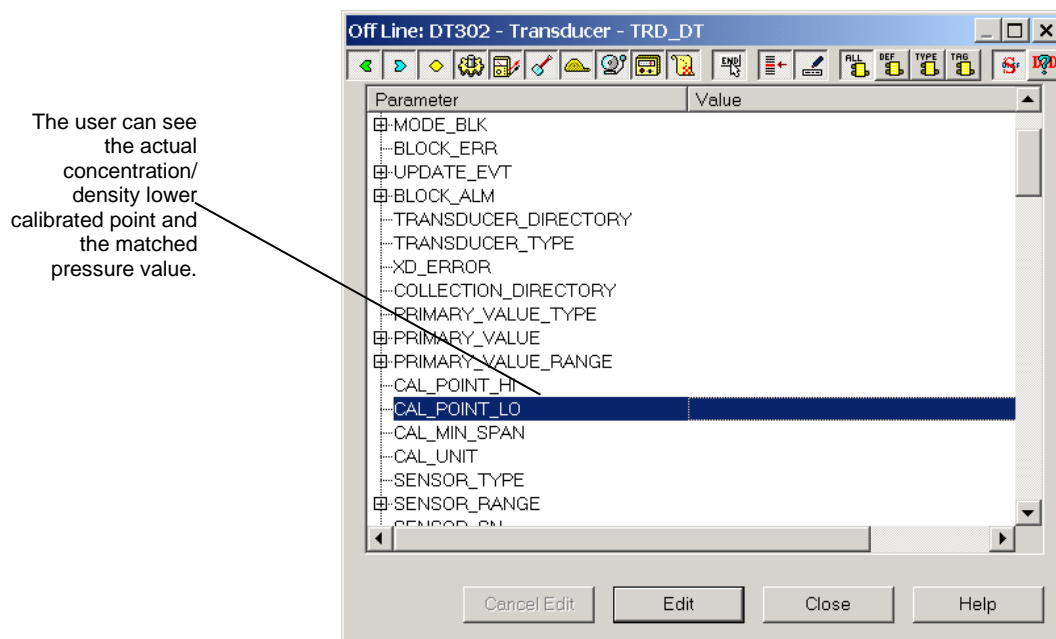
**Figure 3.8 – Transducer Block – Transducer Type Selection**

If is required an adjustment of unit, please just select the desired unit using the measured type parameter according to the application. If the adjust requires a changing of measured values, please, calibrate the device with reference, according to these steps:

- Wait the process stabilization and collect a sample.
- Determine in laboratory the value of density/concentration of stabilized process.

Using the **Syscon** (or any configuration tool), the user can select the measured type and the lower and upper calibration procedure.

If the user selects lower or upper page, the following window is shown and the user can see the actual calibrated point, the primary value and status and the result of calibration procedure:



**Figure 3.9 – Concentration / Density Calibration**

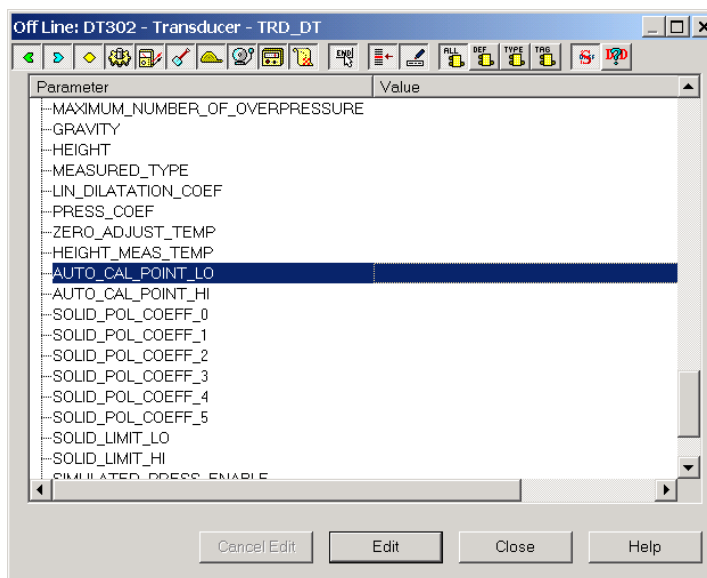
The calibrated point must be inside of the sensor range limits allowed for each type of concentration/density measuring.

## Lower and Upper Concentration/ Density Self-Calibration

With self-calibration it is possible to perform an accurate calibration of the equipment. In this procedure the air density is used as reference (in Kg/m<sup>3</sup>) and water concentration (in BRIX). These references are used because it is easy to have it on the field.

### Lower Calibration (Air Self-Calibration)

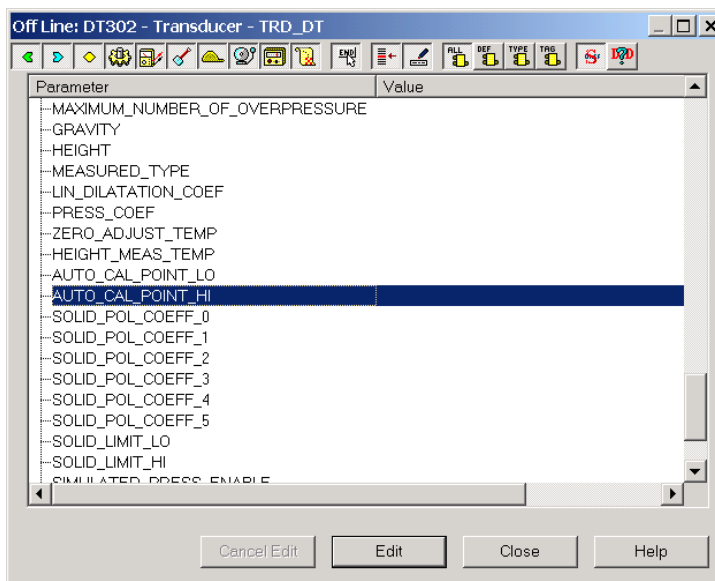
Place the **DT302** in work position (vertical) and facing the air, wait approximately **5** minutes for stabilization. To execute the lower calibration, write a value to **AUTO\_CAL\_POINT\_LO**. Any value written will calibrate internally the transmitter in 1.2 Kg/m<sup>3</sup>. Notice that the **MEASURED\_TYPE** parameter should be configured to Density (Kg/m<sup>3</sup>).



**Figure 3.10 – Lower Concentration / Density Self-Calibration**

### Upper Calibration (Water Self-Calibration)

After air calibration, place the **DT302** in work position (vertical) and in water, immersing both diaphragms, wait approximately **5** minutes for stabilization and then writes a value to **AUTO\_CAL\_POINT\_HI**. Any value written will calibrate internally the transmitter in 0.0 BRIX. Notice that the **MEASURED\_TYPE** parameter should be configured to BRIX.



**Figure 3.11 – Upper Concentration / Density Self-Calibration**

## Via Local Adjustment

### Concentration/Density Calibration

The calibration process is always with reference, it means that the user must apply to the transmitter the measuring conditions. To calibrate via local adjustment, firstly is necessary to configure the TRDTY, LOWER and UPPER in the Display Function Block. For details, please see the section 'Display Transducer Block'.

Please, see the following table for the transducer parameters involved in the calibration process:

Parameter (Name)	Parameter (Relative Index)	Item (Element)	Mnemonic
TRANSDUCER_TYPE	10	-	TRDTY
CAL_POINT_LO	17	-	LO
CAL_POINT_HI	16	-	HI

The adjustment is done following these steps:

- Wait the process stabilization and collect a sample;
- Determine in laboratory the value of density/concentration of stabilized process;
- To enter the local adjustment mode, place the magnetic tool in the orifice "Z" until flag "MD" lights up in the display. Remove the magnetic tool from "Z" and place it in the orifice "S". Remove and reinsert the magnetic tool in "S" until the message "LOC ADJ" is displayed. The message will be displayed during approximately 5 seconds after removing the magnetic tool from "S". Insert the magnetic tool in "Z" and browse up to the TRDTY parameter to select the Transducer Type to "Density". Then, browse up to the LOWER or UPPER to make the calibration process, informing the determined value for the collected sample, for example, if the density is 1000 Kg/m<sup>3</sup>, then with the magnetic tool in the orifice "S", write for example, in UPPER parameter this value and remove the magnetic tool. After returning to monitoring, the Primary Value will indicate the calibrated value for this stabilized condition.

The calibration process procedure for LOWER and UPPER is identical. It is only necessary to inform the concentration/density for the collected sample.

#### Limit Conditions for Concentration / Density Calibration:

For every writing operation in the transducer blocks there is an indication for the operation associate with the writing method. These codes appear in parameter XD\_ERROR. Every time a calibration is performed. Code 16, for example, indicates a successfully performed operation.

Limits for Concentration/Density Calibration					
Measured Type	Range 1		Range 2		AI Unit
	Lower	Upper	Lower	Upper	
Density (g/cm <sup>3</sup> )	0	3	0	10	g/cm <sup>3</sup>
Density (Kg/m <sup>3</sup> )	0	3000	0	10000	Kg/m <sup>3</sup>
Density (lb/ft <sup>3</sup> )	0	187,28	0	624,28	lb/ft <sup>3</sup>
Relative Density @ 20°C	0	3	0	10	-
Relative Density @ 4°C	0	3	0	10	-
Baume	-5	55	-5	55	degBaum
Brix	-10	110	-10	110	degBrix
Plato Degree	-10	110	-10	110	%Plato
INPM	-10	110	-10	110	INPM
GL	-10	110	-10	110	GL
Solid Percent	-10	110	-10	110	%Soli/wt
API	-10	110	-10	110	API

Notes: 1. Reference value @ 20°C  
2. Over range limits +/- 10%

#### NOTE

Exit from calibration mode via local adjustment occurs automatically when the magnetic screwdriver is not being used for a few seconds.  
Keep it in the hole even if the LOWER or UPPER parameter shows the desired value. They must be activated once calibration is complete.

**Limit Conditions for Pressure Calibration:**

For every writing operation in the transducer blocks there is an indication for the operation associate with the writing method. These codes appear in parameter XD\_ERROR. Every time a calibration is performed. Code 16, for example, indicates a successfully performed operation.

**Upper:**

$\text{SENSOR\_RANGE\_EU0} < \text{NEW\_UPPER} < \text{SENSOR\_HI\_LIMIT} * 1.25$

Otherwise, Invalid calibration request.

$(\text{NEW\_UPPER} - \text{TRIMMED\_VALUE}) < \text{SENSOR\_HI\_LIMIT} * 0.1$

Otherwise, Excessive correction.

$(\text{NEW\_UPPER} - \text{CAL\_POINT\_LO}) > \text{CAL\_MIN\_SPAN} * 0.75$

Otherwise, Invalid calibration request.

**Lower:**

$\text{SENSOR\_RANGE\_EU0} < \text{NEW\_LOWER} < \text{SENSOR\_HI\_LIMIT} * 1.25$

Otherwise, Invalid calibration request

$\text{SENSOR\_LO\_LIMIT} < \text{TRIMMED\_VALUE} < \text{SENSOR\_HI\_LIMIT} * 1.25$

Otherwise, Out of range.

$\text{NEW\_LOWER} - \text{TRIMMED\_VALUE} | < \text{SENSOR\_HI\_LIMIT} * 0.1$

Otherwise, Excessive correction.

$\text{CAL\_POINT\_HI} - \text{NEW\_LOWER} | > \text{CAL\_MIN\_SPAN} * 0.75$

Otherwise, Invalid calibration request.

If all limit conditions are according to these rules, the operation will be well succeeded.

**NOTE**

Codes for XD\_ERROR:

16: Default Value Set

22: Out of Range

26: Invalid Calibration Request

27: Excessive Correction.

**Self-Calibration**

To make the self-calibration using the local adjustment, firstly is necessary to configure the AUTO\_CAL\_POINT\_LO (LO) and AUTO\_CAL\_POINT\_HI (HI) into the Display Function Block. For details, please see the section 'Display Transducer Block'.

Please, see the following table for the transducer parameters involved in the calibration process:

Parameter (Name)	Parameter (Relative Index)	Item (Element)	Mnemonic
TRANSDUCER_TYPE	10	--	TRDTY
MEASURED_TYPE	77	--	MEAST
AUTO_CAL_POINT_LO	84	--	LO
AUTO_CAL_POINT_HI	85	--	HI

To perform the Lower calibration, firstly the user should apply air to the sensors and then using the magnetic tool browses up to LO parameter and only writes a value. Any value written will calibrate internally the transmitter in 0.00 mmH<sub>2</sub>O.

To perform the Upper calibration, firstly the user should insert the sensors in water and then using the magnetic tool browses up to HI parameter and only writes a value. In this situation, the applied pressure will be according to the distance between the sensors and the local gravity (500.0 mmH<sub>2</sub>O).

## Temperature Calibration

Write in parameter CAL\_TEMPERATURE any value in the range -10°C to +120°C. After that, check the calibration performance using parameter SECONDARY\_VALUE.

By adjusting this parameter to the current temperature, the device's temperature indication is adjusted.

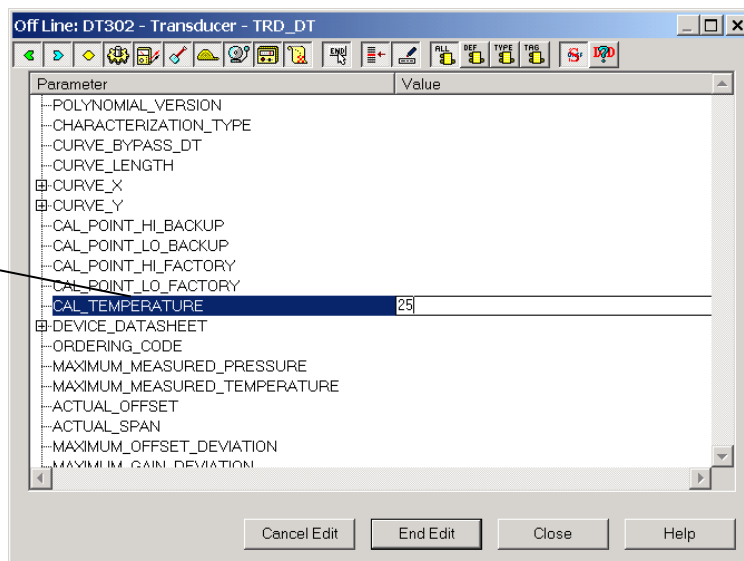


Figure 3.12 – Temperature Calibration Configuration Screen

## Sensor Data Reading

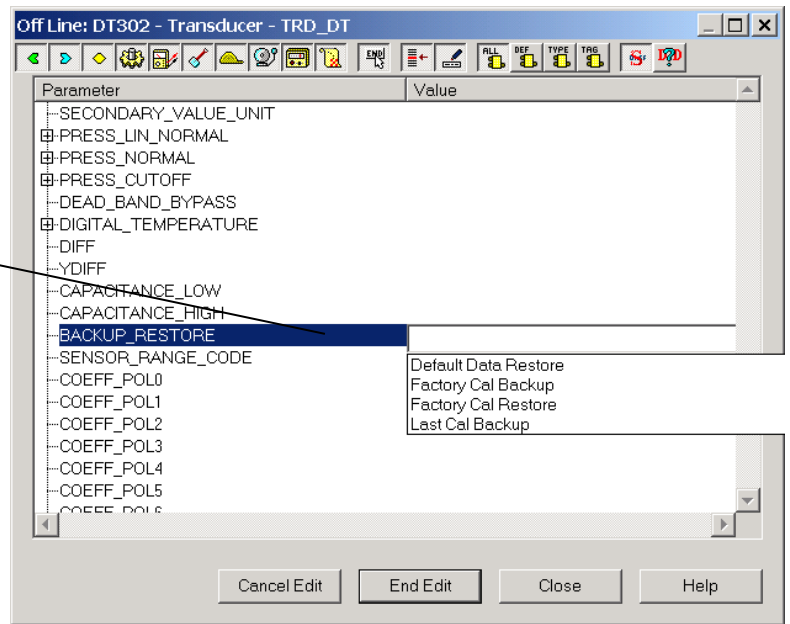
Always when **DT302** is on, is verified if the serial number of the sensor in the sensor board is the same that the saved serial number in EEPROM in the main board. When these numbers are different (a swap of sensor set or main board was carried through) the data stored in the EEPROM of sensor board is copied to the EEPROM of the main board.

Through the parameter **BACKUP\_RESTORE**, also this reading can be made, choosing the option "Sensor Data Restore". The operation, in this case, is done independent of the sensor serial number. Through the option "Sensor Data Backup", the sensor data stored in the main board EEPROM memory can be saved in the EEPROM of the sensor board. (This operation is done at factory).

Through this parameter, we can recover default data from factory about sensor and last saved calibration settings, as well as making the rescue of calibrations. There are the following options:

- **Factory Cal Restore:** Recover last calibration settings done at factory;
- **Last Cal Restore:** Recover last calibration settings done by user and saved as backup;
- **Default Data Restore:** Restore all data as default;
- **Sensor Data Restore:** Restore sensor data saved in the sensor board and copy them to main board EEPROM memory.
- **Factory Cal Backup:** Copy the actual calibration settings to the factory ones;
- **Last Cal Backup:** Copy the actual calibration settings to the backup ones;
- **Sensor Data Backup:** Copy the sensor data at main board EEPROM memory to the EEPROM memory located at the sensor board;
- **None:** Default value, no action is done.

This parameter is used to save or restore the default, factory or user configuration stored at the sensor module.



**Figure 3.13 – Backup Restore Option**

## Transducer Display – Configuration

Using the Syscon or any other configuration tool is possible to configure the Display Transducer block. As the name described it is a transducer due the interfacing of its block with the LCD hardware.

The Transducer Display is treated as a normal block by any configuration tool. It means, this block has some parameters, and those ones can be configured according to customer's needs.

The user can choose up to seven parameters to be shown at LCD display; they can be parameters just for monitoring purpose or for acting locally in the field devices by using a magnetic tool. The first two parameters will be toggle in the display.

## Display Transducer Block

The local adjustment is completely configured by SYSCON or any configuration tool. It means, the user can select the best options to the application. From factory, it is configured with the options to set the Upper and Lower trim, for monitoring the input transducer output and check the Tag. Normally, the transmitter is much better configured by SYSCON, but the local functionality of the LCD allows an easy and fast action on certain parameters, since it does not rely on communication and network wiring connections. Among the possibilities by Local Adjustment, the following options can be emphasized: Mode block, Outputs monitoring, Tag visualization and Tuning Parameters setting.

The interface with the user is described very detailed on the "General Installation, Operation and Maintenance Procedures Manual". Please take a detailed look at this manual in the chapter related to "Programming Using Local Adjustment". It is significantly the resources on this transducer display, also all the Series 302 field devices from Smar has the same methodology to handle with it. So, since the user has learned once, he is capable to handle all kind of field devices from Smar.

All functions blocks and transducers defined according Profibus PA have a description of their features written, by the Device Description Language. This feature permits that third-party configuration tools enabled by Device Description Service technology can interpret these features and make them accessible to configure. The Function Blocks and Transducers of Series 302 have been defined rigorously according to the Foundation Fieldbus specifications in order to be interoperable to other parties.



To work with the local adjustment using the magnetic tool, it is necessary to previously prepare the parameters related with this operation via SYSCON (System Configuration).

There are seven groups of parameters, which may be pre-configured by the user to enable, a possible configuration by means of the local adjustment. As an example, let's suppose that the user does not want to show some parameters; in this case, simply write an invalid Tag in the parameter Block\_Tag\_Param\_X. Doing this, the device will not take the parameters related (indexed) to its Block as a valid parameter.

## Definition of Parameters and Values

### Block\_Tag\_Param

This is tag of the block to which the parameter belongs. Use up to a maximum of 32 characters.

### Index\_Relative

This is the index related to the parameter to be actuated or viewed (0, 1, 2...). Refer to the Function Blocks Manual to know the desired indexes or visualize them on the **SYSCON** opening the desired block.

### Sub\_Index

In case the user wants to visualize a certain tag, configure the index\_relative equal to zero, and the sub-index equal to one (refer to paragraph Structure Block in the Function Blocks Manual).

### Mnemonic

This is the mnemonic for the parameter identification (it accepts a maximum of 16 characters in the alphanumeric field of the display). Choose the mnemonic, preferably with no more than 5 characters because, this way, it will not be necessary to rotate it on the display.

### Inc\_Dec

It is the increment and decrement in decimal units when the parameter is Float or Float Status type, or integer, when the parameter is an integer type.

### Decimal\_Point\_Numb

This is the number of digits after the decimal point (0 to 3 decimal digits).

### Access

The access allows the user to read, in the case of the "Monitoring" option, and to write when "Action" option is selected, then the display will show the increment and decrement arrows.

### Alpha\_Num

These parameters include two options: value and mnemonic. In option value, it is possible to display data both in the alphanumeric and in the numeric fields; this way, in the case of a data higher than 10000, it will be shown in the alphanumeric field. In option mnemonic, the display may show the data in the numeric field and the mnemonic in the alphanumeric field.

In case you wish to visualize a certain tag, opt for the index relative equal to zero, and for the sub-index equal to one (refer to paragraph Structure Block in the Function Blocks Manual).

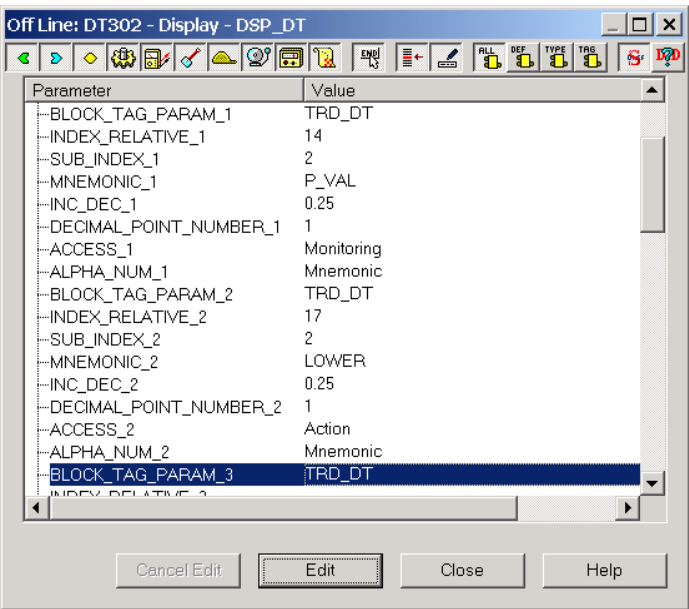


Figure 3.14 – Parameters for Local Adjustment Configuration

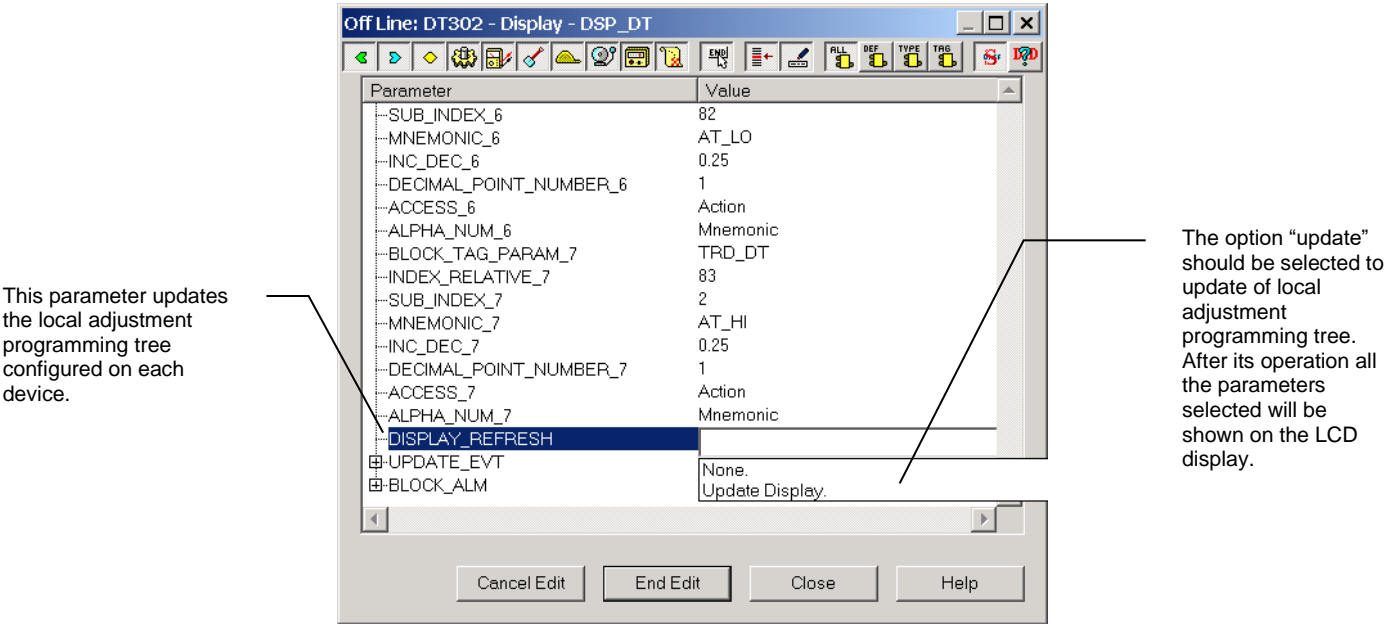


Figure 3.15 – Parameters for Local Adjustment Configuration

## Calibrating Using Local Adjustment

In order to follow the example below the Display Transducer block should be configured to show these parameters: CAL\_POINT\_HI (mnemonic UPPER), CAL\_POINT\_LO (mnemonic LOWER) and TAG (mnemonic TAG).

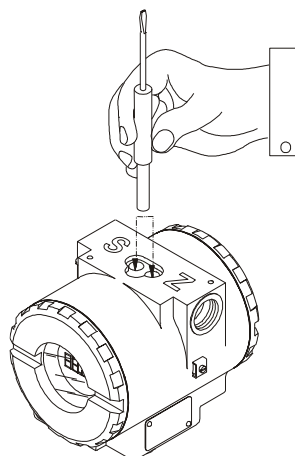
The transmitter has two holes for magnetic switches, located under the identification plate. These magnetic switches are activated by one magnetic tool.

This magnetic tool enables adjustment of the most important parameters of the blocks. It also enables pre-configuration of the communication.

The jumper W1 on top of the main circuit board (figure 3.17) must be in place and the transmitter must be fitted with the digital display for access to the local adjustment. Without the display the local adjustment is not possible.

To enter the local adjustment mode, place the magnetic tool in orifice "Z" until flag "MD" lights up in the display. Remove magnetic tool from "Z" and place it in orifice "S". Remove and reinsert the magnetic tool in "S" until the message "LOC ADJ" is displayed.

The message will be displayed during approximately 5 seconds after the user removes the magnetic tool from "S". By placing the magnetic tool in "Z" the user will be able to access the local adjustment/monitoring tree.



**Figure 3.16 - Local Adjustment**

Table 3.4 shows the actions on the **Z** and **S** holes on the **DT302** when Local Adjustment is enabled.

HOLE	ACTION
<b>Z</b>	Initializes and rotates through the available functions.
<b>S</b>	Selects the function shown in the display.

**Table 3.4 - Purpose of the holes on the Housing**

## J1 Jumper Connections

If J1 (see figure 3.17) is connected to ON, then simulation mode in the AI block is enabled.

## W1 Jumper Connections

If W1 (see figure 3.17) is connected to ON, the local adjustment programming tree is enabled, and then important block parameters can be adjusted.

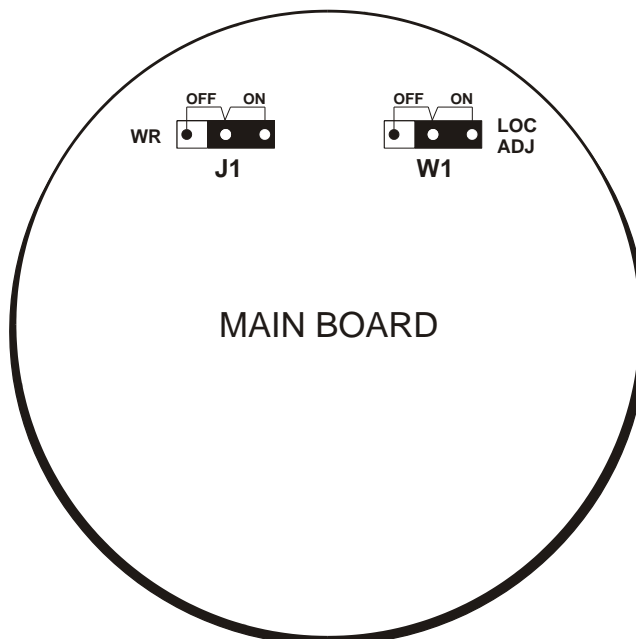


Figure 3.17 - J1 and W1 Jumpers

In order to start the local adjustment, place the magnetic tool in orifice Z and wait until letters MD are displayed.

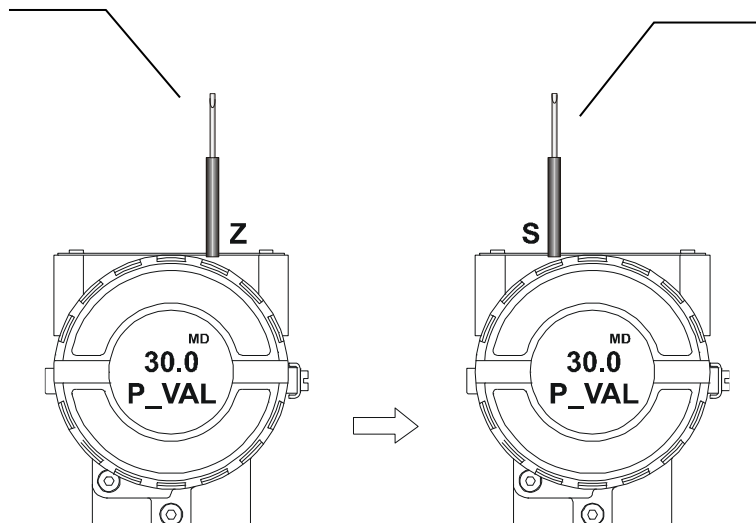
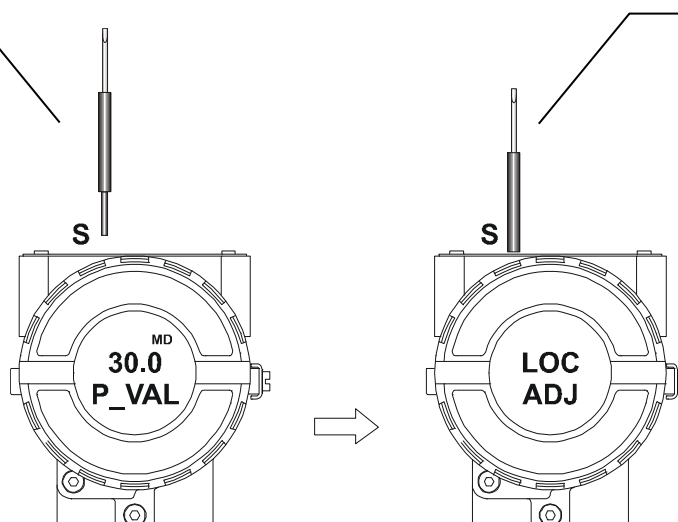


Figure 3.18 - Step 1 - DT302

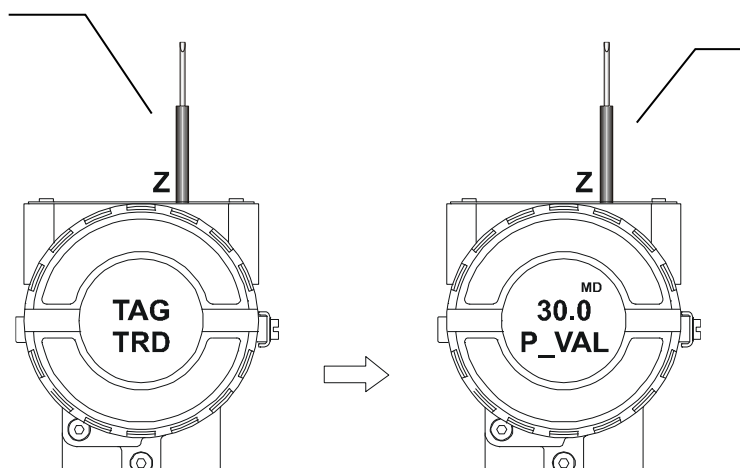
Remove the magnetic tool from orifice S.



Insert the magnetic tool in orifice S and once more LOC ADJ should be displayed.

Figure 3.19 - Step 2 - DT302

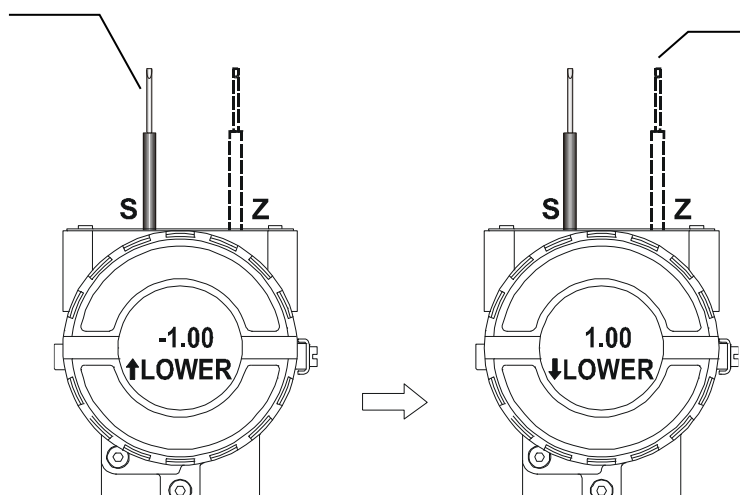
Place the magnetic tool in orifice Z. If this is the first configuration, the option shown on the display is the TAG with its corresponding mnemonic configured by the SYSCON. Otherwise, the option shown on the display will be the one configured in the prior operation. By keeping the tool inserted in this orifice, the local adjustment menu will rotate.



In this option the first variable (P\_VAL) is showed with its respective value. If it is wanted it to be static, place the tool in S and keep it there.

Figure 3.20 - Step 3 - DT302

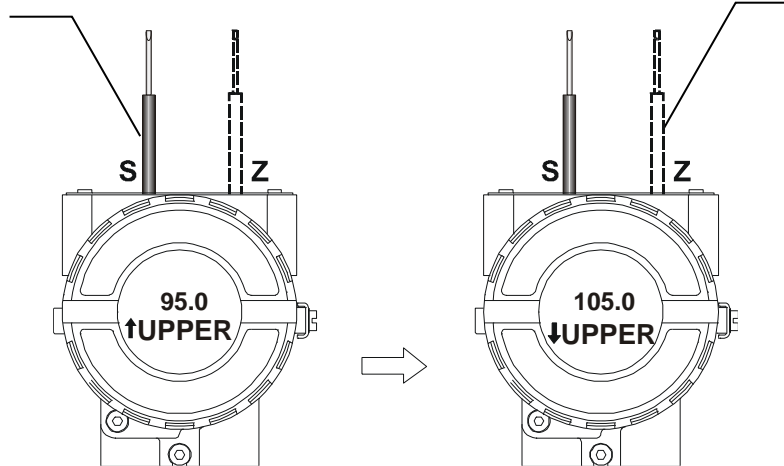
To calibrate the lower value (LOWER), insert the magnetic tool in orifice S as soon as LOWER is shown in the display. An arrow pointing upward (↑) increments the value and an arrow pointing downward (↓) decrements the value. To increment the value, keep the tool inserted in S until the desired value is set.



To decrement the lower value, place the magnetic tool in orifice Z to shift the arrow to the downward position and then, by inserting and keeping the tool in orifice S, it is possible to decrement the lower value.

Figure 3.21 - Step 4 - DT302

To calibrate the upper value (UPPER), insert the magnetic tool in orifice S as soon as upper is shown in the display. An arrow pointing upward (↑) increments the valve and an arrow pointing downward (↓) decrements the value. To increment the value, keep the tool inserted in S until the desired value is set.



To decrement the upper value, place the magnetic tool in orifice Z to shift the arrow to the downward position and then; by inserting and keeping the tool in orifice S, it is possible to decrement the upper value.

Figure 3.22 - Step 5 - DT302

# MAINTENANCE PROCEDURES

## General

**DT302** Concentration/ Density transmitters are extensively tested and inspected before delivery to the end user. Nevertheless, during their design and development, consideration was given to the possibility of repairs by the end user, if necessary.

In general, it is recommended that end users do not try to repair printed circuit boards. Spare circuit boards may be ordered from Smar whenever necessary.

The **DT302** has been designed to operate for many years without malfunctions. The process application can require periodic cleaning of the repeater diaphragms, and then the flanges may be easily removed and reinstalled. The transmitter eventually can require maintenance, and then it may be changed in the field. In this case, the possibly damaged sensor should be returned to Smar for evaluation and, if necessary, repair. Refer to the item "Returning Materials" at the end of this Section. The table 4.1 shows the symptoms and the probable source of problem cause:

SYMPTOM	PROBABLE SOURCE OF PROBLEM
NO COMMUNICATION	<ul style="list-style-type: none"> <li><b>Transmitter Connections</b> Check wiring polarity and continuity. Check for short-circuit or ground loops. Check if the power supply connector is connected to main board. Check if the shield is not used as a conductor. It should be grounded at one end only.</li> </ul>
	<ul style="list-style-type: none"> <li><b>Power Supply</b> Check power supply output. The voltage must be between 9 - 32 VDC at the <b>DT302</b> terminals. Noise and ripple should be within the following limits: a) 16 mV peak to peak from 7.8 to 39 KHz. b) 2 V peak to peak from 47 to 63 Hz for non-intrinsic safety applications and 0.2 V for intrinsic safety application. c) 1.6 V peak to peak from 3.9 MHz to 125 MHz.</li> </ul>
	<ul style="list-style-type: none"> <li><b>Network Connection</b> Check that the topology is correct, and all devices are connected in parallel. Check that two Terminators are OK and correctly positioned. Check that the Terminators are according to the specifications. Check length of trunk and spurs. Check spacing between couplers.</li> </ul>
	<ul style="list-style-type: none"> <li><b>Network Configuration</b> Check the network communication configuration.</li> </ul>
	<ul style="list-style-type: none"> <li><b>Electronic Circuit Failure</b> Check the main board for defect by replacing it with a spare one.</li> </ul>
INCORRECT READING	<ul style="list-style-type: none"> <li><b>Transmitter Connections</b> Check for intermittent short-circuits, open circuits and grounding problems. Check if the sensor is correctly connected to the <b>DT302</b> terminal block.</li> </ul>
	<ul style="list-style-type: none"> <li><b>Noise, Oscillation</b> Adjust damping. Check grounding of the transmitters housing. Check that the shielding of the wires between transmitter / panel is grounded only in one end.</li> </ul>
	<ul style="list-style-type: none"> <li><b>Sensor</b> Check the sensor operation; it shall be within its characteristics. Check sensor type; it shall be the type and standard that the <b>DT302</b> has been configured to. Check if process is within the range of the sensor and the <b>DT302</b>.</li> </ul>

**Table 4.1 - Symptoms and Probable Source of Problem**

If the problem is not presented in the previous table, follow the Note below:

#### NOTE

The Factory Init should be tried as a last option to recover the equipment control when the equipment presents some problem related to the function blocks or the communication. **This operation must only be carried out by authorized technical personnel and with the process offline, since the equipment will be configured with standard and factory data.**

This procedure resets all the configurations run on the equipment, after which a partial download should be performed.

Two magnetic tools should be used to this effect. On the equipment, withdraw the nut that fixes the identification tag on the top of the housing, so that access is gained to the "S" and "Z" holes.

The operations to follow are:

- 1) Switch off the equipment, insert the magnetic tools and keep them in the holes (the magnetic end in the holes);
- 2) Power on the equipment;
- 3) As soon as Factory Init is shown on the display, take off the tools and wait for the "5" symbol on the right upper corner of the display to unlit, thus indicating the end of the operation, otherwise the information will not be saved.

This procedure makes effective the entire factory configuration and will eliminate eventual problems with the function blocks or with the equipment communication.

#### ATTENTION

In general, in every change that needs to be persisted, such as after a download, the information is saved in FRAM. During this operation, the "5" symbol appears on the display and you must not turn off the transmitter, otherwise the information will not be persisted (saved).

## Procedure to change the DT302 Main Electronic Board

- Replace the main electronic board
- Read from sensor (Backup menu).
- Trim the temperature with two temperatures 30°C apart.
- This procedure must be done, when the temperature is steady, a temperature standard must be used as a reference to adjust the DT temperature.
- After the temperature trim, make the self-calibration.

## Disassembly Procedure

#### WARNING

Do not disassemble with power on.

Figures 4.3 and 4.4 show transmitter's exploded view and will help you to understand the text below. The numbers between parentheses are relating to the enumeration of the items of the related drawing.

### Group of the Probe

To have access to the probe for cleaning, it is necessary to remove it from the process. Remove the transmitter loosening the flange.

Cleaning should be done carefully to avoid damaging of the delicate isolating diaphragms. Use of a soft cloth and a nonacid solution is recommended.

To remove the sensor from the electronic housing, the electrical connections (in the field terminal side) and the main electronic board connector must be disconnected.

Loosen the hex screw **(6)** and carefully unscrew the electronic housing from the sensor, observing that the flat cable is not excessively twisted.



**WARNING**

To avoid damage do not rotate the electronic housing more than 270° starting from the fully threaded without disconnecting the electronic circuit from the sensor and from the power supply. See Figure 4.1.



**Figure 4.1 - Safe Housing Rotation**

## Electronic Circuit

To remove the circuit board (3), loosen the two screws that anchor the board.

**WARNING**

The board has CMOS components, which may be damaged by electrostatic discharges. Observe correct procedures for handling CMOS components. It is also recommended to store the circuit boards in electrostatic-proof cases.

Pull the main board out of the housing and disconnect the power supply and the sensor connectors.

## Reassemble Procedure

**WARNING**

Do not assemble the main board with power on.

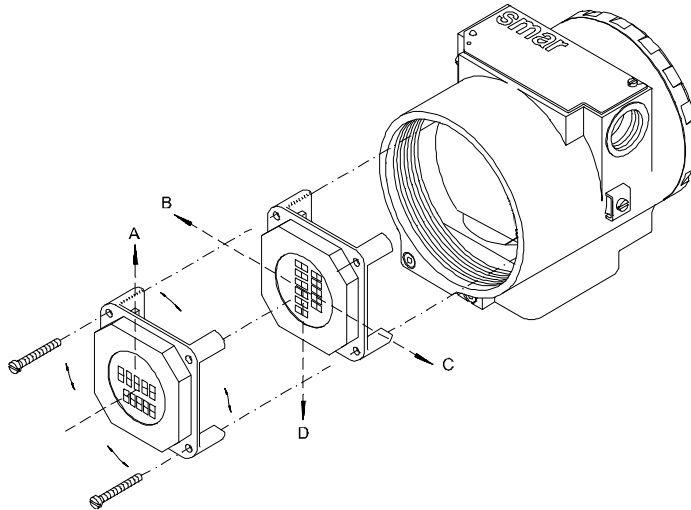
### Group of the Probe

The bolts, nuts, flanges and other parts should be inspected for corrosion or other eventual damage. Damaged parts should be replaced.

The fitting of the sensor must be done with the main board out of the electronic housing. Mount the sensor to the housing turning clockwise until it stops. Then turn it counterclockwise until it faces the protective cover (1) parallel to the process flange. Tighten the hex screw (5) to lock the housing to the sensor. Only after that is recommended to install the main board.

### Electronic Circuit

Plug sensor connector and power supply connector to main board. Attach the display to the main board. Observe the four possible mounting positions. The Smar mark indicates up position.



**Figure 4.2 - Four Possible Positions for Display**

Anchor the main board and display with their screws.

After tightening the protective cover **(1)**, mounting procedure is complete. The transmitter is ready to be energized and tested.

## **Interchangeability**

To obtain an accurate and better temperature compensated response. Each sensor is submitted to a factory characterization process and the specific data is stored in an EEPROM located in the sensor body.

Every time the power is turned on, the main circuit reads the sensor serial number, should it differ from the number stored in the memory. The circuit understands that there is a new sensor and the following information is transferred from the sensor to the main circuit.

- Temperature compensation coefficients.
- Sensor's trim, including characterization curve.
- Sensor characteristics: type, range, diaphragm material and fill fluid.

The other transmitter characteristics are stored in the main circuit memory and are not affected by sensor change.

Data transfer from the sensor to the main circuit can be performed by parameter BACKUP\_RESTORE previously explained. In case of changing of the main board, the information of the sensor, as described above are updated. However, the transmitter information such as upper value and lower value must be reconfigured.

## **Upgrading DT301 to DT302**

The sensor and housing of the DT301 is exactly the same as the **DT302**. By changing the circuit board of the DT301 it becomes a **DT302**.

Upgrading the DT301 to a **DT302** is therefore very much the same as the procedure for replacing the main board described above.

To remove the circuit board **(3)**, loosen the two screws that anchor the board. Caution with the circuit boards must be taken as mentioned above. Pull the DT301 main board out of the housing and disconnect the power supply and the sensor connectors.

Put in the **DT302** main board reversing the procedure for removing the DT301 circuit.

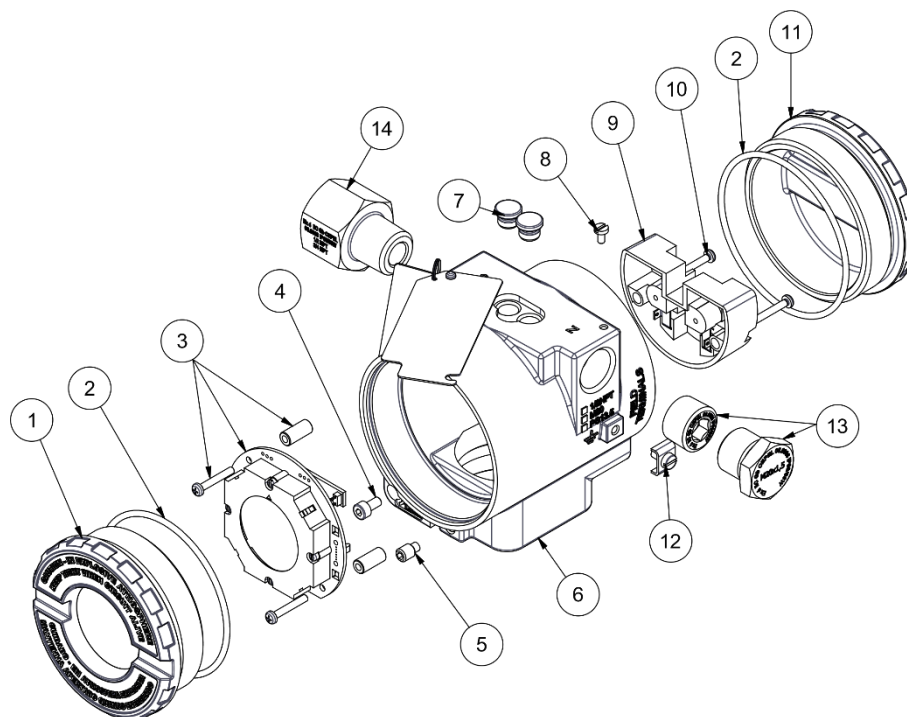
## Returning Materials

If it becomes necessary to return the transmitter and/or configurator to Smar, simply contact our office, informing the defective instrument's serial number, and return it to our factory. To speed up analysis and solution of the problem, the defective item should be returned with the Service Request Form (SRF – Appendix B) properly filled with a description of the failure observed and with as much details as possible. Other information concerning to the instrument operation, such as service and process conditions, is also helpful.

## Accessories

ACCESSORIES	
ORDERING CODE	DESCRIPTION
SD1	Magnetic Tool for Local Adjustment
PS302	Power Supply
FDI302	Field Device Interface
BT302	Terminator
DF47-12 or DF47-17	Intrinsic Safety Barrier
SB302	Insulated Intrinsic Safety Barrier

## Exploded View



SPARE PARTS LIST		
DESCRIPTION	POSITION	CODE
COVER WITH WINDOW FOR INDICATION	1	400-1307-1xx
COVER O-RING	2	204-0122
MAIN ELECTRONIC CIRCUIT BOARD	3	400-1356 (NOTE)
COVER LOCKING SCREW	4	204-0120
SENSOR LOCKING SCREW	5	400-1121
HOUSING	6	400-1314-6xx
LOCAL ADJUSTMENT PROTECTION COVER	7	204-0114
IDENTIFICATION PLATE FIXING SCREW	8	204-0116
TERMINAL BLOCK	9	400-0059
TERMINAL HOLDING SCREW	10	204-0119
COVER WITHOUT WINDOW	11	400-1307-0xx
EXTERNAL GROUND SCREW	12	204-0124
M20 X 1.5 External Socket Plug in 316 SST BR-EX D	13	400-0810
PG13.5 External Socket Plug in 316 SST	13	400-0811
1/2" NPT BR-Ex-d Internal Socket Set Plug in 316 SST	13	400-1484
3/4 NPT Adapter in 316 SST BR-EX D	14	400-0812

### NOTE ITEM 3

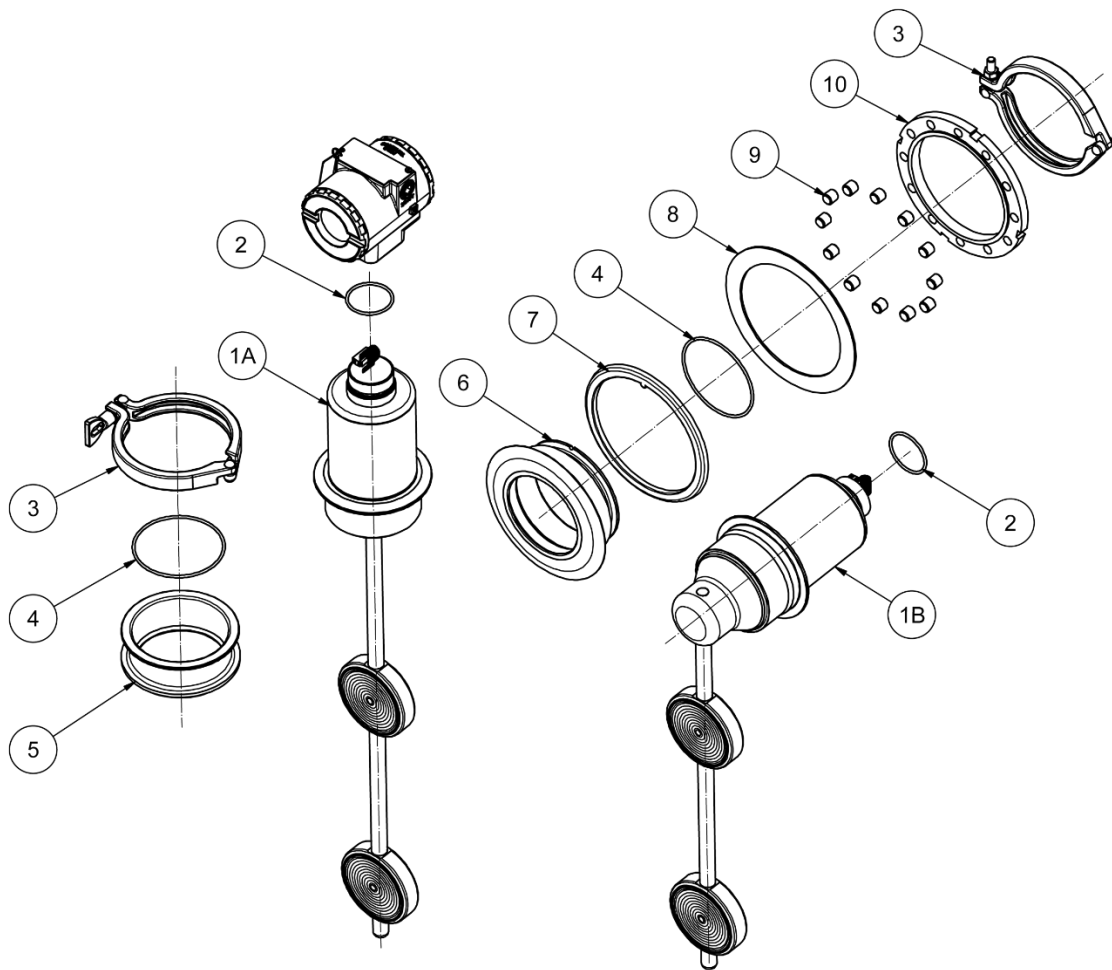
Access <https://www.smar.com/en/support>, in General Support, look for Compatibility Note and consult the document.

### NOTE ITEM 13

The spare part 400-1484, Internal Hexagonal Plug 1/2" NPT 316SST BR-Ex-d, was standardized in 316SST material and will be used in all line of housings (aluminum, copper free aluminum or 316SST). With or without CEPEL certificate.

400-1314	HOUSING			
	COD.	Communication Protocol		
		F Foundation Fieldbus		
	COD.	Electrical Connection		
		0 ½ NPT		
		A M20x1.5		
		B PG13.5		
		COD. Material		
	H0	Aluminum (IP/Type)		
		H1 Stainless steel (IP/Type)		
		H2 Aluminum for saline atmosphere (IPW/Type X)		
		H4 Aluminum Copper Free (IPW/Type X)		
	COD.	Painting		
		P0 Gray Munsell N6.5		
		P8 Without painting		
		P9 Safety Blue Epoxy – Electrostatic painting		
400-1314	F	0	H0	P0
TYPICAL MODEL				

400-1307	Cover			
	COD.	Type		
		0 With window		
	COD.	1 Without window		
		COD. Material		
		H0 Aluminum (IP/Type)		
		H1 Stainless steel (IP/Type)		
		COD. Painting		
	P0	Gray Munsell N6.5		
		P8 Without painting		
		P9 Safety Blue Epoxy – Electrostatic painting		
400-1307	1	H0	P0	
TYPICAL MODEL				



**Figure 4.3 - DT302 Exploded View - Sanitary Model**

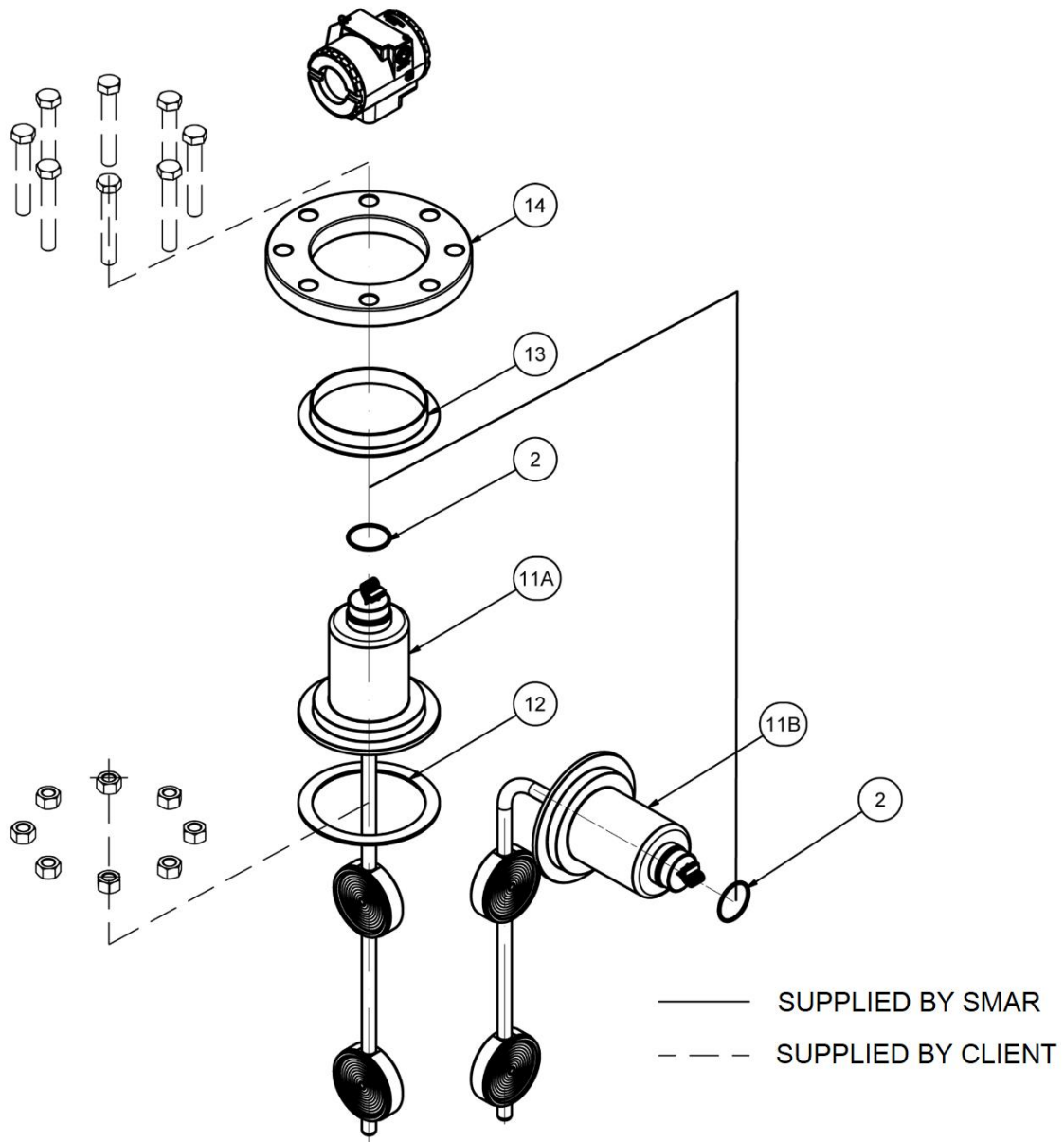


Figure 4.4 - DT302 Exploded View - Industrial Model

## Spare parts

SPARE PARTS LIST			
DESCRIPTION OF PARTS	POSITION	CODE	CATEGORY (NOTE 1)
<b>O-RINGS (NOTE 4)</b>			
Neck, Buna-N	2	204-0113	B
Process connection, Buna-N ( <b>Sanitary Model</b> )	4	400-0815	B
<b>PROCESS CONNECTION – INDUSTRIAL MODEL</b>			
Flange 4" – 150# ANSI B-16.5, 316L SST	14	400-0237	
Flange 4" – 300# ANSI B-16.5, 316L SST	14	400-0238	
Flange 4" – 600# ANSI B-16.5, 316L SST	14	400-0239	
Flange DN 100, PN 25 / 40, DIN 2526 – Form D, 316L SST	14	400-0240	
Teflon Gasket	12	400-0720	
Teflon Insulation Joint	13	400-0863	
<b>PROCESS CONNECTION - SANITARY MODEL</b>			
Tank Adapter for Straight Model 316L SST	5	400-0241	
Tri-Clamp de 4", 316L SST (Clamp 304/ Nut 316L)	3	400-0242	
Tank Adapter for Curve Model 316L SST	6	400-0721	
Silicon O'Ring	7	400-0722	
Protection Flange	8	400-0723	
Tightening Flange	10	400-0724	
Tightening Flange Screw	9	400-0725	
<b>PROBE</b>			
Industrial Probe	11A or 11B	(NOTE 5)	B
Sanitary Probe	1A or 1B	(NOTE 5)	B

**Table 4.2 - Spare Parts List**

**NOTE 1:** For category A, it is recommended to keep, in stock, 25 parts installed for each set, and for category B, 50.

**NOTE 2:** Includes Terminal Block, Bolts, and Identification plate without certification.

**NOTE 3:** The main board of **DT302** and probe are items.

**NOTE 4:** O-rings are packaged in packs of 12 units.

**NOTE 5:** To specify sensors, use the following tables.

400-0243-S	Sanitary Model Probe			
	COD.	RANGE		
	1	0	to	3 g/cm <sup>3</sup> (1)
	2	0	to	10 g/cm <sup>3</sup>
	COD.	Diaphragm Material		
	I	316L SST		
	U	Hastelloy C276		
	COD.	Fill Fluid		
	N	Propylene Glycol – Neobee M2O – Food Grade		
	COD.	Mounting		
	1	Straight		
2	Curved			
400-0243-S	1	I	N	1

Note 1: Values referring to the 250 mm probe between centers. For a 500 mm probe, range 1 ranges from 0 to 2 g/cm<sup>3</sup>.



400-0243-I		Industrial Model Probe		
		CODE	RANGE	
		1	0	to 3 g/cm <sup>3</sup> (1)
		2	0	to 10 g/cm <sup>3</sup> (2)
		CODE	Diaphragm Material / Probe	
		H	Hastelloy C276 / Hastelloy C276	
		I	316L SST / 316L SST	
		L	316L SST HALLAR Plated/ 316L SST HALLAR Plated	
		U	Hastelloy C276 / 316L SST	
		Z	Others - Specify	
		CODE	Fill Fluid	
		N	Propylene Glycol – Neobee M20	
		S	DC 200/20 - Silicone Oil	
		CODE	Mounting	
		1	Straight	
		2	Curved	

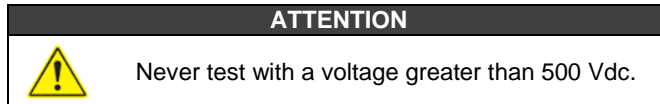
400-0243-I	1	H	S	1
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**Note 1:** Values referring to the 250 mm probe between centers. For a 500 mm probe, range 1 ranges from 0 to 2 g/cm<sup>3</sup> and 800 mm probe, varies from 0 to 1.8 g/cm<sup>3</sup>.

**Note 2:** Values referring to probes of 250 and 500 mm between centers. For 800 mm probe, range 2 ranges from 0 to 7 g/cm<sup>3</sup>.

## Isolation Test on Equipment Housings

1. Power off the equipment in the field, remove its back cover and disconnect all field cables from the transmitter terminal block, isolating them safely.
2. It is not necessary to remove the main board and display.
3. Jumper (connect) the power terminals (positive and negative) with the cable coming from the Megohmmeter (megger).
4. Configure the megohmmeter for 500 Vdc scale and check the isolation between the housing and the cable that short-circuits all the terminals.



5. The value obtained must be greater than or equal to  $2G\Omega$  and the voltage application time must be at least 1 second and at most 5 seconds.
6. If the value obtained by the megohmmeter is below  $2G\Omega$ , the possibility of moisture entering the electrical connection compartment must be analyzed.
7. It is possible to loosen the two screws that secure the terminal block to the housing and carry out a superficial cleaning and dry the surface well. Afterwards, the isolation can be tested again.
8. If the isolation test still shows that the isolation has been compromised, the housing must be replaced and sent to Nova Smar S.A. for analysis and retrieval.

IMPORTANT	
a)	For equipment certified Exd and Exi (Explosion Proof and Intrinsically Safe) the standards advise not to carry out repairs in the field of the housing electronic components, only at Nova Smar S.A.
b)	In normal use, the housing components must not cause failures that affect its isolation. For this reason, it is important to verify whether there are traces of water entering the housing and, if so, an assessment of the electrical installations and the sealing rings of the covers must be carried out. Nova Smar S.A. has a team ready to support the assessment of facilities, if necessary.

## Section 5

# TECHNICAL CHARACTERISTICS

### Filling Fluids

The filling fluid selection shall consider its physical properties in what concerns to pressure temperature limits and chemical compatibility with the process fluid. The latter is an important consideration in case the filling fluid happens to meet the process fluid, should a leakage occur.

Table 5.1 presents the filling fluids, which are available for the **DT302**, together with physical properties and applications.

FILLING FLUID	VISCOSITY (cSt) at 25°C	DENSITY (g/cm <sup>3</sup> at 25°C)	THERMAL EXPANSION COEFFICIENT (1/°C)	APPLICATIONS
Silicone DC 200/20	20	0.95	0.00107	General purpose – Standard
Propylene Glycol (Neobee M20) Food Grade	9.8	0.90	0.001	Beverage and pharmaceutical food grade

**Table 5.1 - Properties of Filling Fluids**

### Functional Specifications

#### Output Signal

Digital, only. Foundation™ Fieldbus, 31.25 kbit/s, voltage mode with bus power.

#### Power Supply

Bus powered: 9 - 32 Vdc.

Quiescent current consumption: 12 mA.

#### Indicator

4 ½ -digit numerical and 5-character alphanumeric LCD indicator.

#### Hazardous Area Certifications

See Appendix A for further information.

#### Temperature Limits

Ambient:	-40	to	85° C	(	-40	to	185° F)
Process:	-20	to	150° C	(	-04	to	302° F)
Storage:	-40	to	100° C	(	-40	to	212° F)
Digital Display:	-10	to	60° C	(	14	to	140° F)

#### Static Pressure Limit

70 kgf/cm<sup>2</sup> (7 MPa) (1015 PSI).

#### Turn-on Time

Approximately 5 seconds.

#### Volumetric Displacement

Less than 0.15 cm<sup>3</sup> (0.01 in<sup>3</sup>)

#### Humidity Limits

0 to 100% RH.

#### Temperature Compensation

Automatic.

## Performance Specifications

Reference conditions: temperature 25°C (77°F), power supply of 24 Vdc, atmospheric pressure, silicone oil fill fluid, 316L diaphragm and range full - scale calibration.

RANGE	ACCURACY (1)	AMBIENT TEMPERATURE EFFECT / 10°C	STABILITY (For 3 Months)	STATIC PRESSURE EFFECT (2) (per 1 kgf/cm <sup>2</sup> )
1	±0.0004 g/cm <sup>3</sup> (±0.1 °Brix)	0.003 kg/m <sup>3</sup>	0.021 kg/m <sup>3</sup>	0.001 kg/m <sup>3</sup>
2	±0.0007 g/cm <sup>3</sup>	0.013 kg/m <sup>3</sup>	0.083 kg/m <sup>3</sup>	0.004 kg/m <sup>3</sup>

(1) Linearity, hysteresis, and repeatability effects are included.

(2) This is systematic error that can be eliminated by calibrating at the operating static pressure.

**Table 5.2 - Performance Specifications**

### Power Supply Effect

±0.005 of calibrated FS per volt.

### Electro-Magnetic Interference Effect

Designed to comply with IEC 61326-1:2006, IEC 61326-2-3:2006, IEC 61000-6-4:2006 and IEC 61000-6-2:2005.

## Physical Specifications

### Electrical Connection

½ -14 NPT, Pg 13.5 or M20 x 1.5".

### Process Connection

Industrial model: AISI316L Stainless Steel Flange, in accordance with ASME B16.5 or EN1092-1 (Former DIN2526).

Sanitary model: AISI316L Stainless Steel Triclamp (Clamp 304/ Nut 316L).

### Wetted Parts

Isolating diaphragms: 316L SST or Hastelloy C276.

Probe material: 316L SST or 316L SST with Halar

O-ring for sanitary model: Buna-N, Viton™ or Teflon™

### Non-wetted Parts

Electronic Housing: injected low copper aluminum with polyester painting or 316 SST housing, with Buna-N o-rings on cover (NEMA 4X, IP67).

Fill fluid: Silicone (DC200/20), Neobee M20 Propylene Glycol.

Identification plate: 316 SST.

### Mounting

Side or top mounting.

### Weight

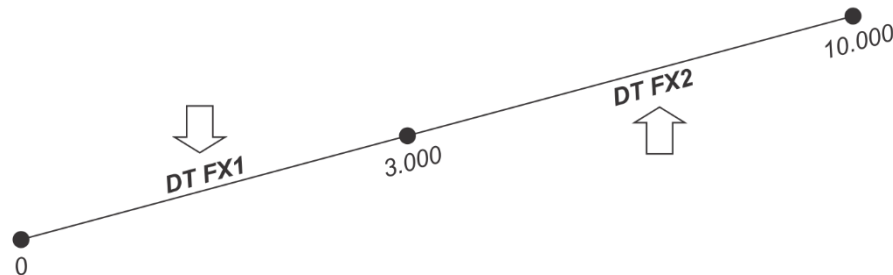
Sanitary model: 9 kg (20 lb) - Industrial model: 12 kg (26 lb).

# Ordering Code

MODEL	SANITARY CONCENTRATION/DENSITY TRANSMITTER											
	CODE	Range				Minimum Span		<b>Note:</b> These measurement ranges are provided for our standard Density Transmitter, 250 mm of distance between diaphragms (centers) on the probe and are valid for straight and curved devices. For instruments with distance between centers of 500, please see table 5.1				
	1	0	to	3 g/cm <sup>3</sup>	0.025 g/cm <sup>3</sup>							
	2	0	to	10 g/cm <sup>3</sup>	0.025 g/cm <sup>3</sup>							
	CODE	Wetted Parts Material										
	I	316L SST										
	U	Probe in 316 SST and Diaphragms in Hastelloy C276										
	CODE	Fill Fluid										
	N	Neobee - M20 Propylene Glycol – Food Grade										
	S	DC 200/20 - Silicone Oil										
	CODE	Local Indicator										
	0	Without Indicator										
	1	With Digital Indicator										
	CODE	Electrical Connection										
	0	½ - 14 NPT (4)										
	1	½ - 14 NPT x ¼ NPT (AI 316) – With Adapter (5)										
	2	½ - 14 NPT x ¼ BSP (AI 316) – With Adapter (6)										
	3	½ - 14 NPT x ½ BSP (AI 316) – With Adapter (6)										
	A	M20 X1.5 (4)										
	B	PG 13.5 DIN (6)										
	Z	Others - Specify										
	CODE	Mounting										
	1	Straight – distance between centers 500 mm										
	2	Curved – distance between centers 500 mm										
	3	Straight – distance between centers 250 mm										
	4	Curved – distance between centers 250 mm										
	CODE	Process Connection										
	J	Tri-clamp – 4"										
	K	SMS thread diameter 89 RD120-4										
	CODE	Wetted O-Rings Material										
	B	Buna-N										
	V	Viton										
	T	Teflon										
	CODE	Tank Adapter										
	0	Without Tank Adapter (Supplied by Customer)										
	2	Curved DT30XS with adapter for D>4m tank										
	3	Curved DT30XS with adapter for 1.2m < D < 3.8m tank										
	4	Curved DT30XS with adapter for 0.5m < D < 1m tank										
	5	Straight DT30XS with adapter (welded)										
	CODE	Tri-Clamp										
	0	Without Tri-clamp										
	1	With Tri-clamp in 304 SST										
	CODE	Continues next page										
DT302S	1	I	N	1	0	2	J	B	1	1	*	◀ TYPICAL MODEL NUMBER

← TYPICAL MODEL NUMBER

\* Leave it blank for no optional items.



MODEL	SANITARY CONCENTRATION/DENSITY TRANSMITTER (CONTINUATION)							
	CODE	Identification Plate						
	I4	ATEX (EX-I, EX-D) (Gas)						
	I5	INMETRO (EX-D, EX-I) (Gas)						
	I6	Without certification						
	I7	ATEX (EX-I) (Mining)						
	IJ	ATEX (EX-D) (Gas)						
	IO	INMETRO (Dust)						
	CODE	Housing Material (1) (2)						
	H0	Aluminum (IP/Type)						
	H1	316 SST (IP/Type)						
	H2	Aluminum for Saline Atmosphere (IPW/TypeX) (3)						
	H3	316 SST for Saline Atmosphere (IPW/TypeX) (3)						
	H4	Copper Free Aluminum (IPW/TypeX) (3)						
	CODE	Special (See notes)						
	Z0	Not Applicable						
	ZZ	See notes						
	CODE	Tag Plate						
	J0	With Tag						
	J1	Blank						
	CODE	Painting						
	P0	Gray Munsell N 6,5						
	P2	Blue Safety – Atmospheric Zone – Petrobras N1021						
	P3	Black Polyester						
	P8	Without Painting						
	P9	Blue Safety Epoxy – Electrostatic Painting						
	CODE	Manufacturing Standard						
	S0	Smar						
DT302S	/	I6	H0	Z0	J0	P0	S0	← TYPICAL MODEL

\* Leave it blank for no optional items.

#### Notes

- (1) IPX8 tested in 10 meters of water column for 24 hours.
- (2) Ingress Protection: IP66/68 protection degree according to IEC60529 standard.
- (3) IPW / TypeX tested for 200 hours according to NBR 8094 / ASTM B 117 standard.
- (4) Certification Ex-d for ATEX / IECEx / INMETRO.
- (5) Certification Ex-d for INMETRO.
- (6) Options not certified for Explosive Atmosphere.

Table 5.1		
Dimensions between diaphragms (centers) mm	Limit Values	
	Measuring range Fx1	Measuring range Fx2
mm	Kg/m <sup>3</sup>	Kg/m <sup>3</sup>
250	0-3000	0-10000
500	0-2000	0-10000

MODEL	INDUSTRIAL CONCENTRATION/DENSITY TRANSMITTER										
CODE		Range			Minimum Span		Note: These measurement ranges are provided for our standard Density Transmitter, 250 mm of distance between diaphragms (centers) on the probe and are valid for straight and curved devices. For instruments with distance between centers of 500 and 800mm, please see table 5.2				
1	2	0	to	3 g/cm <sup>3</sup>	0.025 g/cm <sup>3</sup>						
2	0	to	10 g/cm <sup>3</sup>	0.025 g/cm <sup>3</sup>							
CODE		Diaphragm Material / Probe									
H		Hastelloy C276 / Hastelloy C276									
I		316L SST / 316L SST									
U		Hastelloy C276 / 316L SST									
L		316L SST with Halar coating/ 316L SST with Halar coating									
Z		Others - Specify									
CODE		Fill Fluid									
N		Neobee - M20 Propylene Glycol – Food Grade									
S		DC 200/20 - Silicone Oil									
CODE		Local Indicator									
0		Without Indicator									
1		With Digital Indicator									
CODE		Electrical Connection									
0		½ - 14 NPT (4)									
1		½ - 14 NPT x ¾ NPT (316 SST) – With Adapter (5)									
2		½ - 14 NPT x ¾ BSP (316 SST) – With Adapter (6)									
3		½ - 14 NPT x ½ BSP (316 SST) – With Adapter (6)									
A		M20 X1.5 (4)									
B		PG 13.5 DIN (6)									
Z		Others - Specify									
CODE		Mounting									
1		Straight – distance between centers 500 mm									
2		Curved – distance between centers 500 mm									
3		Straight – distance between centers 800 mm									
4		Curved – distance between centers 800 mm									
5		Straight – distance between centers 250 mm									
6		Curved – distance between centers 250 mm									
7		Straight – distance between centers 250 mm with normalized tube									
Z		Special – See notes									
CODE		Process Connection									
5		4" ANSI B – 16.5									
A		DN 100 DIN 2526 – FORM D									
Z		Others – Specify									
CODE		Pressure Class									
1		150# ANSI B – 16.5									
2		300# ANSI B – 16.5									
3		600# ANSI B – 16.5									
C		PN25/40									
Z		Others – Specify									
CODE		Flange Face									
0		RF									
2		RTJ									
CODE		Continues next page									
*											

DT302I

1

I

S

1

0

1

5

1

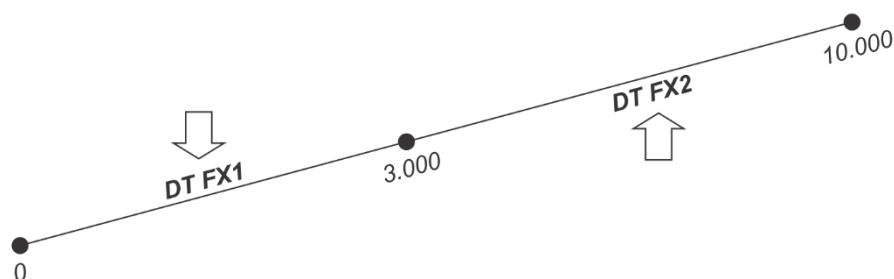
0

\*

◀ TYPICAL MODEL

← TYPICAL MODEL

\* Leave it blank for no optional items.



MODEL	INDUSTRIAL CONCENTRATION/DENSITY TRANSMITTER (CONTINUATION)									
	CODE	Identification Plate								
	I4	ATEX (EX-I, EX-D) (Gas)								
	I5	INMETRO (EX-D, EX-I) (Gas)								
	I6	Without certification								
	I7	ATEX (EX-I) (Mining)								
	IJ	ATEX (EX-D) (Gas)								
	IO	INMETRO (Dust)								
	CODE	Housing Material (1) (2)								
	H0	Aluminum (IP/Type)								
	H1	316 SST (IP/Type)								
	H2	Aluminum for Saline Atmosphere (IPW/TypeX) (3)								
	H3	316 SST for Saline Atmosphere (IPW/TypeX) (3)								
	H4	Copper Free Aluminum (IPW/TypeX) (3)								
	CODE	Special (See notes)								
	ZZ	See notes								
	CODE	Painting								
	P0	Gray Munsell N 6,5								
	P2	Blue Safety – Atmospheric Zone – Petrobras N1021								
	P3	Black Polyester								
	P8	Without Painting								
	P9	Blue Safety Epoxy – Electrostatic Painting								
	CODE	Tag Plate								
	J0	With Tag								
	J1	Blank								
	CODE	Manufacturing Standard								
	S0	Smar								
	CODE	Optional Items								
	*									

DT302I / I6 H0 ZZ J0 P0 S0 ◀ TYPICAL MODEL

\* Leave it blank for no optional items.

## Optional Items

<b>Diaphragm Thickness</b>	<b>N0</b> - Standard
<b>Strengthening of the Probe</b>	<b>R0</b> - Standard <b>R1</b> – With strengthening of the probe
<b>Mounting Position</b>	<b>E0</b> - Standard <b>E1</b> – Reverse position

### Notes

- (1) IPX8 tested in 10 meters of water column for 24 hours.
- (2) Ingress Protection: IP66/68 protection degree according to IEC60529 standard.
- (3) IPW / TypeX tested for 200 hours according to NBR 8094 / ASTM B 117 standard.
- (4) Certification Ex-d for ATEX / IECEx / INMETRO
- (5) Certification Ex-d for INMETRO
- (6) Options not certified for Explosive Atmosphere.

Table 5.2		
Dimensions between diaphragms (centers) mm	Limit Values	
	Measuring range Fx1	Measuring range Fx2
mm	Kg/m <sup>3</sup>	Kg/m <sup>3</sup>
250	0-3000	0-10000
500	0-2000	0-10000
800	Unavailable	350-7000



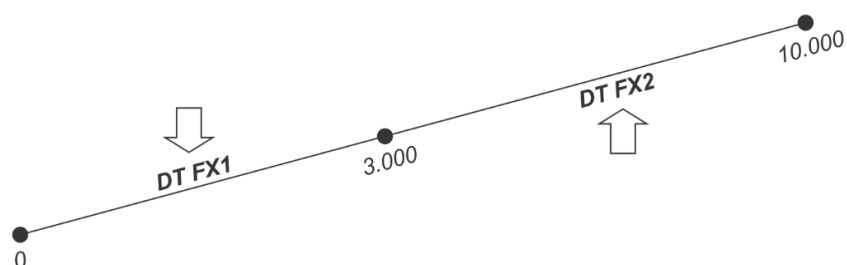
MODEL	SUBMERSIBLE CONCENTRATION/DENSITY TRANSMITTER									
COD.		Range			Minimum Span					
1		0	to	3 kg/cm <sup>3</sup>	0,025 g/cm <sup>3</sup>					
2		0	to	10 kg/cm <sup>3</sup>	0,025 g/cm <sup>3</sup>					
<b>Note:</b> These measurement ranges are provided for our standard Density Transmitter, 250 mm of distance between diaphragms (centers) on the probe and are valid for straight and curved devices. For instruments with distance between centers of 500, please see table 5.3.										
COD.		Diaphragm Material / Probe								
I		316L SST/316L SST								
COD.		Distance Between Centers								
1		250 mm								
2		500 mm								
COD.		Fill Fluid								
S		DC 200/20 - Silicone Oil								
COD.		Normalizer Tube r								
0		Without tube								
1		With 316 SST tube								
COD.		Probe Type								
1		316 SST Tubular Rod								
2		Flanged Hose								
COD.		Probe Length								
1		1 meter								
2		2 meters								
3		3 meters								
4		4 meters								
5		5 meters								
6		6 meters								
7		7 meters								
8		8 meters								
COD.		Power Supply Cable Length								
1		10 meters								
2		15 meters								

DT302M | 1 | I | 1 | S | 0 | 1 | 1 | 1 | TYPICAL MODEL

MODEL	SUBMERSIBLE CONCENTRATION/DENSITY TRANSMITTER (CONTINUATION)									
COD.	Identification Plate									
I6	Without certification									
COD.	Tag Plate									
J0	With Tag									
J1	Blank									
COD.	Centralizer									
1	Standard									
2	With centralizer									
COD.	Probe Strengthening									
R0	Standard									

DT302M | I6 | J0 | 1 | R0 | TYPICAL MODEL

Table 5.3		
Dimensions between diaphragms (centers) mm	Limit Values	
	Measuring range Fx1	Measuring range Fx2
mm	Kg/m <sup>3</sup>	Kg/m <sup>3</sup>
250	0-3000	0-10000
500	0-2000	0-10000





## CERTIFICATIONS INFORMATION

### European Directive Information

Consult [www.Smar.com](http://www.Smar.com) for the EC declarations of conformity and certificates.

**Authorized representative/importer located within the Community:**

Smar Europe BV De Oude Wereld 116 2408 TM Alphen aan den Rijn Netherlands

**ATEX Directive 2014/34/EU - "Equipment for explosive atmospheres"**

The EC-Type Examination Certificate is released by DNV Product Assurance AS (NB 2460) and DEKRA Testing and Certification GmbH (NB 0158).

Designated certification body that monitors manufacturing and released QAN (Quality Assurance Notification) is UL International Demko AS (NB 0539).

**LVD Directive 2014/35/EU – "Low Voltage"**

According the LVD directive Annex II, electrical equipment for use in an explosive atmosphere is outside the scope of this directive.

According to IEC standard: IEC 61010-1 Safety requirements for electrical equipment for measurement, control, and laboratory use - Part 1: General requirements.

**PED Directive 2014/68/EU - "Pressure Equipment"**

This product is in compliance with Article 4 paragraph 3 of the Pressure Equipment Directive 2014/68/EU and was designed and manufactured in accordance with the sound engineering practice. This equipment cannot bear the CE marking related to PED compliance. However, the product bears the CE marking to indicate compliance with other applicable European Community Directives.

**ROHS Directive 2011/65/EU - "Restriction of the use of certain hazardous substances in electrical and electronic equipment"**

For the evaluation of the products the following standards were consulted: EN IEC 63000.

**EMC Directive 2014/30/EU - "Electromagnetic Compatibility"**

For products evaluation, the standard IEC 61326-1 were consulted and to comply with the EMC directive the installation must follow these special conditions:

Use shielded, twisted-pair cable for powering the instrument and signal wiring.

Keep the shield insulated at the instrument side, connecting the other one to the ground.

### Hazardous locations general information

**Ex Standards:**

IEC 60079-0 General Requirements

IEC 60079-1 Flameproof Enclosures "d"

IEC 60079-7 Increased Safe "e"

IEC 60079-11 Intrinsic Safety "i"

IEC 60079-18 Encapsulation "m"

IEC 60079-26 Equipment with Separation Elements or combined Levels of Protection

IEC 60079-31 Equipment dust ignition protection by enclosure "t"

IEC 60529 Classification of degrees of protection provided by enclosures (IP Code)

IEC 60079-10 Classification of Hazardous Areas

IEC 60079-14 Electrical installation design, selection and erection

IEC 60079-17 Electrical Installations, Inspections and Maintenance

IEC 60079-19 Equipment repair, overhaul and reclamation

ISO/IEC 80079-34 Application of quality systems for equipment manufacture

**Warning:**

**Explosions could result in death or serious injury, besides financial damage.**

Installation of this instrument in hazardous areas must be in accordance with the local standards and type of protection. Before proceedings with installation make sure that the certificate parameters are in accordance with the classified hazardous area.

**Maintenance and Repair**

The instrument modification or replaced parts supplied by any other supplier than authorized representative of Smar is prohibited and will void the Certification.

**Marking Label**

The instrument is marked with type of protection options. The certification is valid only when the type of protection is indicated by the user. Once a particular type of protection is installed, do not reinstall it using any other type of protection.

**Intrinsic Safety / Non Incendive application**

In hazardous areas with intrinsic safety or or non-incendive requirements, the circuit entity parameters and applicable installation procedures must be observed.

The instrument must be connected to a proper intrinsic safety barrier. Check the intrinsically safe parameters involving the barrier and equipment including the cable and connections. Associated apparatus ground bus shall be insulated from panels and mounting enclosures. Shield is optional, when using shielded cable, be sure to insulate the end not grounded.

Cable capacitance and inductance plus Ci and Li must be smaller than Co and Lo of the Associated Apparatus.

It is recommended do not remove the housing covers when powered on.

**Explosionproof / Flameproof application**

Only use Explosionproof/Flameproof certified Plugs, Adapters and Cable glands.

The electrical connections entries must be connected using a conduit with sealed unit or closed using metal cable gland or metal blanking plug with at least IP66.

Do not remove the housing covers when powered on.

**Enclosure**

The electronic housing and sensor threads installed in hazardous areas must have a minimum of 6 fully engaged threads.

The covers must be tightening with at least 8 turns, to avoid the penetration of humidity or corrosive gases, and until it touches the housing. Then, tighten more 1/3 turn (120°) to guarantee the sealing.

Lock the housing and covers using the locking screw.

The enclosure contains aluminum and is considered to present a potential risk of ignition by impact or friction.

Care must be taken during installation and use to prevent impact or friction.

**Degree of Protection of enclosure (IP)**

IPx8: Second numeral meaning continuous immersion in water under special condition defined as 10m for a period of 24 hours (Ref: IEC60529).

IPW/ TypeX: Supplementary letter W or X meaning special condition defined as saline environment tested in saturated solution of NaCl 5% w/w at 35°C for a period of 200 hours (Ref: NEMA 250/ IEC60529).

For enclosure with IP/IPW/TypeX applications, all NPT threads must apply a proper water-proof sealant (a non-hardening silicone group sealant is recommended).

## Hazardous Locations Approvals

### DNV

Explosion Proof (Nemko 03ATEX1375X)

II 2G Ex d IIC T6 Gb

Ambient Temperature: -20 °C to +60 °C

Options: IP66/68W or IP66/68

Special conditions for safe use:

Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 1 and 2 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with:

EN 60079-0:2012 General Requirements

EN 60079-1:2007 Flameproof Enclosures "d"

Drawing 102A-1387, 102A-1482

### DEKRA

Intrinsic Safety (DMT 03 ATEX E 359)

I M1 Ex ia I Ma

II 1/2 G Ex ia IIC T4/T5/T6, EPL Ga/Gb

FISCO Field Device

Supply circuit for the connection to an intrinsically safe FISCO fieldbus circuit:

$U_i = 24 \text{ Vdc}$ ,  $I_i = 380 \text{ mA}$ ,  $P_i = 5.32 \text{ W}$ ,  $C_i \leq 5 \text{ nF}$ ,  $L_i = \text{Neg}$

Parameters of the supply circuit comply with FISCO model according to Annex G EN 60079-11:2012, replacing EN 60079-27: 2008.

Ambient Temperature:

$-40^\circ\text{C} \leq T_a \leq +60^\circ\text{C}$  (T4)

$-40^\circ\text{C} \leq T_a \leq +50^\circ\text{C}$  (T5)

$-40^\circ\text{C} \leq T_a \leq +40^\circ\text{C}$  (T6)

The Essential Health and Safety Requirements are assured by compliance with:

EN 60079-0:2009 + A11:2013 General Requirements

EN 60079-11:2012 Intrinsic Safety "i"

EN 60079-26:2015 Equipment with equipment protection level (EPL) Ga

Drawing 102A-1387, 102A-1482, 102A-1268, 102A-1483

### INMETRO NCC

Segurança Intrínseca (NCC 24.0150X)

Ex ia IIC T\* Ga

Ex ia IIIC T\* Da

Equipamento de Campo FISCO

$U_i = 30 \text{ V}$   $I_i = 380 \text{ mA}$   $P_i = 5,32 \text{ W}$   $C_i = 5,0 \text{ nF}$   $L_i = \text{desp}$

Tamb:  $-20^\circ\text{C}$  a  $+50^\circ\text{C}$  para T5 ou  $T_{200} 100^\circ\text{C}$

Tamb:  $-20^\circ\text{C}$  a  $+65^\circ\text{C}$  para T4 ou  $T_{200} 135^\circ\text{C}$

IP66/68 ou IP66W/68W

Prova de Explosão (NCC 24.0151)

Ex db IIC T6 Ga/Gb

Ex tb IIIC T85 °C Da/Db

Tamb:  $-20^\circ\text{C}$  a  $+40^\circ\text{C}$

IP66/68 ou IP66W/68W

Observações:

O número do certificado é finalizado pela letra "X" para indicar que para a versão do Transmissor de Densidade, modelos DT302 e DT303 equipado com invólucro fabricado em liga de alumínio, somente pode ser instalado em localização que exigem o "EPL Ga", se durante a instalação for excluído o risco de ocorrer impacto ou fricção entre o invólucro e peças de ferro/aço.

O produto adicionalmente marcado com a letra suplementar "W" indica que o equipamento foi ensaiado em uma solução saturada a 5% de NaCl p/p, à  $35^\circ\text{C}$ , pelo tempo de 200 h e foi aprovado para uso em atmosferas salinas,

condicionado à utilização de acessórios de instalação no mesmo material do equipamento e de bujões de aço inoxidável ASTM-A240, para fechamento das entradas roscadas não utilizadas.

Os planos de pintura P1 são permitidos apenas para equipamento fornecido com plaqueta de identificação com marcação para grupo de gás IIB.

O grau de proteção IP68 só é garantido se nas entradas roscadas de ½" NPT for utilizado vedante não endurecível à base de silicone.

O segundo numeral oito indica que o equipamento foi ensaiado para uma condição de submersão de dez metros por vinte e quatro horas. O acessório deve ser instalado em equipamentos com grau de proteção equivalente.

É responsabilidade do fabricante assegurar que todos os transformadores da placa analógica tenham sido submetidos com sucesso aos ensaios de rotina de 1500 V durante um minuto.

Este certificado é válido apenas para os produtos dos modelos avaliados. Qualquer modificação nos projetos, bem como a utilização de componentes ou materiais diferentes daqueles definidos pela documentação descritiva dos produtos, sem a prévia autorização, invalidará este certificado.

As atividades de instalação, inspeção, manutenção, reparo, revisão e recuperação dos equipamentos são de responsabilidade dos usuários e devem ser executadas de acordo com os requisitos das normas técnicas vigentes e com as recomendações do fabricante.

**Normas Aplicáveis:**

ABNT NBR IEC 60079-0:2020 Atmosferas explosivas - Parte 0: Equipamentos – Requisitos gerais

ABNT NBR IEC 60079-1:2016 Atmosferas explosivas - Parte 1: Proteção de equipamento por invólucro à prova de explosão "d"

ABNT NBR IEC 60079-11:2013 Atmosferas explosivas - Parte 11: Proteção de equipamento por segurança intrínseca "i"

ABNT NBR IEC 60079-26:2022 Atmosferas explosivas - Parte 26: Equipamentos com elementos de separação ou níveis de proteção combinados

ABNT NBR IEC 60079-31:2022 Atmosferas explosivas - Parte 31: Proteção de equipamentos contra ignição de poeira por invólucros "t"

ABNT NBR IEC 60529:2017 Graus de proteção providos por invólucros (Código IP)

Desenhos 102A1359, 102A1226, 102A1995, 102A1996, 102A2078

## Identification Plate

### ATEX / IECEx



**smar DT302 Density Transmitter**  
BR - 14160  
Sertãozinho  
Brazil

Ex II 1/2G Ex ia IIC T4/T5/T6 Ga/Gb BVS 03 ATEX E 359 ( )  
-40°C ≤ Ta ≤ +60°C  
Pi = 5,32 W Ui = 24 VDC li = 380 mA Li = neg Ci ≤ 5 nF

Ex II 2G Ex d IIC T6 Gb Nemko 03 ATEX 1375X ( )  
Tamb = -20°C to 60°C U = 28 VDC

IP66  
IP68 10m/24h

0000000 - 0000

  0470 **138703**



**smar DT302 Density Transmitter**  
BR - 14160  
Sertãozinho  
Brazil

Ex II 1/2G Ex ia IIC T4/T5/T6 Ga/Gb BVS 03 ATEX E 359 ( )  
-40°C ≤ Ta ≤ +60°C  
Pi = 5,32 W Ui = 24 VDC li = 380 mA Li = neg Ci ≤ 5 nF

Ex II 2G Ex d IIC T6 Gb Nemko 03 ATEX 1375X ( )  
Tamb = -20°C to 60°C U = 28 VDC

IP66W  
IP68W 10m/24h

0000000 - 0000



  0470 **148203**

**smar DT302 Density Transmitter**  
BR - 14160  
Sertãozinho  
Brazil

Ex I M1 Ex ia I Ma BVS 03 ATEX E 359  
-40°C ≤ Ta ≤ +60°C  
Pi = 5,32 W  
Ui = 24 VDC li = 380 mA Li = neg Ci ≤ 5 nF

IP 66 68

0000000 - 0000



  0470 **126801**

**smar DT302 Density Transmitter**  
BR - 14160  
Sertãozinho  
Brazil

Ex I M1 Ex ia I Ma BVS 03 ATEX E 359  
-40°C ≤ Ta ≤ +60°C  
Pi = 5,32 W  
Ui = 24 VDC li = 380 mA Li = neg Ci ≤ 5 nF

IP 66W 68W

0000000 - 0000

  0470 **148301**

### INMETRO NCC



**smar DT302 Transmissor de Densidade**  
Nova Smar SA Av. Dr. Antônio Furlan Jr, 1028 | Sertãozinho - SP - Brasil | 14170-480

Segurança

Ex db IIC T6 Ga/Gb NCC 24.0151 ( )  
Ex ia IIC T4/T5 Ga NCC 24.0150 X ( )  
Tamb= -20° a 65°C (T4) -20° a 50°C (T5)  
Ui= 30V li= 380mA Pi= 5,32W Ci= 5nF Li= desp  
FISCO Field Device

IP66 ou IP68 10m/24h

0000000 - 0000

  **135905**



**smar DT302 Transmissor de Densidade**  
Nova Smar SA Av. Dr. Antônio Furlan Jr, 1028 | Sertãozinho - SP - Brasil | 14170-480

Segurança

Ex db IIC T6 Ga/Gb NCC 24.0151 ( )  
Ex ia IIC T4/T5 Ga NCC 24.0150 X ( )  
Tamb= -20° a 65°C (T4) -20° a 50°C (T5)  
Ui= 30V li= 380mA Pi= 5,32W Ci= 5nF Li= desp  
FISCO Field Device

IP66W ou IP68W 10m/24h

0000000 - 0000

  **122605**



**smar DT302 Transmissor de Densidade**  
Nova Smar SA Av. Dr. Antônio Furlan Jr, 1028 | Sertãozinho - SP - Brasil | 14170-480

Segurança

Ex db IIB T6 Ga/Gb NCC 24.0151 ( )  
Ex ia IIB T4/T5 Ga NCC 24.0150 X ( )  
Tamb= -20° a 65°C (T4) -20° a 50°C (T5)  
Ui= 30V li= 380mA Pi= 5,32W Ci= 5nF Li= desp  
FISCO Field Device

P1/P2 Pintura IP66W ou IP68W 10m/24h

0000000 - 0000

  **199503**



**smar DT302 Transmissor de Densidade**  
Nova Smar SA Av. Dr. Antônio Furlan Jr, 1028 | Sertãozinho - SP - Brasil | 14170-480

Segurança

Ex db IIB T6 Ga/Gb NCC 24.0151 ( )  
Ex ia IIB T4/T5 Ga NCC 24.0150 X ( )  
Tamb= -20° a 65°C (T4) -20° a 50°C (T5)  
Ui= 30V li= 380mA Pi= 5,32W Ci= 5nF Li= desp  
FISCO Field Device

P1/P2 Pintura IP66 ou IP68 10m/24h

0000000 - 0000

  **199603**



**smar DT302 Transmissor de Densidade**  
Nova Smar SA Av. Dr. Antônio Furlan Jr, 1028 | Sertãozinho - SP - Brasil | 14170-480

Segurança

Ex tb IIIC T85°C Db NCC 24.0151 ( )  
Ex ia IIIC T<sub>200</sub>135°C/T<sub>200</sub>100°C Da NCC 24.0150 X ( )  
Tamb= -20° a 65°C (T<sub>200</sub>135°C) -20° a 50°C (T<sub>200</sub>100°C)  
Ui= 30V li= 380mA Pi= 5,32W Ci= 5nF Li= desp  
FISCO Field Device

IP66 ou IP68 10m/24h


0000000 - 0000

  **207804**





# Appendix B

		<b>SRF – Service Request Form Density Transmitters</b>				<b>Proposal No.:</b>	
<b>Company:</b>				<b>Unit:</b>		<b>Invoice:</b>	
<b>COMMERCIAL CONTACT</b>				<b>TECHNICAL CONTACT</b>			
<b>Full Name:</b>				<b>Full Name:</b>			
<b>Function:</b>				<b>Function:</b>			
<b>Phone:</b>		<b>Extension:</b>		<b>Phone:</b>		<b>Extension:</b>	
<b>Fax:</b>				<b>Fax:</b>			
<b>Email:</b>				<b>Email:</b>			
<b>EQUIPMENT DATA</b>							
<b>Model:</b>				<b>Serial Number:</b>		<b>Sensor Number:</b>	
Technology: ( ) HART® ( ) FOUNDATION fieldbus ( ) PROFIBUS PA				<b>Firmware Version:</b>			
<b>PROCESS DATA</b>							
<b>Process Fluid:</b>							
<b>Calibration Range</b>		<b>Ambient Temperature ( °F )</b>		<b>Process Temperature ( °F )</b>		<b>Process Pressure</b>	
<b>Min.:</b>	<b>Max.:</b>	<b>Min.:</b>	<b>Max.:</b>	<b>Min.:</b>	<b>Max.:</b>	<b>Min.:</b>	<b>Max.:</b>
<b>Static Pressure</b>		<b>Vacuum</b>		<b>Density</b>		<b>Concentration</b>	
<b>Min.:</b>	<b>Max.:</b>	<b>Min.:</b>	<b>Max.:</b>	<b>Min.:</b>	<b>Max.:</b>	<b>Min.:</b>	<b>Max.:</b>
<b>Normal Operation Time:</b>				<b>Failure Date:</b>			
<b>FAILURE DESCRIPTION</b> (Please, describe the failure. Can the error be reproduced? Is it repetitive?)							
<b>OBSERVATIONS</b>							
<b>USER INFORMATION</b>							
<b>Company:</b> <b>Contact:</b> <b>Title:</b> <b>Section:</b> <b>Phone:</b> <b>Extension:</b> <b>E-mail:</b> <b>Date:</b> <b>Signature:</b>							
For warranty or non-warranty repair, please contact your representative. Further information about address and contacts can be found on <a href="http://www.smar.com.br/en/contact-us">www.smar.com.br/en/contact-us</a> .							

